

Servo Gear Units

Geared to a higher standard [™]





Servo Gear Units





STOBER Drives Inc. was founded in 1991. Our Maysville, Kentucky

Welcome to STOBER!

Thank you for your interest in the servo gear reducers offered by STOBER Drives, Inc.!

In 1934, the Stöber brothers founded a small shop in Pforzheim, Germany that made machines and repaired engines. Today, STOBER is an international organization with offices in ten countries.

This 80 year heritage has given us expertise in servo gearing for which STOBER is recognized worldwide as the "gold standard." STOBER products are of the highest quality and use only the best components.

This catalog covers our comprehensive servo gearbox products — Servo Precision Planetary and Modular Gearheads. STOBER is recognized across the United States for its solution design, product durability, and service support. We look forward to the opportunity to work with you, and to help with your servo gearing needs.

Peter Feil, General Manager, STOBER Drives, Inc.



Geared to a higher standard ™

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All manufactured components are inspected before being released to assembly. Our quality inspection team ensures every part meets tolerances and is in spec.

Unsurpassed:

STOBER products are designed and built to perform for the toughest applications. Reliability, adaptability and maintainability are our focus, and durability is truly our trademark.

Solution Designs that build quality around every requirement.

Product Durability that enhances the reliability and life of every application.

Service Support that is empowered to meet and exceed client expectations.













STOBER Serviced Industries:

Beverage
Food Processing
Packaging
Machine Tool
Robotics
Material Handling
Semiconductor
Printing
Converting and many others...

Servo Gear Units

The Best you Can Buy...

At STOBER, offering the best is not a buzz word — it is our passion and way of life. We offer the best product, provided by the best people and processes, and backed by the best service.

Why is STOBER considered the industry Gold Standard? Our products are backed with superior service, outstanding quality, and the STOBER guarantee.

- STOBER gearheads survive in the toughest environments, providing long life under extreme conditions.
 Their high reliability and durability saves non-productive downtime and cost
- Our product reliability is backed by one of the best warranties in the industry
- We build and ship in 1 day saving you inventory hassle and cost
- Adapts to <u>any</u> servo motor

The Servo Gear Difference

A STOBER Servo Gearhead helps optimize your total operational performance with:

- High torsional stiffness, superior accuracy
- Smoother running, better efficiency
- · Leakage free, maintenance free
- Runs cool a difference you can feel
- Runs measurably quieter 16 times more quiet*
- Lower backlash
- The versatility and interchangeability of our components allow most products to be assembled and shipped in 1 day

* Noise Level

If a planetary is loud — something is WRONG!

STOBER Servo planetary = 60 dB(A)

Convention spur gear planetary = 70-72 dB(A)

Bottom line: 1 conventional gearhead produces the same noise level as 16 STOBER planetary gearheads with HeliCamber™ gearing

Striving Harder to Deliver the Best Gear Solutions

STOBER Drives has been assembling products at our Maysville, Kentucky facility for over twenty years. Our expertise in the production and assembly of low-backlash gear units produces products that comply with the highest quality standards.

But, we don't remain satisfied with the status quo. We are continuously improving our modern machining production center including numerous recent acquisitions to improve our manufacture time and to ensure maximum quality levels.

All reducer components (gears, covers, material, etc.) are backed by a five year warranty. Normal wear items (oil seals, bearings, etc.) are covered for two years.

Vision: To be recognized as the gold standard

Mission: To provide the most reliable drive solutions for demanding applications in the shortest lead-time

Values: Seeking the best; operating with integrity; serving others, growth through learning

Servo Gear Units V.28



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Assembly stages of "F" Series gearheads: Paint curing oven allows for one day assembly and higher paint durability (left); units awaiting final inspection prior to shipment (right).





Key STOBER Numbers

- 1 day shipping
- 1 hour quoting
- 3 rings or less when you call in - we answer the phone, not an automated switchboard!

100% inspected and tested during assembly for seal pressure test and ratio verification, STOBER also observes the reducer for any abnormal noise or vibrations during testing

5 year warranty

24/7 customer service





Service Support for a Lifetime

We stand behind every drive we sell, which is why our service support is also the gold standard in the industry:

STOBER takes pride in offering knowledgeable, factory-trained USA-based service support for our customers. When you call, you won't get a call center on the other side of the globe. Your call is answered in 3 rings or less, letting you know you've found a support system that values your time.

Our easy order method insures you maintain a single contact throughout the process. And, your service representatives are directly responsible for your account. After the sale, our products are easy to install, but if you do have a question or a problem, we provide application and installation support anywhere in the US. With over 80 years gearing & 30 years motor and electronics experience, we have the expertise to solve your most difficult problems.

Application Support Programs

- For support during normal business hours: call 800-711-3588 or email sales@stober.com
- 24/7 emergency customer service hotline: 606.563.6035
- Consultative product support team available via phone or live chat on our website
- **Application Sizing Software**
- Online web tools: CAD and configurator
- On-site training available
- Emergency shipments available 24/7

STOBER Staff Team Members

Facing page: Earl Bennington, Warehouse Team Leader, 1992, and Anita Truesdell, Picker, 2007; From top, left to right: Stephanie Berry, LMS Administrator, 2006; Brian Sharp, Product Management Team Leader, 2003; Rick McCall, Machinist, 2007; Lee Thomas, Industrial Engineer, 2003



The Servo Gear Unit Difference

The following outlines some of our quality standards and unique STOBER features that set Servo gearheads apart from all others...

Food and Corrosion Resistant Duty

P PKX PK C F K/KL KSS

Lifetime lubrication; double output seals (where possible); maintenance free design; stainless output bushing, shaft, or bore — finish is USDA approved for food processing and handling; heat cured.

KSS for extreme high pressure food washdown!

- IP69K certified for extreme high pressure food washdown (sprayed at close distance at 100 bars or 1,450 PSI)
- Certified against dust and water ingress
- 304 stainless steel cast housing

Explosion Proof

P PA PH PHA PHQ PHQA PKX PHKX C F K

ATEX is often used in process control and converting where unstable gases and dust can be found

ATEX is a directive consisting of two European directives describing equipment or work environment allowed in an environment with an explosive atmosphere. ATEX derives its name from the ATmospheres EXplosible.

Please consult our product support team for assistance selecting an ATEX gearbox.

Large Input Planetary

P PA PE PH PHA PHQ PHQA KS

Equipping a Servo gearhead with the large input option allows a larger shaft diameter motor to be used, keeping gearhead size and cost down! This input is ideal for inertia matching.

ServoCool®

P PA PH PHA



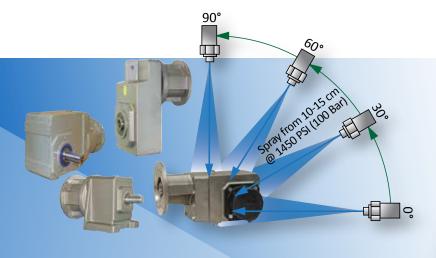
Servo gearheads with the air cooled ServoCool® option reduces the operating temperature 22°C (increases the ambient temperature limit 22°C), increases the output speed 54% and improves the servo motor rating 25%.

Servo motors are connected to Servo gearheads by using a motor adapter.

