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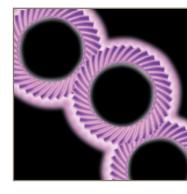








Gearheads and Gearmotors





Parker Hannifin is a Fortune 250 global leader in motion and control technologies. For 100 years the company has engineered the success of its customers in a wide range of diversified industrial and aerospace markets. Parker's engineering expertise and broad range of core technologies uniquely positions the company to help solve the world's greatest engineering challenges. We are the only manufacturer offering customers a choice of electromechanical, hydraulic, pneumatic, or computer-controlled motion systems.

Total System Solutions

Parker's team of highly qualified application engineers, product development engineers, and system specialists can turn pneumatic, structural, and electromechanical products into an integrated system solution.



Moreover, our Selectable Levels of Integration™ allows you to choose the appropriate system, subsystem, or component to meet your specific need.

First in Delivery, Distribution, and Support

In today's competitive, fast-moving economy, what good is an application that isn't ready on time? This is especially true when compressed design cycles make the quick delivery of critical components essential. With factories strategically located on five continents, Parker offers an unrivaled delivery record, getting solutions out our door and onto your floor faster than ever.

Parker also has the industry's largest global distribution network, with more than 8,600 distributors worldwide. Each of these locations maintains ample product inventory to keep your downtime to a minimum. And many distributors have in-house design capabilities to support your system and subsystem requirements.

Throughout the design process, Parker's factory-



Parker world headquarters in Cleveland



trained electromechanical engineers work hand in hand with you and day or night at 1-800-C-Parker. Our operators will connect you with a live, on-call representative who will identify replacement parts or services for all motion

technologies.

Training

Parker's best-in-class technology training includes handson classes, Web-based instruction, and comprehensive texts for employees, distributors, and customers. Parker also provides computer-based training, presentations,

exams, drafting and simulation software, and trainer stands.

parkermotion.com

Our award-winning Web site is your single source for:

- Product information
- Downloadable catalogs
- Motion-sizing software
- 3D design files
- Training materials
- Product-configuration software
- RFQ capabilities
- Videos and application stories

24/7 Emergency Breakdown Support

The Parker product information center is available any time of the day or night at 1-800-C-Parker. Our operators will connect you with a live, on-call representative who will identify replacement parts or services for all motion technologies.





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Visit our Website

Complete up-to-date technical assistance can be found on our web at www.parker.com/emn. This includes all the latest information on current products, new product



introductions, local assistance and support, plus complete product catalog data, product configurators, performance charts and graphs, engineering data and calculations, CAD drawings, local service and support directory, application stories and videos.

Welcome!

Thank you for your interest in the products offered by the Parker Hannifin Electromechanical & Drives Division. This catalog presents Parker's electromechanical solutions for high-precision and high-speed automation. Our gearheads, motors, and integrated products are recognized around the world for their functionality, performance, and reliability.

Bayside pioneered the market for precision servo gearheads many years ago. Parker continues this tradition in quality and design with innovations like our Stealth Generation II Helical Planetary Gearhead, enhanced to provide superior performance for the most demanding applications. Our PV Series planetary gearhead combines power and versatility in an economical package. Our line of frameless motors and other integrated products provide an ideal solution for machine designs that require high performance in small spaces.

As you read through this catalog, you will discover that Parker offers the widest variety of electromechanical solutions that are delivered in the shortest amount of time. Still, many customers require special solutions to satisfy unique or special requirements. Parker has been providing custom engineered solutions for over 30 years to satisfy those requirements. If your application cannot be fulfilled by the complement of products found in this catalog, please contact an authorized Parker Automation Technology Center or a factory applications engineer.

Parker is proud to present these high precision products to you. We invite you to discover the advantages that can be realized by relying on Parker for products and systems which represent the very best value in the electromechanical marketplace.

Offer of Sale

Please visit parker.com/emn to view Parker's Offer of Sale



FAILURE OR IMPROPER SELECTION OR IMPROPER USE OF THE PRODUCTS AND/OR SYSTEMS DESCRIBED HEREIN OR RELATED ITEMS CAN CAUSE DEATH, PERSONAL INJURY AND PROPERTY DAMAGE.

This document and other information from Parker Hannifin Corporation, its subsidiaries and authorized distributors provide product and/or system options for further investigation by users having technical expertise. It is important that you analyze all aspects of your application and review the information concerning the product or system in the current product catalog. Due to the variety of operating conditions and applications for these products or systems, the user, through its own analysis and testing, is solely responsible for making the final selection of the products and systems and assuring that all performance, safety and warning requirements of the application are met.

The products described herein, including without limitation, product features, specifications, designs, availability and pricing, are subject to change by Parker Hannifin Corporation and its subsidiaries at any time without notice.

Product Overview

Planetary Gearheads

Our new Generation II Stealth® Series provides higher radial load, increased service life and ease of mounting than comparably sized planetary gearheads. The Stealth Generation II Helical Planetary Gearheads incorporate design enhancements to provide superior performance for the most demanding high performance applications. For larger frame sizes, Parker offers Generation I Stealth® Series gearheads in 142 to





220 mm and NEMA 56 frame sizes. For standard precision applications, the PV Series gearhead combines power and versatility in an economical package available in a wide range of options.

	Prod Ser		Gear Geometry	Performance	Configuration	Frame Size	Nominal Continuous Torque Nm (in-lb)	Radial Load N (lbs)	Backlash arc-min	
	_	PS	Helical Planetary	High Precision	In-Line	60 – 115 mm	27 – 230 (240 – 2047)	1650 – 7500 (370 – 1683)	8 – <3	12
	neration I Stealth®	РХ	Helical Planetary	Mid Precision	In-Line	60 – 115 mm NEMA 23 – 42	20 – 160 (178 – 1424)	1550 – 6800 (348 – 1526)	10 – <6	16
Generation Stocke	ienera Stea	RS	Helical Planetary/ Spiral Bevel	piral Bevel Precision		60 – 115 mm	13 – 220 (115 – 1958)	1650 – 7500 (370 – 1683)	14 – <6	20
		RX	Helical Planetary/ Right Angle	Mid Precision Right Angl		60 – 115 mm NEMA 23 – 42	10 – 136 (89 – 1210)	1550 – 6800 (348 – 1526)	20 – <12	24
	eneration I Stealth®	PS	Helical Planetary	High Precision	In-Line	180 – 220 mm	294 – 1808 (2616 – 16,091)	7900 – 58,000 (1775 – 13,020)		30
	Generation Stealth®	RS	Helical Planetary/ Spiral Bevel	High Precision	Right Angle	180 – 220 mm	141 – 1808 (1255 – 16,091)	7900 – 58,000 (1775 – 13,020)	10 – <4	34
		PV	Planetary	Standard	In-Line	40 – 115 mm NEMA 17 – 42	3.5 – 148 (31 – 1317)	190 – 10,555 (43 – 2370)	15 – <12	40

MultiDrive Gearheads

Stealth® MultiDrive (MD) offers three different output options for true flexibility. MultiDrive models include low-ratio, dual-shaft and hollow-shaft options in a compact, right angle package. With 5 frame sizes and multiple ratios to choose from,you are guaranteed to find a Stealth® MultiDrive to fit your servo motor application.





Product Series	Gear Geometry	Performance	Configuration	Frame Size	Continuous Torque Nm (in-lb)	Radial Load N (lbs)	Backlash arc-min	
RT	Helical	High Precision	Right Angle Hollow Shaft	90 – 220 mm	23 – 565 (204 – 5178)	2800 – 7500 (692 – 1685)	<14 - <6	48
RD	Helical	High Precision	Right Angle Double Shaft	90 – 220 mm	30 – 150 (266 – 1328	2800 – 7500 (692 – 1685)	<14 - <6	48
RB	Helical	High Precision	Right Angle Low Ratio	90 – 220 mm	35 – 190 (266 – 1682)	2800 – 7500 (692 – 1685)	<14 - <6	48

Application Examples

Plastic Bottle Extrusion

The manufacturer of high-performance plastic extrusion equipment needed a drop-in replacement gearhead for an existing worm gearbox used with their motor without having to



alter the design of their machine. The gearhead/motor combination is being used to drive the machine's rollers, controlling the speed at which the plastic is extruded into high-quality plastic sheets. The smoothness of the rollers is critical to the quality of the plastic sheets being produced.

Application Challenges:

High Transmission Error and Velocity Ripple

The customer used worm gearheads to control the rollers. Worm gears exhibit a sliding action of involute gears instead of a rolling action, contributing to the lack of smoothness of the machine rollers. Due to the high transmission error and velocity ripple from the worm drive, the rollers operated at differing speeds. This produced small lines and imperfections on the plastic sheets, rendering it unusable.