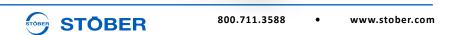
Spiral Groove Hollow Bore

F K KL KS KSS

The inside diameter on our hollow bore units feature a spiral (rifle) bore design providing an anti-seize lubricating groove. This enables the Servo gearhead to slide off freely when servicing without damage to the output shaft. With conventional smooth-surface hollow bore designs, any anti-seize lubricant applied during installation of the output shaft has no where to go except out the other end. Invariably, these designs will seize, making it necessary to cut off the output shaft when servicing.



Above: KSS Servo Gearheads are IP69K certified to withstand frequent pressure cleaning operations typical in the food industry and elsewhere. Other STOBER products, including C, F and K Series, are optionally available with IP69K compliant protection.



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Wobble Free Bushing

F K KL KSS

The STOBER "Wobble Free" bushing is a unique (U.S. Patent Number 5,496,127), bushing system which can be supplied on a single side or double sides. Each case size can be provided with a variety of bushing bores. The unit is selected based on torque rating, output speed or ratio, and the shaft size of the driven equipment.

- A distinct support side and a clamp side, the dual tapered cones will overcome a wide range of tolerances normally found with standard shaft materials. No shaft key necessary.
- Many unit sizes can be supplied with output covers on one or both sides which protect the seals and also cover the rotating bushing
- The reducer output bore can be changed any time by changing the bushing kit
- The quill, all bushing parts, and hardware can be supplied stainless steel to provide corrosion resistance for washdown applications



Double Sided Bushing:

This unique design allows the unit to be mounted on the shaft from either side of the reducer by reversing the clamp side and support side bushings. The clamp side is determined by the customer but is usually the easily accessible outside bushing.

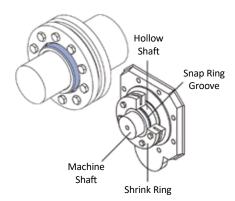
The double sided bushing is not installed into the unit at assembly, but with easy-to-follow installation instructions, the unit and bushing can be mounted on the machinery quickly without any special tools.

Single Sided Bushing:

The single sided bushing is assembled at the time of the order. The bushing side extension must be specified by the customer before assembly. The bushing is installed into the unit for shipping and is not interchangeable once the unit is assembled.

Shrink Ring Connection

F K KL KS



F, K, KL and KS Series gearheads with a hollow bore can be connected to a finished machine drive shaft by frictional engagement through compression of a shrink ring on the hollow shaft.

This shaft-hub connection is totally free of backlash. Because of its selfcentering property, it can transmit high torques and axial thrusts with great accuracy.

Gear units supplied with a shrink ring, are shipped with the ring installed on the hollow shaft end, ready for assembly.

See page 331 for More Servo Gearhead Compatible Products...

EZ Series Servo Motors available to fit all Servo gearheads

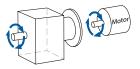
Rack and Pinion Servo gearhead systems are a ready to install engineered solution for precision automation applications requiring forces up to 122 kN (27,400 lbs.) with linear backlash as low as 7 μ m

ServoStop automatic, electrically-actuated integrated holding brake used in place of a servo motor brake for dynamic safety braking, or in conjunction with the servo motor brake for redundancy in safety applications



Servo Gear Units

Inline & Offset Inline Gearheads







P/PA — Shaft Output *

STOBER P Series is the cornerstone of most of our inline family of precision planetary gearheads. They are the most accurate and efficient planetary gearheads available. HeliCamber® gear technology provides minimum wear, low backlash and low noise. The PA Advanced Series takes backlash to the absolute minimum, and performance to the max.

- 3:1 to 100:1
- Up to 2,000 Nm torque (nom)
- Up to 8,000 RPM input speed
- Backlash: P: <3 arc min; PA: <1 arc min



PH/PHA/PHQ/PHQA — Flange Output*

STOBER PH family geaheads offer a rotating flange output version of the P Series. The PHA Advanced Series takes backlash to the absolute minimum, and the PHQ and PHQA feature "Quattro" power planetary gearing for extreme torque and ratio capabilities.

- 4:1 to 600:1
- Up to 13,000 Nm torque (nom)
- Up to 8,000 RPM input speed
 Backlash: PH/PHQ: <3 arc min; PHA/PHQA: <1 arc min





PE — Shaft Output*

STOBER PE Series Servo Precision Planetary Gearheads are available for applications where very low backlash is not a criteria. They are an economical helical tooth planetary, comparable in quality to other STOBER units.

- 3:1 to 100:1
- Up to 160 Nm torque (nom)
- Up to 8,000 RPM input speed
- Backlash: < 8 arc min



C — Shaft Output*

STOBER C Series gear drives offer performance, durability, and economy for a wide range of applications. High efficiency helical gearing keeps motor size to a minimum while running almost silently.

- 2:1 to 276:1
- Up to 7,000 Nm torque (nom)
- Up to 6,500 RPM input speed
- Backlash: < 14 arc min

F — Versatile Outputs*

STOBER F Series gear drives are a popular choice for applications that require high performance, efficiency, durability, and flexibility. F Series are available with a wide selection of configurations to match almost any mounting requirement.

- 4:1 to 551:1
- Up to 1,100 Nm torque (nom)
- Up to 7,000 RPM input speed
- Backlash: < 10 arc min

* See page 326 for comparison of all output options and sizes available



Right Angle Gearheads



K — Versatile Outputs*

STOBER K Series helical/bevel gear drives are the most popular and versatile Servo right angle gearheads. They are the optimal drive for truly demanding continuous-duty applications, offering higher efficiencies than conventional worm gear drives or planetary gearheads.

- 4:1 to 381:1
- Up to 12,000 Nm torque (nom)
- Up to 7,000 RPM input speed
- Backlash <10 arc min





Many right angle gearheads offer output on either or both sides



PKX/PK — Shaft Output*

STOBER PKX and PK Series precision planetary gearheads combine the P Series gearhead with the low ratio "KX" right angle platform or the reduced backlash K Series platform.

- Ratios: 3:1 to 300:1;
- Up to 2,000 Nm torque (nom)
- Up to 6,000 RPM input speed
- Backlash: PKX: ≤4 arc min;
 PK: ≤3.5 arc min



PHKX/PHK/PHQK — Flange Output*

STOBER PH right angle geahead configurations offer a rotating flange output combining the P Series gearhead with the low ratio "KX" or reduced backlash K Series. The PHQK features the "Quattro" power planetary gearing for extreme torque and ratio capabilities.

- 4:1 to 591:1
- Torque: 13,000 Nm (nom)
- Up to 7,000 RPM input speed
- Backlash <3.5 arc min



KL — Verstile Outputs*

The STOBER KL Series offers the same output and housing versatility as the K series, but is much more compact and ideal for smaller gearhead size applications.

- 4:1 to 32:1
- Up to 50 Nm torque (nom)
- Up to 6,000 RPM input speed
- Backlash: <20 arc min



KS — Verstile Outputs*

STOBER KS Series precision planetary gearheads use time-tested helical gearing and finish ground spiral bevel gears to provide a low backlash unit, that is smooth running, with high efficiency, high power density, and high input speed capacity..