High Wear and Low Efficiency

The high level of rubbing (sliding action) between the worm and wheel teeth in the worm gearhead caused a high gear-tooth-wear rate and a lower efficiency (70%) than other major gear types.

Parker SOLUTION:

Stealth PS Gearhead and RT MultiDrive (hollow shaft) Gearhead were used in combination to provide the required 120:1 ratio. The result was high-quality plastics sheets that exceeded the customer's specifications.



The Stealth's all-helical planetary design (HeliCrown Gear Tooth) features extremely high gear tooth accuracy, minimizing transmission error and velocity ripple. The HeliCrown design features extremely high efficiency (95%) while minimizing tooth wear by providing a pure rolling action. Parker's Plasma Nitriding heat-treating process further heightens the gear tooth's wear resistance.

The MultiDrive gearhead features a space-saving bore (hollow shaft) option, eliminating compliance that occurs when coupling a gearhead shaft to the rollers being driven. This solution can be used for a variety of applications, including packaging, food, semiconductor, automotive and medical.

Food/Packaging Automation

A manufacturer of machines for gluing, fill, sealing and diverting food containers for the food-processing industry had a



requirement for the motor and gearhead to be mounted above the food plane. Certain modifications were also needed for the gearhead to make it safe for the food environment, and capable to withstand frequent washdowns.

Gearhead Design Considerations:

- Lubrication must be USDA food grade approved in case of incidental contact to food
- Sealing –must prevent any leaking as well as prevent any ingress of the fluid during washdown
- Finish special FDA-approved finish must be used making it very durable and resistant to chipping, oxidizing or rusting

 Output Shaft – stainless steel prevents any rust from developing and contaminating the processing food.

Parker SOLUTION:

Stealth PS planetary gearhead with standard F01 food grade special option



Stealth PS planetary gearhead with standard food grade option provides the gearhead with standard modifications including special lubrication, viton seals, special finish and a stainless steel output shaft.

Since this food grade modification is a standard option, delivery is only one week over the standard gearhead lead time. (Note: Similar standard modifications exist for vacuum, clean room, high temperature and radiation.)

High-Speed Milling

High-speed milling machines are commonplace in industries such as aerospace and automotive because they allow large structural components to be machined from one piece rather than assembled from



many smaller subcomponents. For a customer that manufactures high-speed milling machines, spindle heads are operating at speeds ranging from 18,000 to 40,000 RPM, so that the cutting is above the resonant frequency of the machine. Because of this, many characteristics become more critical than with their standard machines. The extremely large size of the spindle head also posed problems for the manufacturer in trying to keep it accurately positioned during the milling stage.

Application Challenge:

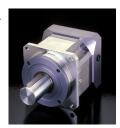
Low Stiffness

The spindle head was moved rotationally by 2 bull gears, driving a large ring gear. Because of the system characteristics, it was difficult to keep the spindle head absolutely stiff during the milling process. The problems associated with low stiffness are:

- Poor surface finish
- Accuracy errors
- · Excessive tool chatter
- · Reduced tool life

Parker SOLUTION:

Two Stealth® PS Helical Planetary Gearheads were used in tandem to create a stiff platform for the spindle machine head. One gearhead, acting as the master, and the other as the slave, were attached to the bull gears to simultaneously turn the ring



gear that positioned the machine head. While the master gearhead moved the ring, the slave was taking up the backlash. In this way, the precision gears allowed for the spindle to be moved accurately, while the two gearhead combination maintained maximum system stiffness.

Parker's Stealth PS gearhead features an all-helical planetary gear design. Helical gears have a much higher tooth-contact ratio and greater face width than straight-spur gears, providing higher loads, smoother tooth engagement and quieter operation. The Stealth's HeliCrown Gear Tooth design provides extremely high gear tooth accuracy, while minimizing tooth wear. Parker Bayside's Plasma Nitriding heat-treating process further heightens the gear tooth's wear resistance.

This solution can also be used in the aerospace and automotive industries.

High-, Mid- and Standard-Precision Planetary Gearheads

Helical planetary technology is superb for low-backlash, high-stiffness and high-accuracy requirements, making the Parker Generation II Stealth® line of helical planetary gearheads ideal for these high-and medium-level performance applications. The introduction of the PV Series gearhead completes the Parker gear family by offering a standard-grade gearhead with the highest radial load capacity available today in a cost-effective solution. Whether you need high-, medium- or standard-grade performance, Parker can match the need. All Parker gearheads are proudly manufactured in the USA in our state-of-the-art facility which, displays the best use of Lean manufacturing practices. For more information go to parkermotion.com.



Generation II Stealth® PS/PX/RS/RX:

Our new Generation II Stealth® series provides higher radial load, increased service life and ease of mounting

The Generation II Stealth* Helical Planetary Gearheads incorporate design enhancements to provide superior performance for the most demanding high performance applications.

Stealth Generation II incorporates dual angular contact bearings providing higher radial load capacities while maintaining high input speeds. Design enhancements also include full complement needle bearings allowing for increased service life and extended warranties. Internal design changes and optimized gearing geometries allow for one oil fill level for any orientation, resulting in shortened part number designation and simplified order placement.

Universal mounting kits provide common mounting kits across multiple product lines to promote quicker deliveries and ease of mounting to any servo motor. Applications that require either high precision (PS/RS Series Gearheads) or mid-range precision (PX/

RX Series Gearheads) utilize the same mounting kit part numbers within the same frame size.

Mounting to any servo motor is as easy as A-B-C (adapter, bushing, collet).

Features & Benefits

- Higher radial load capacity: widely spaced angular contact output bearings
- Increased service life: full complement of planet needle bearings
- Universal mounting kits: quicker deliveries and easier mounting
- High torque and low backlash: helical planetary gearing
- High stiffness: Integral ring gear and rigid sun gear
- Higher gear wear resistance: plasma nitriding heat treating
- PX models are optionally available with flange mounting for easy installation. (Contact factory for flange mount availability for RX models.)



Other Planetary Gearheads:

Generation I Stealth® PS, PX and RS Gearheads

For larger frame sizes, Parker offers Generation I Stealth* Series gearheads in 142 to 220 mm and NEMA 56 frame sizes.

PV Series Precision Gearheads

The PV Series gearhead combines power and versatility in an economical package. It comes in a wide range of options including dimensional output face crossovers to the Parker Bayside PX, Alpha LP, Neugart PLE, Stober PE and standard NEMA gearheads.

Standard Options for Planetary Gearheads

Gearheads Ready to Mount to Linear Actuators

Most belt driven linear slides need a gearhead to reduce inertia.



Parker has pre-engineered in-line and right-angle gearheads to mount directly to most popular linear slides, eliminating the need for couplings or adapters.

Input Shaft Speed Reducer/Speed Increaser for Increased Design Flexibility

Parker gearheads are available with an input-shaft option. The input-shaft option allows more

design flexibility, as options like brakes, encoders, or safety couplings can be used between the motor and the gearhead. This option also allows you to operate the gearhead as a speed increaser.

Mil-Spec Gearheads

Parker has extensive experience in military and aerospace applications. The Stealth Bomber, M1 Tank and the Space Shuttle all use Parker gearheads. Parker's



quality system has been approved by NASA and the US Government to MIL-I-45208A.

Special Environments

Put a Parker gearhead anywhere! Parker can supply gearheads to operate in the harshest environments:



Vacuum - Available as a standard option to 10^{-6} Torr vacuum ratings.

Clean Room - Special gearheads for Class 10,000 clean room applications.

High Temperature - Special lubricants and seals for temperatures up to 250° C.

Radiation - Gearheads customized to operate within radioactive environments.

Food Grade/Washdown - Gearheads customized to operate within food-handling and washdown environments.