- 6:1 to 200:1
- Up to 250 Nm torque (nom)
- Up to 6,000 RPM input speed
- Backlash: < 4 arc min



KSS — Versatile Outputs*

STOBER is proud to offer our qualityproven, high-efficiency KSS Series Helical/Bevel speed reducer in a stainless steel housing necessary for the toughest washdown applications.

- 4:1 to 70:1
- Up to 346 Nm torque (nom)
- Up to 6,000 RPM input speed
- Backlash: < 10 arc min



Servo Gear Units

Versatility

STOBER Drives offers the world's largest variety of gearheads to fit virtually all servo needs.

INLINE & OFFSET INLINE GEARHEADS











Performance, Configurations and Options P PA PH PHA PHQ PHQA PE C page 14 page 46 page 92 page 102 page 92 page 102 ServoCool Solid Shaft P PA PH PHA PHQ PHQA PE C page 46 page 92 page 102	page 140
Options page 14 page 46 page 92 page 102 Input Large Input • • • • •	•
Options page 14 page 46 page 92 page 102 Input Large Input • • • • • ServoCool • • • • • •	•
ServoCool • • • •	
ServoCool • • • •	
Solid Shaft • • •	
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Output Patrice Flores	
Rotating Flange	•
(see page 326 Shrink Ring for details)	•
Single Bushing	•
Double Bushing	•
Flange •	•
Housing Foot Mount •	•
Tapped Holes •	•
	•
Protection	
ATEX Certified Opt Opt Opt Opt Opt Opt	Opt
304SS Housing	
Paint/ Food Duty • • • • • • • • • • • • • • • • • • •	•
Resistant Duty	•
Added ServoStop* • • • •	•
Functionality Rack and Pinion* • • •	
Performance Continuous RPM +++ +++ ++ ++ ++ +++ +++	++
+ Good +++ Better Stiffness +++ +++ +++ +++++ + +++++ + ++++++ ++++	++++
+++++ Best Torque Density +++ +++ ++ ++++ +++++ + +++++ + ++++++	++++
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1-3	
Precision 3-5	
ArcMin Backlash 5-10 Opt	Opt
10-15	
15-20	
Nominal 50-200 • • • • • • •	•
Torque 200-1,000 • • • • • • • • •	•
Ranges 1,000-5,000 • • • • • • • • • •	•
Nm 5,000-10,000 • • • •	•

^{*} See page 331 for more information

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RIGHT ANGLE GEARHEADS

















K	KL	PKX	PK	РНКХ	PHK	PHQK	KS	KSS
page	e 162	page	214		page 248		page 298	page 312
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Servo Gear Units Application-Tailored Solutions

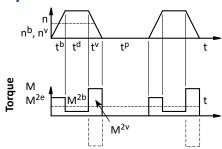
Industry	Ideal Gearhead Applications		Recommended STOBER Gearhead
Aerospace	 Automated Guided Vehicles (AGV) Drilling and Riveting Machine Tool Testing and Inspection 	Carbon Fiber PlacementFuselageSpace Tracking SystemsWing assembly	Inline: P, PA, PH, PHA Right Angle: KS Also: STOBER rack and pinion systems and hollow bore servo motors
Automation	Assembly turn tablesLinear pressesRobotics auxiliary axisPalletizing	Custom assembly machinesRadarPipe and wire bending	Inline: P, PA, PE, PH, PHA Right Angle: K/KL, PKX, KS Also: STOBER rack and pinion systems, hollow bore servo motors, and servo brakes
Automotive Manufacturing	Transfer linesRobotic auxiliaryMachiningTire manufacturingCarbon fiber production	Metal cutting and bendingPick and placeIndex tablesElectronics assembly	Inline: P, PA, PE, PH, PHA Right Angle: K/KL, PKX, KS Also: STOBER rack and pinion systems, hollow bore servo motors, and servo brakes
Converting	Cutting Tension Control Web Lines	WindingPaper Converting	Inline: P, PA, C, PH, PHA Right Angle: K/KL Also: STOBER hollow bore servo motor, servo brakes and fans
Machine Tool	 Horizontal and vertical mills Large gantry cranes Carbon fiber placement Flame, laser, water jet, and plasma cutting Back gauging 	 Grinding X-Y tables Indexing tables Chip conveyors Bending and forming Tool changers 	Inline: P, PA, PH, PHA, PHQ, PHQA Right Angle: PKX, PHKX, PHK, PHQK, KS Also: STOBER rack and pinion systems, hollow bore servo motors, and servo brakes
Material Handling	Pick and placeLine diverterSorting/diverting	Linear transferPalletizing	Inline: PE, C Right Angle: K/KL, F Also: STOBER hollow bore servo motors
Medical	Imaging Radiation Centrifuge		Inline: P, PA, C, PH, PHA Right Angle: K/KL, F, KS Also: STOBER hollow bore servo motors
Packaging	Continuous or intermittent fil	ling applications	Inline: P, PA, PE, C, PH, PHA Right Angle: K/KL, F, PKX, KS Also: STOBER hollow bore servo motors
Plastics/ Composites	Often used to replace hydraulic actuators in injection molding Injection molding Carbon fiber placement	Extrusion linesBlow moldingThermoformingRubber molding	Inline: P, PA, PH, PHA, PHQ, PHQA Also: STOBER rack and pinion systems and hollow bore servo motors
Printing	Labels Flexographic printing	Circuit BoardsSheet	Inline: P, PA, PH, PHA Also: STOBER hollow bore servo motors and servo brakes
Robotics	Delta Pick and place Telescoping arms	Auxiliary axis to rotate and move robotPositioning axis	Inline: PH, PHA, PHQ, PHQA Also: STOBER rack and pinion systems and hollow bore servo motors
Semiconductor	Wafer polishing Wafer handling	Circuit web printing	Inline: P, PA, PH, PHA Also: STOBER hollow bore servo motors
Valve Control	Ideal for handling rapid dithering positioning Ball, gate, and globe valves	 Throttle/governor valves Chokes Process valves ATEX explosion proof available 	Inline: P, PA, PH, PHA Right Angle: K/KL, F, PKX, PHKX Also: STOBER hollow bore servo motors

Sizing/Selection

Use the chart on the facing page and below to determine the best series and the right size gearhead to meet your specific application requirements. In each product section of this catalog, the necessary data and a "Load/Life/Speed Calculation" section are provided to help you work through these equations..

By all means, please feel free to call or email (sales@stober.com), if you have any questions or need assistance determining the best solution for your application.

Cycle Run



$$M_{2e} = \sqrt[3]{\frac{n_{2b} \cdot t_b \cdot M_{2b}^3 + \ldots + n_{2n} \cdot t_n \cdot M_{2n}^3}{n_{2b} \cdot t_b + \ldots + n_{2n} \cdot t_n}}$$

Service Factor

Apply to Nominal Rating ONLY

P, PA, PE PH, PHA PHV, PHVA, PHQ, PHQA,	PKX, PK, PHKX, PHK, PHQK,
KS	C, F, K, KSS
1.0	1.0
1.0	1.25
1.0	1.4
	PH, PHA PHV, PHVA, PHQ, PHQA, KS

Running Time Factor f

≤8 hours	1.0
≤16 hours	1.15
≤24 hours	1.2

Apply to Input RPM

Temperature Factor f_T

	Without Ventilation	Fan Cooled
<20°C	1.00	0.90
<30°C	1.10	1.00
<40°C	1.25	1.15

Continuous Duty: Drive is considered continuous duty if the running time ($t^r = t^b + t^d + t^v$) is 60% of the complete cycle time ($t^b + t^d + t^v + t^p$) or longer than 20 minutes.

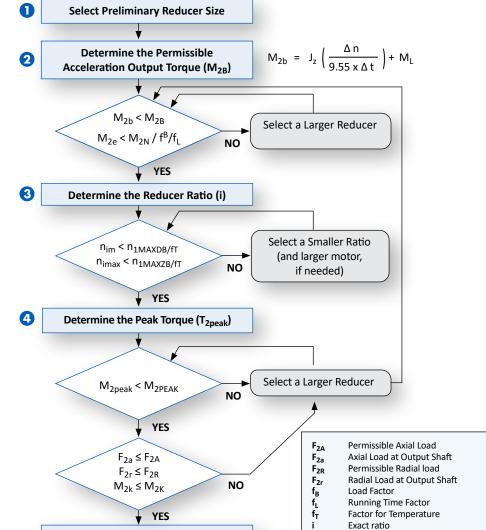
Cyclic Duty: Drive will cycle on and off.

For cyclic operation, the recommended ratio of external (application) inertia to gearhead inertia can be determined by the following equation:

$$\frac{J_z}{i^2} = 4 \cdot J_D$$

The gearhead selected, using the following equation for inertia ratio, will result in the lowest motor torque demand and the optimum drive selection:

$$\frac{J_{Z}}{i^{2}} = J_{D}$$



Rated Tilting Torque M_{2K} M_{2k} **Equivalent Tilting Load** M_{2N} Nominal Output Torque M_{2peak} Peak Output Torque Maximum Continuous Input n_{1db} Maximum Cyclic Input n_{1zb} Maximum Continuous Speed n_{im} Maximum Cyclic Speed n_{imax} T_{2PEAK} Peak Torque **Running Time** Acceleration Time t_b **Duration Time** Deceleration Time

 \mathbf{J}^{D}

J_z M_L

 M_{2B}

 M_{2b}

Motor + Reducer Inertia @ Motor RPM

Total Inertia @ Reducer RPM

Acceleration Output Torque

Application Acceleration Torque

Equivalent Torque (Avg RMS Torque)

Friction Torque (Losses)

Reducer Selection Complete

(See Load Calculations

for each Gearhead Series)

KS Series: RIGHT ANGLE - Versatile Outputs

Features

- 6:1 to 200:1 ratios (higher ratios available. Contact STOBER.)
- Quiet running (<62dB(A))
- · Flexilibity for mounting
- Adaptability: shafts available in metric and imperial to meet your requirements
- Large motor input option to accept bigger diameter motor shafts so you don't use an oversized gearbox
- Error free motor mounting and quick changeover with toleranced pilot on motor plate
- Low no load running torque, giving you more torque for your application
- Magnetic oil filtration to remove contaminants to prevent breakdowns
- Build and ship in one day
- Assembled in the USA

STOBER KS Series uses helical and bevel gearing to provide a low backlash unit, that is smooth running, with high efficiency, high power density, and high input speed capacity. The KS also offers flexibly with three output options: shaft, flange, and hollow. Every gearbox is made to order. STOBER will custom whatever you need to fit your application. Contact us today to learn more.



General Specifications

delier at Spec	IIICations				
Ambient Temperature	0°C to +40°C (104°F) [Unit temperature <80°C Max]				
Backlash	≤4 standard arcmins (see performance overview chart, see page 300)				
Coating	Standard Black (RAL 790-4)				
Degree of Protection	IP65				
Direction of Rotation	Input and output rotate the SAME direction (see page 300)				
Efficiency	2 stage 95%; 3 stage 93%;				
Input RPM	Up to 6,000 RPM				
Installation	Requires 10.9 fasteners for tapped holes housing. See page 328, for more information				
Lubrication	Lubricated for life – standard Mobil SHC629; option food grade Mobil SHC CIBUS 150				
Mounting Position	Must be specified, see page 301				
Warranty	5 Year Limited (2 Years on normal wear items: bearings, seals, etc.)				
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Overview



Selection Options At-a-Glancee

Using the **Selection Data** table later in this section, select the KS Series Gearhead with the appropriate performance and design options tailored to your motor choice and exact application requirements. Use the part number guide below as a reference to build a part number for the complete gearhead assembly.

1 2 3 4 5 6 7 8 9 Part Number Examples: KS 4 0 2 P F 0060 MT L EL1

		Part Number	
	Design Option	Code	Description
1	Series	KS	Concentric helical
2	Size	4 5 7	3 sizes of gearhead
3	Generation	0	Version of gearhead
	# of Stages	2	Two stage for ratios ≤20:1
4	# of Stages	3	Three stage for ratios >20:1
		Р	Shaft with key
(E)	Outout	G	Plain shaft (no key)
(5)	Output	F	Flanged hollow
		S	Shrink ring
6	Housing	F	Standard
	Dati-	2252	Ratios range from 6:1 to 200:1
7	Ratio	0060	(0060=6:1; 0200=20:1; 2000=200:1)
	Nata Adamta		MT Motor adapter
8	Motor Adapter	MT	(See also motor mounting plate option, page 301)
10	Options	L	Large Input
*	Mounting Position	EL1 EL2 EL3 EL4 EL5 EL6	Required special instruction for all units, see page 301

Options

Coating Options

 KS Series are also available with a multi-layer, industrial 316 stainless steel epoxy coating (contact factory)

Large Input

 Accommodates a larger diameter motor shaft without going to a larger size gearbox

ATEX

 ATmosphere EXplosible — Please contact factory for this option and allow additional time for delivery

Oil Reservoir

 Use with 3 stage units (for vertical EL5 orientation, see page 300)



KS Series: RIGHT ANGLE - Versatile Outputs

KS Performance Overview

KS Series performance is dependent on several factors including duty cycle, bearing design, gearhead size and stage configuration, among others. Use the chart below for preliminary evaluation, then use the following performance chart and selection information on the following pages for specific performance sizing and selection.

Size/Generation # of Stages		KS40		KS50		KS70	
		2	3	2	3	2	3
cceleration Nm 90 orque M _{2BMAX}		200		400			
Output Torque Nom. ¹⁾ M _{2N}	Nm	65		125		250	
Torsional Stiffness C ₂	Nm/arcmin	≤8.5		≤17		≤42	
Torsional Backlash ²⁾ Δφ	arcmin	≤6		≤5		≤4	
Input Speed Max. n1MAX	Continuous Cyclic	4000 6000	4500 6000	3500 6000	4200 6000	3200 6000	4000 6000
Efficiency (@nom torque)	%	95	93	95	93	95	93
Weight	kg Ibs	8.4 18.5	8.2 18.1	13.6 30	14.4 31.8	26.8 59.1	28.1 62
Noise 3) dB(A)		≤65		≤62		≤63	
Performance by Output Option (P:	= Shaft with Key; G	= Shaft witho	ut Key; F = Fla	nged Hollow O	utput; S = Shri	nk Ring) 4)	
Size/Generation		KS40		KS	50	KS70	

P/G Ν 3400 6000 10,000 Axial Load Max. 4000 Ν 6000 10,000 F₂AMAX N 4000 6000 10,000 Radial Load Max. P/G Ν 5000 8000 10,000 F_{2RMAX} Tilting Moment Max.