Planetary Gearhead Selection Overview

					Nominal Continuous	Radial Load		
	Gear Geometry	Performance	Configuration	Frame Size	Torque Nm (in-lb)			
PS	Helical Planetary	High Precision	In-Line	60 – 115 mm	27 - 230 (240 - 2047)	1650 – 7500 (370 – 1683)	8 – <3	12
PX	Helical Planetary	Mid Precision	In-Line	60 – 115 mm NEMA 23 – 42	20 – 160 (178 – 1424)	1550 – 6800 (348 – 1526)	10 – <6	16
RS	Helical Planetary/ Spiral Bevel	High Precision	Right Angle	60 – 115 mm	13 – 220 (115 – 1958)	1650 – 7500 (370 – 1683)	14 – <6	20
RX	Helical Planetary/ Right Angle	Mid Precision	Right Angle	60 – 115 mm NEMA 23 – 42		1550 – 6800 (348 – 1526)	20 – <12	24
PS	Helical Planetary	High Precision	In-Line	180 – 220 mm	294 – 1808 (2616 – 16,091)	7900 – 58,000 (1775 – 13,020)	8 – <3	30
RS	Helical Planetary/ Spiral Bevel	High Precision	Right Angle	180 – 220 mm	141 – 1808 (1255 – 16,091)	7900 – 58,000 (1775 – 13,020)	10 – <4	34
PV	Planetary	Standard	In-Line	40 – 115 mm NEMA 17 – 42			15 – <12	38
	PX RS RX PS	PS Helical Planetary RS Helical Planetary RS Helical Planetary/ Spiral Bevel RX Helical Planetary/ Right Angle PS Helical Planetary RS Helical Planetary RS Helical Planetary Spiral Bevel	PS Helical Planetary High Precision PX Helical Planetary Mid Precision PX Helical Planetary Mid Precision RS Helical Planetary/ High Precision RX Helical Planetary/ Mid Precision RX Helical Planetary/ High Precision PS Helical Planetary High Precision RS Helical Planetary/ High Precision	PS Helical Planetary High Precision Ps Helical Planetary High Precision In-Line Ps Helical Planetary Mid Precision In-Line Ps Helical Planetary Precision Precision Right Angle Ps Helical Planetary High Precision Ps Helical Planetary Precision Precision Ps Helical Planetary Precision Precision Ps Helical Planetary Precision Precision Precision Right Angle Ps Helical Planetary High Precision Precision Right Angle Ps Helical Planetary Precision Precision Right Angle	PS Helical Planetary High Precision Right Angle Fight Angle PS Helical Planetary Mid Precision Right Angle Helical Planetary Mid Precision Right Angle Fight Angle Precision Right Angle RS Helical Planetary High Precision Right Angle Fight Angle Right Angle R	Continuous Torque Nm (in-lb)	Continuous Load	Continuous Load Torque Racklash Reference Frame Size Torque Racklash Reference Right Angle R

Helical Planetary Gearhead Features

Parker planetary gearheads incorporate the latest technology enhancements...

- Latest technology in seals to reduce heat and wear
- Oil lubrication reduces friction and operating temperature, increasing gear life

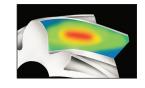
Helical Planetary Design

Helical gears have more tooth contact and greater face width than spur gears. This results in higher loads, smoother tooth engagement, quieter operation and lower backlash.



HeliCrown®

Parker developed the HeliCrown gear tooth to further optimize Stealth's* performance. Since most



vibration occurs at the entry and exit points of a gear tooth, HeliCrown eliminates metal only in these areas, without sacrificing gear strength, producing a quieter and stronger gear.

Plasma Nitriding

Parker's in-house Plasma
Nitriding process results in an ideal gear tooth. The surface is very hard (65 Rc) and the core is strong, but flexible (36 Rc).
The result is a wear-resistant gear tooth that can withstand



heavy shock, ensuring high accuracy for the life of the gearhead.

ServoMount®

Parker's ServoMount design features a balanced input gear supported by a floating bearing. This unique design compensates for motor shaft runout and misalignment, ensuring TRUE alignment of



the input sun gear with the planetary section and allowing input speeds up to 6,000 RPM. ServoMount ensures error-free installation to any motor, in a matter of minutes.





"The Helical Advantage"

Parker planetary gearheads are a superior design with construction integrity to deliver power, speed and accuracy – quietly and efficiently.

Power... 30% more torque than comparably

sized gearheads

Speed... up to 6,000 RPM input speeds

Accuracy... Less than 3 arc-minutes backlash

Quiet... Less than 68 dB noise Efficiency... Over 97% efficiency

Parker Stealth® planetary gearhead features

Universal mounting kits offer easier mounting and quick delivery

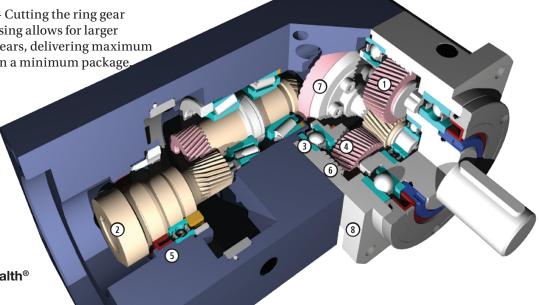
Features unique to Generation II Stealth® gearheads

Widely spaced angular contact bearings provide higher radial load capacity

Full compliment of needle bearings for increased service life

Common features for all Generation I & II Stealth® gearheads

- 1 Helical Planetary Provides smooth, quiet operation, high torque and high accuracy.
- 2 **ServoMount*** Motor-mounting design ensures error-free installation and the balanced pinion allows higher input speeds.
- 3 **Precision Bearings** Provide high speed and high radial and axial load capacity.
- 4 HeliCrown[®] Parker's proprietary gear tooth geometry ensures quieter operation and higher loads than conventional gears.
- 5 **Sealed Unit** Vition seals and O-Rings provide IP65 protection to prevent leaks and protect against harsh environments.
- **6 Integral Ring Gear** Cutting the ring gear directly into the housing allows for larger bearing and planet gears, delivering maximum power and stiffness in a minimum package.



Features unique to Stealth® right-angle gearheads

- **Spiral Bevel Gears** Deliver high efficiency and high torque in a compact, right angle package.
- **®** Compact Design Package size is the same regardless of ratio.

Space Tight? Turn Right

For space constrained applications, Parker's RS and RX right-angle gearheads offer as much as a 2X space savings compared to in-line products.

PS Generation II Performance Specifications

Parameter	Units	Ratio	PS60 Gen II	PS90 Gen II	PS115 Gen II	PS142 Gen II		
		3,15,30	27 (239)	76 (673)	172 (1522)	300 (2656)		
Nominal Output Torque 1)	Nm (in-lb)	4,5,7,20,25,40,50,70	37 (327)	110 (974)	230 (2036)	430 (3807)		
T _{nom r}	, ,	10,100	32 (283)	93 (823)	205 (1814)	310 (2745)		
Maximum Acceleration Output		3,15,30	34 (300)	105 (930)	225 (1990)	450 (3984)		
Torque 2)	Nm (in-lb)	4,5,7,20,25,40,50,70	48 (425)	123 (1090)	285 (2525)	645 (5711)		
T _{acc r}	, ,	10,100	37 (325)	112 (990)	240 (2125)	465 (4117)		
		3,15,30	80 (710)	260 (2300)	600 (5310)	1100 (9739)		
Emergency Stop Output Torque 3)	Nm (in-lb)	4,5,7,20,25,40,50,70	70 (620)	230 (2035)	500 (4425)	970 (8588)		
T _{em r}	, ,	10,100	60 (530)	200 (1770)	430 (3805)	830 (7349)		
		3	3000	2500	2000	1500		
		4,5	3500	3000	2500	2000		
	DD14	7,10,15	4000	3500	3000	2500		
Nominal Input Speed N _{nom r}	RPM	20,25,30	4500	4000	3500	3000		
		40,50	4800	4400	3800	3200		
		70,100	5200	4800	4200	3600		
Maximum Input Speed N _{max r} 4)	RPM	3 – 100	6000	5500	4500	4000		
Maximum Radial Load Prmax 5,7)	N (lbs)		1650 (370)	4800 (1080)	7500 (1685)	10,000 (2247)		
Maximum Axial Load Pa _{max 6}	N (lbs)		2100 (475)	3600 (810)	6800 (1530)	8800 (1976)		
Service Life	h			20,	000			
Standard Backlash 8)	arc-min	3 – 10	<6	<6	<4	<4		
Otanida de Daokidon	aro min	15 – 100	<8	<8	<6	<6		
Low Backlash 8)	arc-min	3 – 10	<4	<4	<3	<3		
	are min	15 – 100	<6	<6	<5	<5		
Efficiency at Nominal Torque	%	3 – 10	97	97	97	97		
·		15 – 100	94	94	94	94		
Noise Level at 3000 RPM 9	db	3 – 100	<62	<62	<65	<66		
Torsional Stiffness	Nm/arc-min (in-lb/arc-min)	3 – 100	3 (27)	12 (105)	27 (240)	50 (438)		
Maximum Allowable Case Temperature	°C	3 – 100	-20 to 90					
Lubrication		3 – 100		Per Maintena	nce Schedule			
Mounting Position		3 – 100		А	ny			
Direction of Rotation		3 – 100		Same a	as Input			
Degree of Protection				IP	65			
Maximum Weight	kg (lbs)	3 – 10	1.3 (2.9)	3.0 (6.6)	7.0 (15.4)	14.0 (30.0)		
Maximum Worght	ng (ibs)	15 – 100	1.7 (3.7)	5.0 (11.0)	10.0 (22.0)	20.0 (43.0)		
At nominal speed Nnom r								

¹⁾ At nominal speed Nnom r.