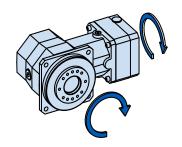
M2KMAX

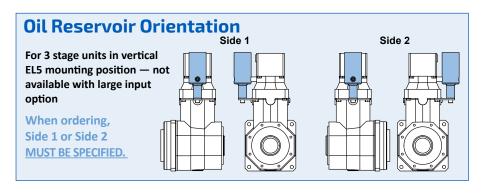
F/S Nm 210

Ratings based on input speed (n,) of 2000 RPM. $M_{\text{Nm}} = \frac{M_{\text{2N}}}{M_{\text{2N}}}$

For torque at higher input speeds (M_{2nx}) solve the formula: where $n_* = \text{Actual Input Speed}$.

KS Direction of Rotation





460

780

²⁾ Tested at 1.5% of nominal torque and recorded on the output side of the gearhead. For lower backlash, contact STOBER technical support.

³⁾ Measurement at one (1) meter distance with input speed (n_1) of 2000 RPM.

⁴⁾ Rating based on output speed (n.) of 100 RPM. For values at other speeds see page 302.

Overview



KS Series Motor Mounting Plate Option (Motor information required with Motor Adapter ME option)

STOBER Servo Gearheads fit the motor of your choice with the appropriate motor mounting plate assembled between the motor and the gearhead.

NOTE: When ordering a gearhead:

- Specify the motor manufacturer and part number
- Provide the motor drawing with dimensions, or specify the motor mounting dimensions (per the list shown at right)

For a precise dimension on a specific motor, or for general assistance, we recommend you contact STOBER Technical Support.

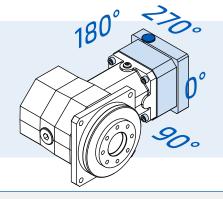
Customer Required Dimensions for Properly Sized Motor Mounting Plate Motor Shaft Diameter (If an adapter bushing is required it will be supplied with the motor plate.) b6 Pilot Diameter e6 **Bolt Circle Diameter** s6 **Bolt Diameter** 15 **Motor Shaft** Length f6 Pilot Length d2 a6 Square Flange (Optional – motor plate will typically be made to match this dimension.)

Motor Mounting Plate Dimensions — mm (Gearhead Part Number Specific)	KS403	KS402 KS403L KS503	KS402L KS502 KS503L KS703	KS502L KS702 KS703L	KS702L
Maximum Allowed Motor Shaft Dia. d2	14	19	24	32	38
Minimum Allowed Motor Plate Thickness c	15	18	21	24	25

^{*} Note that the c motor plate thickness is determined by the motor shaft length. The minimum motor plate thickness is the value listed.

KS Series Motor Mounting Plate Access Hole

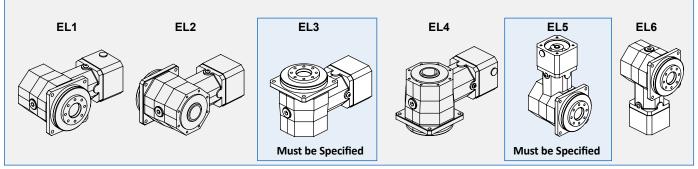
Access to the clamping screw for the motor coupling is located on the 270° side of the motor mounting plate at the location shown. If necessary, the motor mounting plate can be rotated in the field, if a 0°, 90° or 180° orientation for the access hole is desirable.



KS Mounting Position Options

KS Units can be mounted in any of the positions illustrated below.

When ordering KS units mounted in a vertical position (EL3) or in a horizontal position (EL5), the mounting position <u>MUST BE SPECIFIED.</u> <u>NOTE: EL5 3 stage units are only available with the oil reservoir option.</u>



KS Series: RIGHT ANGLE – Versatile Outputs

Permissible Motor Tilting Torque

The permissible tilting torque of the motor attached to the gear unit is a result of the static and dynamic load "F" from the motor weight, mass acceleration, and vibration multiplied by the distance from the center of gravity "Is" of the motor.



M _{1K}	KS403	KS402 KS503	KS502 KS703	KS702
Nm	10	20	40	80

 $M_{1k} = F \times I_S \leq M_{1K}$

Permissible Output Shaft Load and Tilting Moments*

	• • • • • • • • • • • • • • • • • • •					
	z ₂	F _{2A}	F _{2R}	F _{2RB}	M _{2K}	M _{2KB}
Unit	mm	N	N	N	Nm	Nm
/G Solid Shaft	(with/without key					
KS4	34	3400	5000	5000	260	260
KS5	40	6000	8000	8000	550	550
KS7	51	10,000	10,000	10,000	920	920
Flange Hollov	v Output					
KS4	38	4000	6842	10,263	260	390
KS5	45	6000	12,222	18,333	550	825
KS7	55	10,000	16,727	25,091	920	1380
Hollow Outpu	ıt with Shrink Ring					
KS4	36	4000	5000	5000	260	260
KS5	42	6000	8000	8000	550	550
KS7	52	10,000	10,000	10,000	920	920

^{*} Refer to illustration and definitions below.

During EMERGENCY OFF operation (maximum stops per gearhead = 1000) the permissible values in the table for F_{2N} , F_{2R} and M_{2k} can be multiplied by a factor of

KS Series Load/Life/Speed Calculations

The permissible load and tilting moment values are based on an output speed of 100 RPM. For higher speeds the following applies, where n₂ is the desired speed:

$$F_{2AX} = \frac{F_{2A}}{\sqrt[3]{\frac{n_2}{100}}} \qquad F_{2RX} = \frac{F_{2R}^{'}}{\sqrt[3]{\frac{n_2}{100}}} \qquad M_{2KX} = \frac{M_{2K}}{\sqrt[3]{\frac{n_2}{100}}}$$

The application output tilting moment should be determined by the following formula:

Output P & G
$$M_{2A} = \frac{2 \cdot F_{2a} \cdot y_2 + F_{2rb} \cdot (x_2 + z_2)}{1000} \le M_{2KB}$$

Output F & S
$$M_{2A} = \frac{F_{2a} \cdot y_2 + F_{2rb} \cdot (x_2 + z_2)}{1000} \le M_{2KB}$$

$$M_{2ka} = \sqrt[3]{\frac{n_{2b1} \cdot t_{b1} \cdot M_{2kb1}^3 + ... + n_{2bn} \cdot t_{bn} \cdot M_{2kbn}^3}{n_{2b1} \cdot t_{b1} + ... + n_{2bn} \cdot t_{bn}}} \le N$$

Where:

M_{2K} Rated Tilting Torque Axial Load at Output Shaft F_{2a} F_{2A} Permissible Axial Load M_{2k} **Equivalent Tilting Load** M_{2KB} Acceleration Tilting Torque Radial Load at Output Shaft F_{2r} **Distance Factor** Permissible Radial Load **z**2 F_{2R}