²⁾ Parker MotionSizer sizing software available for free download at parkermotion.com.

³⁾ Maximum of 1000 stops.

⁴⁾ For intermittent operation.

⁵⁾ Max radial load applied to the center of the shaft at 100 rpm.

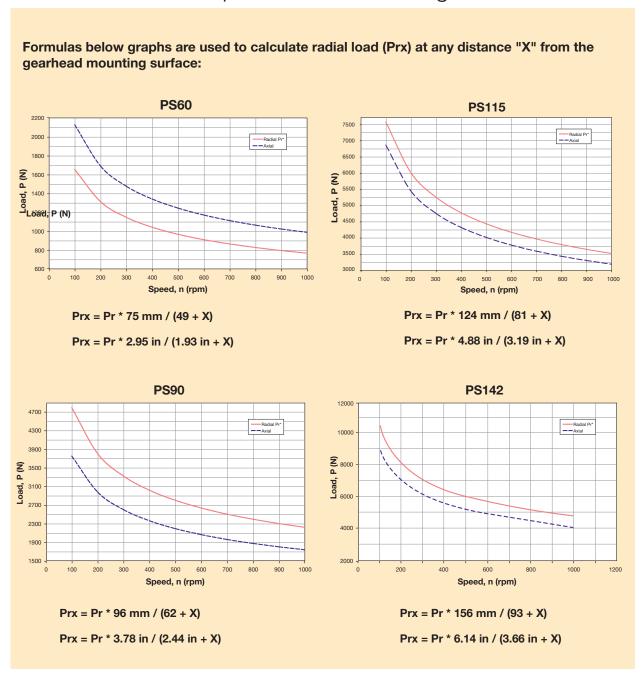
⁶⁾ Max axial load at 100 rpm.

⁷⁾ For combined radial and axial load consult factory.

⁸⁾ Measured at 2% of rated torque.

⁹⁾ Measure at 1m.

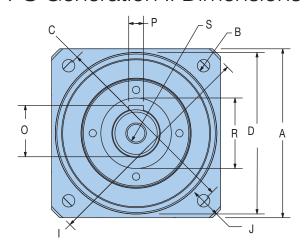
PS Generation II Output Shaft Load Rating

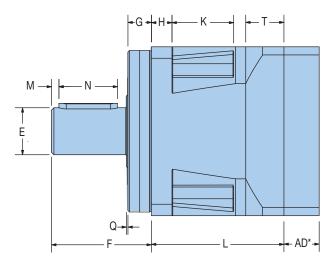


^{*} Radial load applied to center of the shaft.

PS Generation II Dimensions

Free 3D Solid Models and drawings available at parkermotion.com





Metric Frame Sizes

Frame	Squ	A uare nge	B Bolt Hole		C Bolt Circle		Pi	O lot neter	Outpu	E t Shaft neter	Outpu	F t Shaft	Pi	G lot kness
Size	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in
PS60	62	2.441	5.5	0.217	70	2.756	50	1.969	16	0.630	40	1.575	11	0.433
PS90	90	3.543	6.5	0.256	100	3.937	80	3.150	22	0.866	52	2.047	15	0.591
PS115	115	4.528	8.5	0.335	130	5.118	110	4.331	32	1.260	68	2.677	16	0.630
PS142	142	5.591	11.0	0.433	165	6.496	130	5.118	40	1.575	102	4.016	20	0.787

	H	4		I		J	-	<	L	.1	L	.2	N	/ I
Frame		nge kness	Housing Diameter		Housing Recess			ess	(3-	igth -10 iios)	(15-	ngth -100 :ios)		ce from t End
Size	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in
PS60	8	0.315	80	3.150	5	0.197	24	0.945	59.8	2.354	94.8	3.732	2	0.079
PS90	10	0.394	116	4.567	6.5	0.256	33	1.299	69.5	2.736	113	4.449	3	0.118
PS115	14	0.551	152	5.984	7.5	0.295	42	1.654	90.2	3.551	143.4	5.646	5	0.197
PS142	15	0.591	185	7.283	10.0	0.394	45	1.772	103.7	4.083	170.7	6.720	5	0.197

	- 1	N	0		P		Q		1	R	s		Т
Frame	-	way ngth	Key Height		Keyway Width			ulder ight		ulder neter	Tap & Depth		lousing kness
Size	mm	in	in mm in		mm	in	mm	in	mm	in	(end of shaft)	mm	in
PS60	25	0.984	18	0.709	5	0.197	1	0.039	22	0.866	M5x8	20.3	0.799
PS90	32	1.260	24.5	0.965	6	0.236	1	0.039	35	1.378	M8x16	20	0.787
PS115	40	1.575	35	1.378 10		0.394	1.5	0.059	50	1.969	M12x25	26	1.024
PS142	63	2.480	43	1.693	12	0.472	2.5	0.098	78	3.071	M16x32	31	1.220

PS Generation II Universal Mounting Kit*

Adapter Length "AD" Dimension

	Motor Sha	aft Length	Gearhead Adapte	er Length
Frame Size	mm	in	mm	in
60	16 – 35	0.630 – 1.378	16.5	0.65
	35.1 – 41	1.382 – 1.614	22.5	0.886
90	20 - 40	0.787 – 1.575	20	0.787
	40.1 - 48	1.579 – 1.890	28.5	1.122
115	22 - 50	0.866 - 1.969	24	0.945
	50.1 - 61	1.972 - 2.402	35	1.378
142	26 - 62	1.023 – 2.441	30	1.181
	62.1 - 82	2.445 – 3.228	50	1.969

^{*} Know your motor and need our mounting kit part number? See page 29 or use our Motor Mounting Search Tool on our website at: www.parkermotion.com

PS Generation II Inertia

All moment of inertia values are as reflected at the input of the gearhead

Ratio	Units*	PS60	PS90	PS115	PS142
3	kg-cm ²	0.2500	0.9700	3.4000	14.8000
3	in-lb-sec ²	0.000221	0.000858	0.003009	0.013098
4	kg-cm ²	0.1700	0.6700	2.2000	9.8000
4	in-lb-sec ²	0.000150	0.000593	0.001947	0.008673
5	kg-cm ²	0.1500	0.5100	1.7000	7.0000
5	in-lb-sec ²	0.000133	0.000451	0.001505	0.006195
7	kg-cm ²	0.1400	0.4100	1.3000	5.3000
1	in-lb-sec ²	0.000124	0.000363	3.4000 14 0.003009 0.0 2.2000 9 0.001947 0.0 1.7000 7 0.001505 0.0 1.3000 5 0.001151 0.0 1.1000 4 0.000974 0.0 0.1700 6 0.000150 0.0 1.7000 6 0.001505 0.0 1.7000 6 0.001505 0.0 1.7000 6 0.001505 0.0 1.7000 6	0.004691
10	kg-cm ²	0.1400	0.3700	1.1000	4.4000
10	in-lb-sec ²	0.000124	0.000327	0.000974	0.003894
15	kg-cm ²	0.1500	0.5200	0.1700	6.4000
15	in-lb-sec ²	0.150000	0.000460	0.000150	0.005664
20	kg-cm ²	0.1500	0.5100	1.7000	6.4000
20	in-lb-sec ²	0.000133	0.000451	0.001505	0.005664
25	kg-cm ²	0.1500	0.5100	1.7000	6.4000
20	in-lb-sec ²	0.000133	0.000451	0.001505	0.005664
20 40 50 70 400	kg-cm ²	0.1300	0.3700	1.1000	4.2000
30, 40, 50, 70, 100	in-lb-sec ²	0.000115	0.000327	0.000974	0.003717

^{*} Note: 1 kg-cm² = 0.000885 in-lb-sec²

PX Generation II Performance Specifications

Parameter	Units	Ratio	PX60 Gen II	PX90 Gen II	PX115 Gen II
Naminal Outrat Tarras 1)		3,15,30	20 (177)	56 (496)	120 (1062)
Nominal Output Torque ¹⁾ Tnom r	Nm (in-lb)	4,5,7,20,25,40,50,70	32 (283)	66 (584)	152 (1345)
· nom r		10,100	25 (221)	60 (531)	160 (1416)
Maximum Acceleration Output		3,15,30	27 (240)	84 (743)	180 (1593)
Torque ²⁾	Nm (in-lb)	4,5,7,20,25,40,50,70	39 (345)	98 (867)	228 (2018)
T _{acc r}		10,100	30 (265)	90 (797)	192 (1700)
Emergency Stop Output Torque		3,15,30	64 (565)	208 (1840)	480 (4248)
3)	Nm (in-lb)	4,5,7,20,25,40,50,70	56 (495)	184 (1628)	400 (3540)
T _{em r}		10,100	48 (425)	160 (1416)	344 (3044)
		3	3000	2500	2000
		4,5	3500	3000	2500
Nominal Input Speed N _{nom r}	RPM	7,10,15	4000	3500	3000
Nominal input Speed Nnom r	I II IVI	20,25,30	4500	4000	3500
		40,50	4800	4400	3800
		70,100	5200	4800	4200
Maximum Input Speed N _{max r} 4)	RPM	3 – 100	6000	5500	4500
Maximum Radial Load Prmax 5,7)	N (lbs)		1550 (348)	2800 (630)	5500 (1235)
Maximum Axial Load Pa _{max 6}	N (lbs)		2100 (475)	3600 (810)	6800 (1530)
Service Life	h			20,000	
Standard Backlash 8)	arc-min	3 – 10	<10	<9	<8
		15 – 100	<12	<11	<10
Low Backlash 8)	arc-min	3 – 10	<8	<7	<6
		15 – 100	<10	<9	<8
Efficiency at Nominal Torque	%	3 – 10	97	97	97
		15 – 100	94	94	94
Noise Level at 3000 RPM 9	db	3 – 100	<62	<62	<65
Torsional Stiffness	Nm/arc-min (in-lb/arc- min)	3 – 100	2.5 (22) 10 (9		22 (195)
Maximum Allowable Case Temperature	° C	3 – 100		-20 to 90	
Lubrication		3 – 100	Per	Maintenance Scheo	dule
Mounting Position		3 – 100		Any	
Direction of Rotation		3 – 100		Same as Input	
Degree of Protection				IP65	
Maximum Weight	ka (lbe)	3 – 10	1.0 (2.2)	3.0 (6.6)	7.0 (15.4)
waxiiiuiii weigiit	kg (lbs)	15 – 100	2.0 (4.4)	5.0 (11.0)	10.0 (22.0)

¹⁾ At nominal speed Nnom r.

²⁾ Parker MotionSizer sizing software available for free download at parkermotion.com.

³⁾ Maximum of 1000 stops.

⁴⁾ For intermittent operation.

⁵⁾ Max radial load applied to the center of the shaft at 100 rpm.

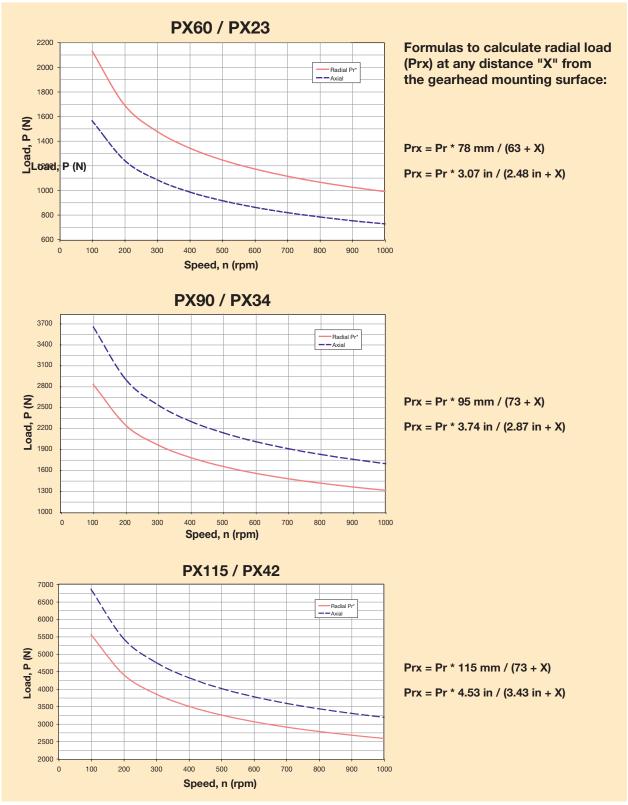
⁶⁾ Max axial load at 100 rpm.

⁷⁾ For combined radial and axial load consult factory.

⁸⁾ Measured at 2% of rated torque.

⁹⁾ Measure at 1m.

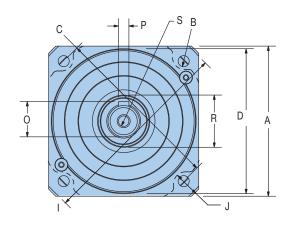
PX Generation II Output Shaft Load Rating

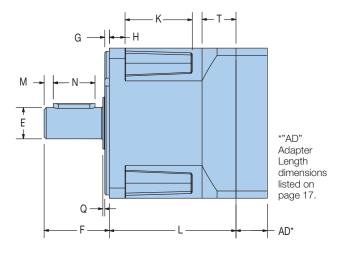


^{*} Radial load applied to center of the shaft.

PX Generation II Dimensions

Free 3D Solid Models and drawings available at parkermotion.com





Metric Frame Sizes

		Α	ı	3	(С	ı)	ı	E		F	(G	ı	Н		I	,	J	ı	K
	Sq	uare		nge olt		nge olt				Output Output Shaft Shaft		•	Pi	lot	Fla	nge	Hou	sing	Hou	sing	Red	ess
Frame	riange		Н	ole	Ci	rcle	Dian	neter	Dian	neter	Ler	ngth	Thic	kness	Thic	kness	Dian	neter	Red	ess	Ler	ngth
Size	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in
PX60	62	2.441	5.5	0.217	70	2.756	50	1.969	16	0.630	25	0.984	2.5	0.098	8	0.315	82	3.228	5	0.197	35	1.38
PX90	90	3.543	6.5	0.256	100	3.937	80	3.150	20	0.787	40	1.575	3	0.118	10	0.394	116	4.567	6.5	0.256	43	1.69
PX115	115	4.528	8.5	0.335	130	5.118	110	4.331	24	0.945	50	1.969	3.5	0.138	14	0.551	152	5.984	7.5	0.295	51	2.0

		L	.1	L	2	ı	M	- 1	N	()		Р	(Q	- 1	R	s		Т
		Ler	igth	Len	gth	Dist	ance											Tap &	Re	ear
		Sin	gle	Dou	ıble	fre	om	Key	way	K	ey	Key	way	Sho	ulder	Sho	ulder	Depth	Hou	sing
	Frame	Stage		Sta	ge	Shaf	t End	Ler	Length		Height		dth	He	ight	Dian	neter	(end of	Thicl	kness
	Size	mm	in	mm	in	mm	in	mm			in	mm	in	mm	in	mm	in	shaft)	mm	in
	PX60	70.3	2.77	105.3	4.15	3	0.118	16	0.630	18	0.709	5	0.197	1	0.039	21	0.827	M5x8	20.3	0.799
	PX90	80	3.15	123.5	4.87	5	0.197	28	1.102	22.5	0.886	6	0.236	1	0.039	29	1.142	M8x16	20	0.787
Ì	PX115	97	3.82	150.2	5.92	7	0.276	32	1.260	27	1.063	8	0.315	1.5	0.059	36	1.417	M8x16	26	1.024

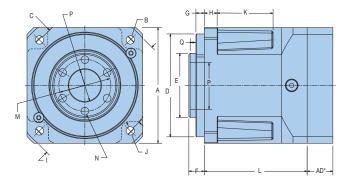
NEMA Frame Sizes

	В			С	- 1	D	E Control Chaff			F	N		О		Р	
Frame	Hole			olt rcle	Pilot Diameter		Output Shaft Diameter		Output Shaft Length		Keyway Length		Keyway Depth		Keyway Width	
Size	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm
PX23	0.2	4.953	2.625	66.675	1.5	38.100	0.38	9.525	1	25.400	_	_	_	_	_	_
PX34	0.22	5.512	3.88	98.425	2.88	73.025	0.5	12.700	1.25	31.750	1.06	27.000	0.07	1.829	0.13	3.251
PX42	0.28	7.137	4.95	125.730	2.19	55.550	0.63	15.875	1.5	38.100	1.14	29.007	0.09	2.388	0.19	4.775

PX23 has a flat on output shaft, not a keyway

NOTE: NEMA Sizes have 20% lower torque/stiffness ratings due to smaller output shaft diameter.

PX Flange Mount Option Dimensions



Dimensions A through D and H through L2 are the same as the metric frame dimensions shown on the previous page 18.