Acceleration Permissible Radial Load

The hours of life (L_b) of the unit can be determined by the following formula:

bearing life for duty cycle ≤ 40%

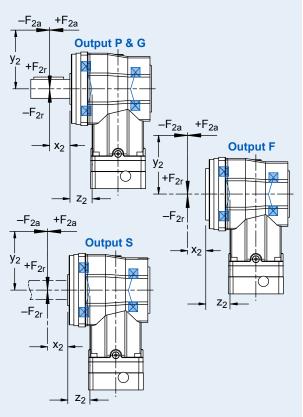
 $L_h > 10,000 \text{ hours if } M_{2k}/M_{2A} < 1.25 \text{ and } > 1$ $L_h^{"} > 20,000 \text{ hours if } M_{2K}/M_{2A} > 1.25 \text{ and } > 1.5$ $L_h > 30,000$ hours if $M_{2K}/M_{2A} < 1.5$

bearing life for duty cycle ≥ 40%

$$L_{hA} = L_{h} \left(\frac{40\%}{\text{Duty Cycle}} \right)$$

All formulas shown are based on METRIC values

Upper case letters are permissible values. Lower case letters are for existing values



Selection Data

Output Torque



Torsional

Exact	Nominal 1) M2N	Acceleration M2B	Peak ²⁾ M2PEAK	Down November *		Input Speed (n1)	Motor Shaft Max Ø D ⁶	Input Inertia ³⁾ j1	Torsional Stiffness C2 (per arcmin)
Ratio (i)	Nm	Nm	Nm	Part Number* (Gearhead + Input)	Cont.	Cyclic	mm	kgcm²	Nm
KS4									
6.000	60	00	140	KS402_0060MT	2000	6000	19	1.2	0.5
6.000	60	90	140	KS402_0060MTL	3000	6000	24	1.9	8.5
8 000	6F	00	140	KS402_0080MT	3500	6000	19	0.9	0.5
8.000	65	90	140	KS402_0080MTL	3500	6000	24	1.6	8.5
10.00	CE	00	1.40	KS402_0100MT	2000	C000	19	0.8	0.5
10.00	65	90	140	KS402_0100MTL	3800	6000	24	1.4	8.5
14.00	CE	00	1.40	KS402_0140MT	4000	C000	19	0.6	0.5
14.00	65	90	140	KS402_0140MTL	4000	6000	24	1.3	8.5
20.00	60	00	4.40	KS402_0200MT	4000	6000	19	0.6	0.5
20.00	60	90	140	KS402_0200MTL	4000	6000	24	1.3	8.5
24.00	60	00	4.40	KS403_0240MT	25.00	5000	14	0.2	0.5
24.00	60	90	140	KS403_0240MTL	3500	6000	19	0.7	8.5
22.00	C.F.	00	4.40	KS403_0320MT	25.00	5000	14	0.2	0.5
32.00	65	90	140	KS403_0320MTL	3500	6000	19	0.6	8.5
40.00	C.F.	00	4.40	KS403_0400MT	2500	6000	14	0.2	0.5
40.00	65	90	140	KS403_0400MTL	3500	6000	19	0.6	8.5
50.00	C.F.	00	4.40	KS403_0500MT	4000	5000	14	0.1	0.5
50.00	65	90	140	KS403_0500MTL	4000	6000	19	0.6	8.5
70.00	C.F.	00	4.40	KS403_0700MT	4500	5000	14	0.1	0.5
70.00	65	90	140	KS403_0700MTL	4500	6000	19	0.6	8.5
00.00	C.F.	00	4.40	KS403_0800MT	4500	5000	14	0.1	0.5
80.00	65	90	140	KS403_0800MTL	4500	6000	19	0.6	8.5
		0.0		KS403_1000MT		5000	14	0.1	0 =
100.0	65	90	140	KS403_1000MTL	4500	6000	19	0.6	8.5
446.0	6-	0.5	4.00	KS403_1400MT	4500	6600	14	0.1	c =
140.0	65	90	140	KS403_1400MTL	4500	6000	19	0.6	8.5
205 -		0.7		KS403_2000MT		00	14	0.1	
200.0	60	90	140	KS403_2000MT KS403_2000MTL	4500	6000	19	0.6	8.5

^{*} MT = Motor Adapter L = Large Input Option



 $^{^{1)}\,}$ Based on input speed of 2000 RPM. See page 300 for details on torque calculations.

²⁾ Maximum momentary torque for emergency stops or heavy shock load. (Admissible stops per life of gearhead = 1,000 stops maximum.)

³⁾ Inertia based on maximum input. For lower inertia, using smaller diameter input, contact STOBER.

KS Series: RIGHT ANGLE – Versatile Outputs

		Output Torque							Torsional
Exact	Nominal 1) M2N	Acceleration M2B	Peak ²⁾ M2PEAK	Doub November #		Input Speed (n1)	Motor Shaft Max Ø D ⁶	Input Inertia ³⁾	Stiffness C2 (per arcmin)
Ratio (i)	Nm	Nm	Nm	Part Number* (Gearhead + Input)	Cont.	Cyclic	mm	kgcm²	Nm
KS5		1			1	,	1		
6.000	100	200	300	KS502_0060MT	2500	5500	24	2.9	17.0
0.000	100	200		KS502_0060MTL	2300	3300	32	5.1	17.0
8.000	125	200	300	KS502_0080MT	2800	6000	24	2.3	17.0
8.000	123	200	300	KS502_0080MTL	2800	0000	32	4.5	17.0
10.00	125	200	200	KS502_0100MT	2000	6000	24	1.9	17.0
10.00	125	200	300	KS502_0100MTL	3000	6000	32	4.1	17.0
44.00	425	200	200	KS502_0140MT	2200	6000	24	1.5	47.0
14.00	125	200	300	KS502_0140MTL	3200	6000	32	3.8	17.0
				KS502_0200MT	3500	5000	24	1.3	
20.00	120	200	300	KS502_0200MTL	3500	6000	32	3.6	17.0
				KS503_0240MT			19	0.8	
24.00	100	200	300	KS503_0240MTL	3100	6000	24	1.5	17.0
	_			KS503_0320MT			19	0.8	
32.00	125	200	300	KS503_0320MTL	3100	6000	24	1.5	17.0
				KS503_0400MT			19	0.8	
40.00	125	200	300	KS503_0400MTL	3100	6000	24	1.4	17.0
				KS503_0500MT			19	0.7	
50.00	125	200	300	KS503_0500MTL	3500	6000	24	1.4	17.0
				KS503_0700MT			19	0.6	
70.00	125	200	300	KS503_0700MTL	4200	6000	24	1.3	17.0
				KS503_0800MT			19	0.6	
80.00	125	200	300	KS503_0800MTL	4200	6000	24	1.3	17.0
				KS503_1000MT			19	0.6	
100.0	125	200	300	KS503 1000MTL	4200	6000	24	1.3	17.0
				KS503_1400MT			19	0.6	
140.0	125	200	300	KS503_1400MTL	4200	6000	24	1.2	17.0
				KS503_2000MT			19	0.6	
200.0	120	200	300	KS503_2000MTL	4200	6000	24	1.2	17.0

MT = Motor Adapter L = Large Input Option



Based on input speed of 2000 RPM. See page 300 for details on torque calculations.
 Maximum momentary torque for emergency stops or heavy shock load. (Admissible stops per life of gearhead = 1,000 stops maximum.)
 Inertia based on maximum input. For lower inertia, using smaller diameter input, contact STOBER.