	E	E	ı	=	G		
Frame	-	Hollow iameter	-		Pilot Thickness		
Size	mm	in	mm	in	mm	in	
PX60-T01	32	1.26	7.5	0.30	2.5	0.10	
PX90-T01	50	1.97	12	0.47	6.5	0.26	
PX115-T01	70	2.76	14.5	0.57	8.5	0.33	

	M		N	F)		Q	
				Sh	aft			
	Shaft Bolt		Tap	Pi	lot	Shaft		
Frame	Ci	rcle	Size	Dian	neter	Pilot Depth		
Size	mm	in		mm	in	mm	in	
PX60-T01	25	0.984	M5 x 0.8	18	0.709	4	0.157	
PX90-T01	40	1.575		25	0.984	5	0.197	

PX Generation II Universal Mounting Kits* Adapter Length "AD" Dimension

Frame	Motor S	haft Length		rhead r Length
Size	mm	in	mm	in
60	16 – 35	0.630 - 1.378	16.5	0.65
	35.1 – 41	1.382 - 1.614	22.5	0.886
90	20 – 40	0.787 - 1.575	20	0.787
	40.1 – 48	1.579 - 1.890	28.5	1.122
115	22 – 50	0.866 - 1.969	24	0.945
	50.1 – 61	1.972 - 2.402	35	1.378

^{*} Know your motor and need our mounting kit part number? See page 29 or use our Motor Mounting Search Tool on our website at: www.parkermotion.com

PX Generation II Inertia

All moment of inertia values are as reflected at the input of the gearhead

Ratio	Units*	PX60 / PX23	PX90 / PX34	PX115 / PX42
3	kg-cm ²	0.2500	0.9700	3.4000
3	in-lb-sec ²	0.000221	0.000858	0.003009
4	kg-cm ²	0.1700	0.6700	2.2000
4	in-lb-sec ²	0.000150	0.000593	0.001947
5	kg-cm ²	0.1500	0.5100	1.7000
5	in-lb-sec ²	0.000133	0.000451	0.001505
7	kg-cm ²	0.1400	0.4100	1.3000
1	in-lb-sec ²	0.000124	0.000363	0.001151
10	kg-cm ²	0.1400	0.3700	1.1000
10	in-lb-sec ²	0.000124	0.000327	0.000974
15	kg-cm ²	0.1500	0.5200	1.7000
15	in-lb-sec ²	0.150000	0.000460	0.000150
20	kg-cm ²	0.1500	0.5100	1.7000
20	in-lb-sec ²	0.000133	0.000451	0.001505
25	kg-cm ²	0.1500	0.5100	1.7000
20	in-lb-sec ²	0.000133	0.000451	0.001505
20 40 50 70 400	kg-cm ²	0.1300	0.3700	1.1000
30, 40, 50, 70, 100	in-lb-sec ²	0.000115	0.000327	0.000974

^{*} Note: 1 kg-cm² = 0.000885 in-lb-sec²

RS Generation II Performance Specifications

Parameter	Units	Ratio	RS60	Gen II	RS90	Gen II	RS115	Gen II	RS142	Gen II
		5	13	(115)	55	(487)	85	(752)	225	(1992)
Nominal Output Torque 1)	Nino (in Ila)	10	24	(212)	80	(708)	160	(1415)	365	(3232)
T _{nom r}	Nm (in-lb)	15,20,25,50	35	(310)	88	(779)	220	(1947)	430	(3807)
		30,40,100	30	(266)	86	(752)	195	(1726)	310	(2745)
		5	19	(168)	83	(743)	127	(1124)	337	(2984)
Maximum Acceleration Output	.	10	36	(320)	120	(743)	240	(2124)	547	(4843)
Torque ²⁾ T _{acc r}	Nm (in-lb)	15,20,25,50	45	(400)	123	(867)	255	(2257)	645	(5711)
acc r		30,40,100	37	(327)	112	(797)	240	(2124)	465	(4717)
		5	40	(355)	150	(1327)	270	(2390)	625	(5534)
Emergency Stop Output Torque 3)	Nico Co. Hal	10	72	(637)	240	(2125)	480	(4248)	1000	(8854)
T _{em r}	Nm (in-lb)	15,20,25,50	80	(708)	250	(2213)	510	(4514)	1100	(9739)
		30,40,100	60	(531)	200	(1770)	430	(3806)	830	(7349)
		5 to 10	32	00	28	00	24	00	20	000
Nominal Input Speed N _{nom r}	RPM	15,20,25,30,40	37	00	33	00	29	000	25	00
		50,100	4200		3800		3400		3000	
Maximum Input Speed N _{max r} ⁴⁾	RPM	5 – 100	6000		5300		45	00	3800	
Maximum Radial Load Pr _{max} 5, 7)	N (lbs)		1650	(370)	4800	(1080)	7500	(1685)	10,000	(2247)
Maximum Axial Load Pa _{max 6)}	N (lbs)		2100	(475)	3600	(810)	6800	(1530)	8800	(1976)
Service Life	h					20,	000			
Standard Backlash 8	arc-min	5 – 10	<	14	<	12	<	12	<	10
Standard Backlasii	arc-min	15 – 100	<	12	<	10	<	10	<	:8
Low Backlash 8)	arc-min	5 – 10	<	10	<	8	<	:8	<	:6
LOW BUCKIESTI	are min	15 – 100	<	:8	<	6	<	:6	<	:4
Efficiency at Nominal Torque	%	5 – 100	9	4	9	4	9	14	9	14
Noise Level at 3000 RPM 9	db	5 – 100	<(65	<6	86	<	68	<	70
Torsional Stiffness	Nm/arc-min (in-lb/arc-min)	5 – 100	2.5	(22)	10	(90)	22	(195)	42	(372)
Maximum Allowable Case Temperature	° C	5 – 100				-20 1	to 90			
Lubrication		5 – 100			Per M	laintena	nce Sch	nedule		
Mounting Position		5 – 100				Aı	ny			
Degree of Protection						IP	65			
Maximum Weight	kg (lbs)	5 – 100	2.0	(4.4)	6.0	(13.2)	11.0	(24.2)	24	(52)

¹⁾ At nominal speed Nnom r.

²⁾ Parker MotionSizer sizing software available for free download at parkermotion.com.

³⁾ Maximum of 1000 stops.

⁴⁾ For intermittent operation.

⁵⁾ Max radial load applied to the center of the shaft at 100 rpm.

⁶⁾ Max axial load at 100 rpm.

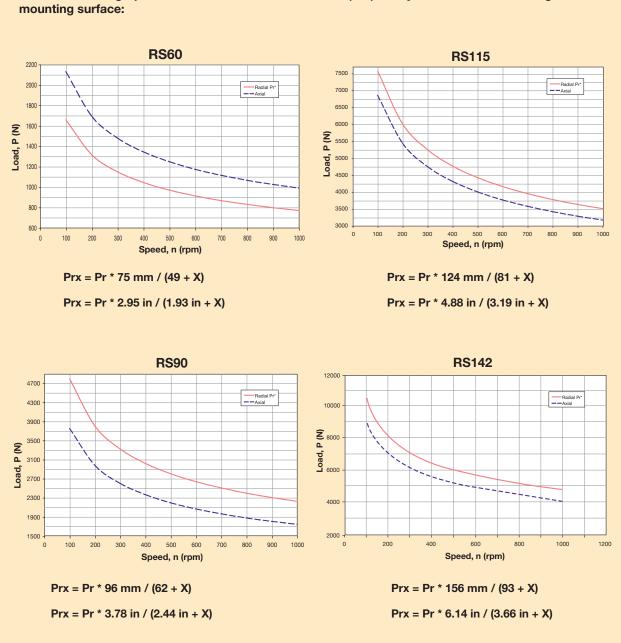
⁷⁾ For combined radial and axial load consult factory.

⁸⁾ Measured at 2% of rated torque.

⁹⁾ Measure at 1m.

RS Generation II Output Shaft Load Rating

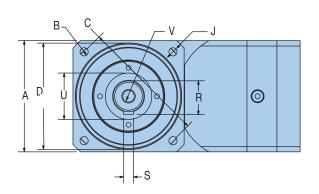
Formulas below graphs are used to calculate radial load (Prx) at any distance "X" from the gearhead

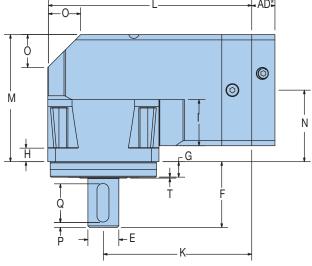


^{*} Radial load applied to center of the shaft.