Selection Data

Output Torque



Torsional Stiffness

Exact Ratio	Nominal ¹⁾ M2N	Acceleration М2в	Peak ²⁾ M2PEAK	Part Number*		Input Speed (n1)	Motor Shaft Max Ø D ⁶	Input Inertia 3) j1	C2 (per arcmin)
(i)	Nm	Nm	Nm	(Gearhead + Input)	Cont.	Cyclic	mm	kgcm²	Nm
KS7									
6.000	240	400	500	KS702_0060MT	2400	4500	32	9.3	42.0
6.000	240	400	600	KS702_0060MTL	2100	4500	38	12.3	42.0
0.000	250	400	500	KS702_0080MT	2500	5000	32	6.4	42.0
8.000	250	400	600	KS702_0080MTL	2500	5000	38	9.4	42.0
10.00	250	400	500	KS702_0100MT	2000	5000	32	5.3	42.0
10.00	250	400	600	KS702_0100MTL	2800	6000	38	8.3	42.0
1100	250	400	500	KS702_0140MT	2000	5000	32	4.3	42.0
14.00	250	400	600	KS702_0140MTL	3000	6000	38	7.4	42.0
20.00	250	400	500	KS702_0200MT	2200	6000	32	3.9	42.0
20.00	250	400	600	KS702_0200MTL	3200	6000	38	6.9	42.0
24.00	240	400	500	KS703_0240MT	2000	6000	24	2.0	42.0
24.00	240	400	600	KS703_0240MTL	3000	6000	32	4.2	42.0
22.00	250	400	500	KS703_0320MT	2000	6000	24	1.8	42.0
32.00	250	400	600	KS703_0320MTL	3000	6000	32	4.0	42.0
40.00	250	400	500	KS703_0400MT	2000	6000	24	1.8	42.0
40.00	250	400	600	KS703_0400MTL	3000	6000	32	4.0	42.0
50.00	250	400	500	KS703_0500MT	2200	6000	24	1.6	42.0
50.00	250	400	600	KS703_0500MTL	3200	6000	32	3.8	42.0
70.00	250	400	500	KS703_0700MT	2500	6000	24	1.4	42.0
70.00	250	400	600	KS703_0700MTL	3500	6000	32	3.6	42.0
00.00	250	400	500	KS703_0800MT	4000	6000	24	1.3	42.0
80.00	250	400	600	KS703_0800MTL	4000	6000	32	3.6	42.0
400.0	250	400	500	KS703_1000MT	4000	5000	24	1.3	42.0
100.0	250	400	600	KS703_1000MTL	4000	6000	32	3.6	42.0
1.40.0	250	400	600	KS703_1400MT	4000	6000	24	1.3	42.0
140.0	250	400	600	KS703_1400MTL	4000	6000	32	3.5	42.0
200.0	250	400	600	KS703_2000MT	4000	6000	24	1.3	42.0
200.0	250	400	600	KS703_2000MTL	4000	6000	32	3.5	42.0

^{*} MT = Motor Adapter L = Large Input Option



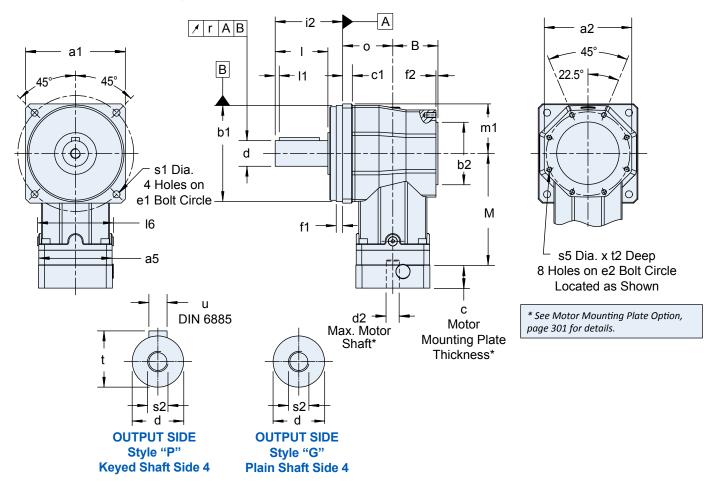
¹⁾ Based on input speed of 2000 RPM. See page 300 for details on torque calculations.

²⁾ Maximum momentary torque for emergency stops or heavy shock load. (Admissible stops per life of gearhead = 1,000 stops maximum.)

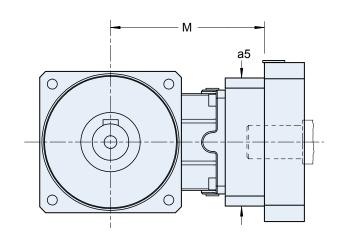
³⁾ Inertia based on maximum input. For lower inertia, using smaller diameter input, contact STOBER.

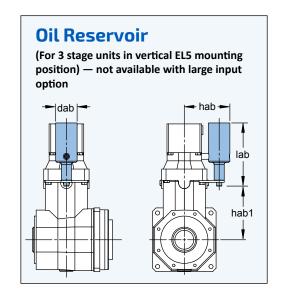
Shaft Output — "P" (with key) & "G" (without key)

With Standard Input



With Large Input Option





Dimensional Data



Table 1 Dimensions (mm)

Unit	a1	a2	В	b1	h6	b2	h6	c1	d	k6	e1	e2
KS4	101	93	51	95	+0.000/-0.022	75	+0.000/-0.019	10	22	+0.015/+0.002	120	88
KS5	125	109	58	120	+0.000/-0.022	90	+0.000/-0.022	10	32	+0.018/+0.002	145	105
KS7	155	135	70	150	+0.000/-0.025	110	+0.000/-0.022	15	40	+0.018/+0.002	180	130

Table 2 Dimensions (mm)

Unit	f1	f2	i2	I	l1	16	m1	0	r	s1	s2	s5	t	t2	u
KS4	8	3	52	36	3	77.5	50.5	53	0.020	6.6	M8	M5x0.80	24.5	9	A6x6x28
KS5	9	3	75.5	58	3	98	62.5	62	0.020	9	M12	M6x1.00	35	11	A10x8x50
KS7	10	3	105	82	4	120	77.5	78	0.025	11	M16	M8x1.25	43	14	A12x8x70

Table 3 Dimensions (mm)

Stand	dard Inpu	it	Lar	ge Input	
Unit	a5	М	Unit	a5	М
KS402	72	137.5	KS402_L	100	141.5
KS403	55	161.0	KS403_L	75	177.5
KS502	98	158.0	KS502_L	115	166.5
KS503	72	205.5	KS503_L	100	209.5
KS702	115	191.0	KS702_L	145	205.0
KS703	98	240.5	KS703_L	115	249.0