RS Generation II Dimensions

Free 3D Solid Models and drawings available at parkermotion.com





Metric Frame Sizes

	,	4	E	3	(С	ı	ס	ı	E		F		G	ı	н
_	Square Flange		Bo Ho			olt cle	Pilot Di	iameter	•	t Shaft neter		ıt Shaft ngth		ilot kness		nge kness
Frame Size	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in
RS60	62	2.441	5.5	0.217	70	2.756	50	1.969	16	0.630	40	1.575	11	0.433	8	0.315
RS90	90	3.543	6.5	0.256	100	3.937	80	3.150	22	0.866	52	2.047	15	0.591	10	0.394
RS115	115	4.528	8.5	0.335	130	5.118	110	4.331	32	1.260	68	2.677	16	0.630	14	0.551
RS142	142	5.591	11.0	0.433	165	6.496	130	5.118	40	1.575	102	4.016	20	0.787	15	0.591

			I		J	ŀ	(- 1	L	N	И		N		0	I	Р
	Recess Lengtl		Length	Hou Rec	Ū	Distance to Output Centerline		Housing Length		Housing Width		Distance to Input Centerline		Taper Distance		Distance from Shaft End	
	Frame																
	Size	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in
	RS60	23.5	0.925	5.0	0.197	66.0	2.598	124.7	4.909	78.0	3.071	47.0	1.850	15	0.591	2	0.079
	RS90	33.0	1.299	6.5	0.256	132.0	5.197	177.0	6.969	103.0	4.055	58.0	2.283	27	1.063	3	0.118
j	RS115	42.0	1.653	7.5	0.295	153.5	6.043	211.0	8.307	132.0	5.177	74.0	2.913	34	1.339	5	0.197
	RS142	56.5	2.224	10.0	0.394	198.5	7.815	269.5	10.610	158.2	6.228	87.2	3.433	42	1.654	5	0.197

	(2	F	3	:	S		т	ι	J	V
_	Keyway Length		Key H	Key Height Keyway \		y Width	Shoulder Width Height			ulder neter	- 05 11
Frame Size	mm	in	mm	in	mm	in	mm	in	mm	in	Tap & Depth (end of shaft)
RS60	25	0.984	18.0	0.709	5	0.197	0.5	0.020	22	0.866	M5x8
RS90	32	1.260	24.5	0.965	6	0.236	0.5	0.020	35	1.378	M8x16
RS115	40	1.575	35.0	1.378	10	0.394	1	0.039	45	1.772	M12x25
RS142	63	2.480	43.0	1.693	12	0.472	2.5	0.098	78	3.071	M16x32

RS Generation II Universal Mounting Kits*

Adapter Length "AD" Dimension

From	Motor Sha	aft Length	Gearhead Adapter Length			
Frame Size	mm	in	mm	in		
60	16 – 35	0.630 - 1.378	16.5	0.65		
	35.1 – 41	1.382 - 1.614	22.5	0.886		
90	20 – 40	0.787 - 1.575	20	0.787		
	40.1 – 48	1.579 - 1.890	28.5	1.122		
115	22 – 50	0.866 - 1.969	24	0.945		
	50.1 – 61	1.972 - 2.402	35	1.378		
142	26 - 62	1.023 - 2.441	30	1.181		
	62.1 - 82	2.445 - 3.228	50	1.969		

^{*} Know your motor and need our mounting kit part number? See page 29 or use our Motor Mounting Search Tool on our website at: www.parkermotion.com

RS Generation II Inertia

All moment of inertia values are as reflected at the input of the gearhead

Ratio	Units*	RS60	RS90	RS115	RS142
5	kg-cm ²	0.2200	0.8100	2.5000	9.4000
5	in-lb-sec ²	0.000195	0.000717	0.002213	0.008319
10	kg-cm ²	0.1900	0.6100	1.9000	6.7000
10	in-lb-sec ²	0.000168	0.000540	0.001682	0.005929
15	kg-cm ²	0.1800	0.6000	1.7000	6.6000
15	in-lb-sec ²	0.150000	0.000531	0.001505	0.005841
20	kg-cm ²	0.1700	0.5100	1.4000	5.2000
20	in-lb-sec ²	0.000150	0.000451	0.001239	0.004602
25	kg-cm ²	0.1600	0.4200	1.3000	4.5000
25	in-lb-sec ²	0.000142	0.000372	0.001151	0.003983
30	kg-cm ²	0.1800	0.6000	1.7000	6.7000
30	in-lb-sec ²	0.000159	0.000531	0.001505	0.005929
40	kg-cm ²	0.1700	0.5100	1.4000	5.2000
40	in-lb-sec ²	0.000150	0.000451	0.001239	0.004602
50	kg-cm ²	0.1500	0.4000	1.1000	3.4000
00	in-lb-sec ²	0.000133	0.000354	0.000974	0.003009
100	kg-cm ²	0.1500	0.4000	1.1000	3.4000
100	in-lb-sec ²	0.000133	0.000354	0.000974	0.003009

^{*} Note: 1 kg-cm² = 0.000885 in-lb-sec²

RX Generation II Performance Specifications

Parameter	Units	Ratio	RX60 Gen II/23	RX90 Gen II/34	RX115 Gen II/42
		5	10 (89)	44 (390)	68 (602)
Nominal Output Torque 1)	Nm (in-lb)	10	19 (168)	64 (566)	128 (1133)
T _{nom r}	MIII (III-ID)	15,20,25,50	24 (212)	66 (585)	136 (1204)
		30,40,100	20 (177)	60 (530)	128 (1133)
		5	15 (133)	66 (584)	102 (903)
Maximum Acceleration Output Torque 2)	Nina (in Ila)	10	28 (248)	96 (850)	192 (1700)
T _{acc r}	Nm (in-lb)	15,20,25,50	36 (319)	100 (885)	204 (1805)
acc r		30,40,100	30 (266)	90 (797)	192 (1700)
		5	32 (283)	120 (1062)	216 (1912)
Emergency Stop Output Torque 3)	Nm (in lh)	10	58 (513)	192 (1700)	384 (3398)
T _{em r}	Nm (in-lb)	15,20,25,50	64 (566)	200 (1770)	408 (3611)
		30,40,100	48 (425)	160 (1416)	345 (3053)
		5,10	3200	2800	2400
Nominal Input Speed N _{nom r}	RPM	15,20,25,30,40	3700	3300	2900
		50,100	4200	3800	3400
Maximum Input Speed N _{max r} ⁴⁾	RPM	5 – 100	6000	5300	4500
Maximum Radial Load Pr _{max} 5,7)	N (lbs)		1550 (348)	2800 (1079)	5500 (1236)
Maximum Axial Load Pa _{max 6)}	N (lbs)		2100 (475)	3600 (810)	6800 (1530)
Service Life	h			20,000	
Standard Backlash 8)	arc-min	5 – 10	<20	<18	<16
	G. 6 11	15 – 100	<20	<18	<16
Low Backlash 8)	arc-min	5 – 10	<18	<16	<14
	0/	15 – 100	<16	<14	<12
Efficiency at Nominal Torque	%	5 – 100	94	94	94
Noise Level at 3000 RPM 9	db	5 – 100	<65	<68	<68
Torsional Stiffness	Nm/arc-min (in-lb/arc- min)	5 – 100	2.5 (22)	10 (90)	22 (195)
Maximum Allowable Case Temperature	°C	5 – 100		-20 to 90	
Lubrication		5 – 100	Per	Maintenance Scheo	lule
Mounting Position		5 – 100		Any	
Degree of Protection				IP65	
Maximum Weight	kg (lbs)	5 – 100	2.0 (4.4)	6.0 (13.2)	11.0 (24.2)

¹⁾ At nominal speed Nnom r.

²⁾ Parker MotionSizer sizing software available for free download at parkermotion.com.

³⁾ Maximum of 1000 stops.

⁴⁾ For intermittent operation.

⁵⁾ Max radial load applied to the center of the shaft at 100 rpm.

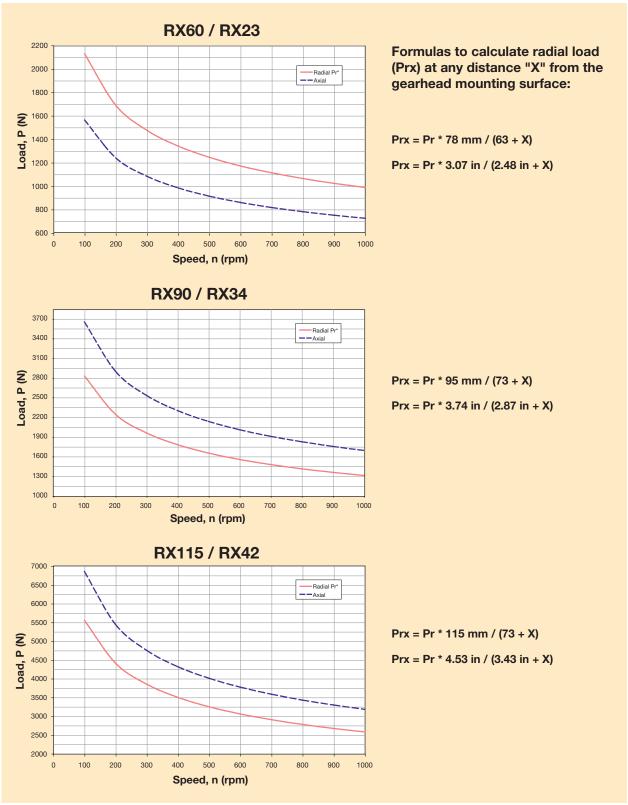
⁶⁾ Max axial load at 100 rpm.