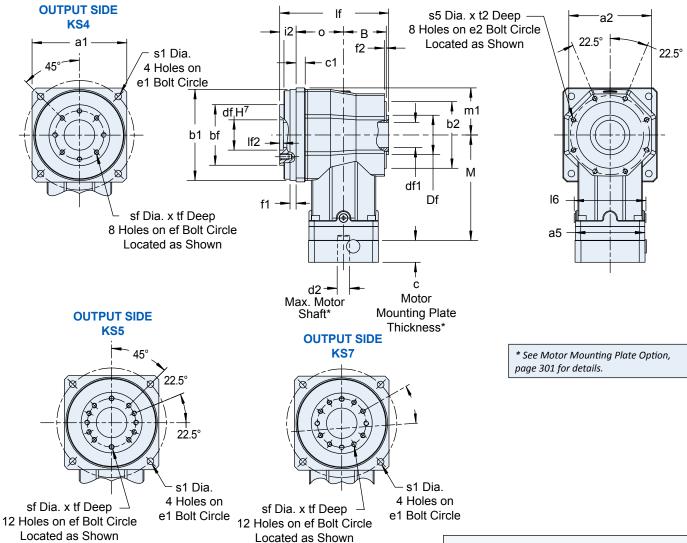
Table 4 Oil Reservoir Dimensions (mm)

Unit Type	dab	hab	hab1	lab
KS403	34	74.5	85	100
KS503	39	92	105	122
KS703	49	109.5	132	134

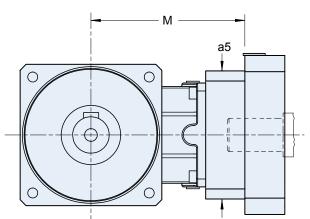


Flanged Hollow Output — "F"

With Standard Input



With Large Input Option



Oil Reservoir (For 3 stage units in vertical EL5 mounting position) - not available with large input option lab hab1

Dimensional Data



Table 1 Dimensions (mm)

Unit	a1	a2	В	b1	h6	b2	h6	bf	h7	c1	Df	d ⁹	df	H ⁷	df1
KS4	101	93	51	95	+0.000/-0.022	75	+0.000/-0.019	63	+0.000/-0.030	10	40	-0.080/-0.180	31.5	+0.025/-0.0	30
KS5	125	109	58	120	+0.000/-0.022	90	+0.000/-0.022	80	+0.000/-0.030	10	48	-0.080/-0.180	40	+0.025/-0.0	38
KS7	155	135	70	150	+0.000/-0.025	110	+0.000/-0.022	100	+0.000/-0.035	15	60	-0.100/-0.174	50	+0.025/-0.0	49

Table 2 Dimensions (mm)

Unit	e1	e2	ef	f1	f2	i2	16	lf	lf2	m1	o	s1	s5	sf	t2	tf
KS4	120	88	50	8	3	20	77.5	127	6	50.5	53	6.6	M5x0.80	M6x1.00	9	11
KS5	145	105	63	9	3	22	98	145	7	62.5	62	9	M6x1.00	M6x1.00	11	12
KS7	180	130	80	10	3	27	120	178	7	77.5	78	11	M8x1.25	M8x1.25	14	15

Table 3 Dimensions (mm)

Stand	dard Inpu	it	Lar	ge Input	
Unit	a5	М	Unit	a5	М
KS402	72	137.5	KS402_L	100	141.5
KS403	55	161.0	KS403_L	75	177.5
KS502	98	158.0	KS502_L	115	166.5
KS503	72	205.5	KS503_L	100	209.5
KS702	115	191.0	KS702_L	145	205.0
KS703	98	240.5	KS703_L	115	249.0

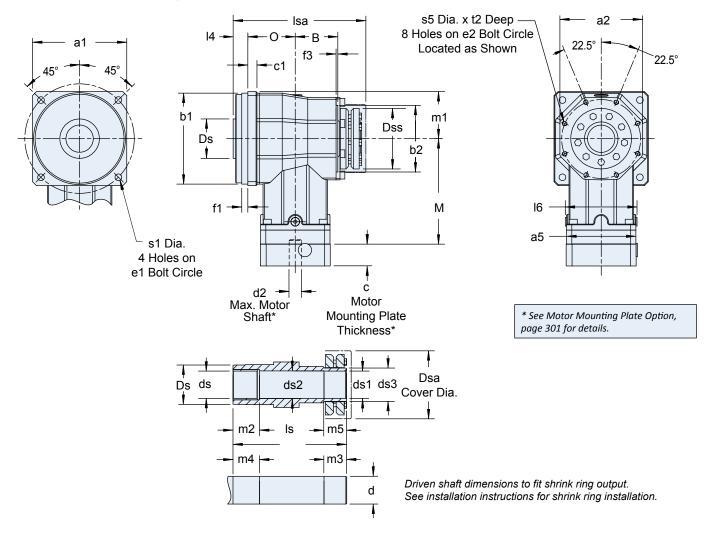
Table 4 Oil Reservoir Dimensions (mm)

Unit Type	dab	hab	hab1	lab
KS403	34	74.5	85	100
KS503	39	92	105	122
KS703	49	109.5	132	134

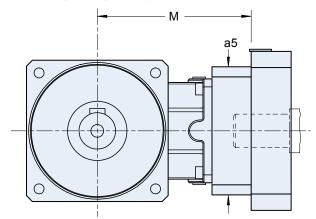


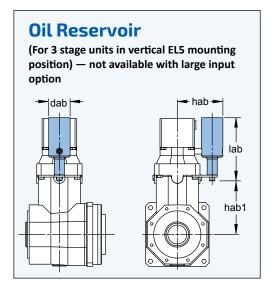
Shrink Ring Output — "S"

With Standard Input



With Large Input Option





Dimensional Data



Table 1 Dimensions (mm)

														d	ds1		
Unit	a1	a2	В	b1	h6	b2	h6	c1	Ds	Dsa	Dss	ds	h9	Bore ^{H9}	Shaft ^{h9}	ds2	ds3
KS4	101	93	51	95	+0.000/-0.022	75	+0.000/-0.019	10	40	72	60	25	+0.000/-0.052	25	25	25.5	30
KS5	125	109	58	120	+0.000/-0.022	90	+0.000/-0.022	10	50	92	80	35	+0.000/-0.062	35	35	35.5	44
KS7	155	135	70	150	+0.000/-0.025	110	+0.000/-0.022	15	65	112	100	45	+0.000/-0.062	45	45	45.5	55

Table 2 Dimensions (mm)

Unit	e1	e2	f1	f2	14	16	ls	lsa	m1	m2	m3	m4	m5	o	s1	s5	t2
KS4	120	88	8	3	18	77.5	151	158	50.5	20	34	25	29	53	6.6	M5x0.80	9
KS5	145	105	9	3	19.5	98	171.5	179.5	62.5	30	39	35	34	62	9	M6x1.00	11
KS7	180	130	10	3	24	120	211	218	77.5	40	42	45	37	78	11	M8x1.25	14

Table 3 Dimensions (mm)

Stan	dard Inpu	t	Large Input				
Unit	a5	М	Unit	a5	М		
KS402	72	137.5	KS402_L	100	141.5		
KS403	55	161.0	KS403_L	75	177.5		
KS502	98	158.0	KS502_L	115	166.5		
KS503	72	205.5	KS503_L	100	209.5		
KS702	115	191.0	KS702_L	145	205.0		
KS703	98	240.5	KS703_L	115	249.0		

Table 4 Oil Reservoir Dimensions (mm)

Unit Type	dab	hab	hab1	lab
KS403	34	74.5	85	100
KS503	39	92	105	122
KS703	49	109.5	132	134

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