⁷⁾ For combined radial and axial load consult factory.

⁸⁾ Measured at 2% of rated torque.

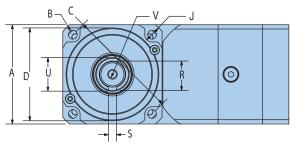
⁹⁾ Measure at 1m.

RX Generation II Output Shaft Load Rating

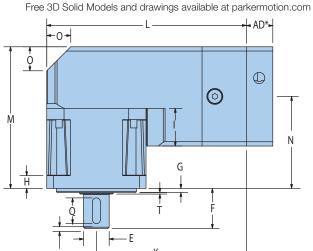


^{*} Radial load applied to center of the shaft.

RX Generation II Dimensions



RX Gearheads also available with Flange Mount Option – Contact Factory



Metric Frame Sizes

		Α	- 1	В		С		D		E		F		G		Н		I		J	ŀ	(
									Οι	tput	Ou	tput									Dista	ance
	Sq	uare	В	olt	В	olt	Р	ilot	S	haft	Sh	naft	Р	ilot	Fla	ange	Red	cess	Ηοι	using	to O	utput
Fram	Fla	nge	He	ole	Ci	rcle	Diar	meter	Dia	meter	Lei	ngth	Thic	kness	Thic	kness	Ler	ngth	Re	cess	Cent	erline
Size	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in
RX60	62	2.441	5.5	0.217	70	2.756	50	1.969	16	0.630	25	0.984	2.5	0.098	13	0.512	23.5	0.925	5	0.197	93.7	3.689
RX90	90	3.543	6.5	0.256	100	3.937	80	3.150	20	0.787	40	1.575	3	0.118	17	0.669	36.5	1.437	6.5	0.256	132	5.197

		L	ı	VI	- 1	N		0		Р	(Q		R		S		Т		U	V
					Dist	ance			Dis	tance											
	Hou	sing	Hou	sing	to I	nput	Ta	per	from	Shaft	Key	way			Ke	yway	Sho	ulder	Sho	ulder	Tap & Depth
Frame	Ler	ngth	Wi	dth	Cent	erline	Dist	ance	E	nd	Ler	ngth	Key I	Height	W	idth	He	ight	Diar	neter	(end of
Size	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	shaft)
RX60	124.5	4.902	88.5	3.484	57.5	2.264	14	0.551	3	0.118	16	0.630	18	0.709	5	0.197	0.5	0.020	21	0.827	M5x8
RX90	177	6.969	114	4.469	68.5	2.697	25	0.984	5	0.197	28	1.102	24.5	0.965	6	0.236	0.5	0.020	29	1.142	M8x16
RX115	211	8.307	138	5.445	81	3.189	32	1.260	7	0.276	32	1.260	27	1.063	8	0.315	1	0.039	36	1.417	M8x16

NEMA Frame Sizes

		В		С		D		ı	E		F	(2	F	3	5	3
_		Bolt Hole		Bolt Circle		Pilot Diameter			Output Shaft Diameter		t Shaft ngth	Keyway Length		•	way pth	Key Wi	way dth
	rame																
S	ize	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm
R	X23	0.2	4.953	2.625	66.675	1.5	38.100	0.38	9.525	1	25.400	-	_	_	_	_	_
R	X34	0.22	5.512	3.88	98.425	2.88	73.025	0.5	12.700	1.25	31.750	1.06	27.000	0.07	1.829	0.13	3.251
R	X42	0.28	7.137	4.95	125.730	2.19	55.550	0.63	15.875	1.5	38.100	1.14	29.007	0.09	2.388	0.19	4.775

RX23 has a flat on output shaft, not a keyway NOTE: NEMA Sizes have 20% lower torque/stiffness ratings due to smaller output shaft diameter.

RX Generation II Universal Mounting Kits*

Adapter Length "AD" Dimension

France	Motor Sha	aft Length	Gearhead Ad	lapter Length
Frame Size	mm	in	mm	in
60	16 – 35	0.630 - 1.378	16.5	0.65
	35.1 – 41	1.382 - 1.614	22.5	0.886
90	20 - 40	0.787 - 1.575	20	0.787
	40.1 - 48	1.579 - 1.890	28.5	1.122
115	22 – 50	0.866 - 1.969	24	0.945
	50.1 – 61	1.972 - 2.402	35	1.378

^{*} Know your motor and need our mounting kit part number? See page 29 or use our Motor Mounting Search Tool on our website at: www.parkermotion.com

RX Generation II Inertia

All moment of inertia values are as reflected at the input of the gearhead

Ratio	Units*	RX60 / RX23	RS90 / RX34	RS115 / RX42
5	kg-cm ²	0.2200	0.8100	2.5000
5	in-lb-sec ²	0.000195	0.000717	0.002213
10	kg-cm ²	0.1900	0.6100	1.9000
10	in-lb-sec ²	0.000168	0.000540	0.001682
15	kg-cm ²	0.1800	0.6000	1.7000
15	in-lb-sec ²	0.150000	0.000531	0.001505
20	kg-cm ²	0.1700	0.5100	1.4000
20	in-lb-sec ²	0.000150	0.000451	0.001239
25	kg-cm ²	0.1600	0.4200	1.3000
20	in-lb-sec ²	0.000142	0.000372	0.001151
30	kg-cm ²	0.1800	0.6000	1.7000
30	in-lb-sec ²	0.000159	0.000531	0.001505
40	kg-cm ²	0.1700	0.5100	1.4000
40	in-lb-sec ²	0.000150	0.000451	0.001239
50	kg-cm ²	0.1500	0.4000	1.1000
50	in-lb-sec ²	0.000133	0.000354	0.000974
100	kg-cm ²	0.1500	0.4000	1.1000
100	in-lb-sec ²	0.000133	0.000354	0.000974

^{*} Note: 1 kg-cm² = 0.000885 in-lb-sec²

Generation II Stealth® How to Order

Choose gearhead series, frame size, ratio, backlash and specify motor, make and model for mounting kit from the charts below and on the following page.

Sizing/Selection Design Assistance

To properly size and select a gearhead for a specific application requires consideration of several interrelated parameters including: speed, continuous torque, repetitive peak torque or acceleration torque, emergency stop torque, duty cycle, ambient temperature and radial and axial shaft load.

The 9 step procedure on pages 60-61 provides a straightforward method of selecting the correct gearhead for your application.

Gearhead Ordering Information

		1 2	3	4	5 6	
Ord	ler Example:	PS 60	- 003	- XXX	- S 2	
1	2	3		4	5	6

Series	Frame Size	Ratio	Special Options*	Backlash	GEN 2 Identifier
PS	60, 90, 115, 142	003, 004, 005, 007, 010, 015, 020, 025, 030, 040, 050, 070, 100	XXX = Factory issued		
PX	60, 90, 115, 23, 34, 42	003, 004, 005, 007, 010, 015, 020, 025, 030, 040, 050, 070, 100	XXX = Factory issued T01 = Flange Mount	S = Standard	2
RS	60, 90, 115, 142	005, 010, 015, 020, 025, 030, 040, 050, 100	XXX = Factory issued	L = Low	
RX	60, 90, 115, 23, 34, 42	005, 010, 015, 020, 025, 030, 040, 050, 100	XXX = Factory issued (Contact factory for Flange Mount Option)		

^{*} Standard special options include: F01 Food Grade, W01 Washdown, G01 Genl Spacer Plate, L02 No lubricant (standard is oil filled), V01 Vacuum, C01 CleanRoom Class 10,000. Leave blank if no special option required.

Motor Mounting How to Order

Know your motor and need our mounting kit part number? Use the charts below or use our Motor Mounting Search Tool on our website at:

www.parkermotion.com

	①	8
Order Example:	MU 60	- XXX
	①	8
Universal Mounting*	Frame Size **	Mounting Kit Suffix Number
MU	60, 90, 115	See Motor Mounting Selection Tool on our website at:

Universal Mounting Kit Adapter Length "AD" Dimension

	Motor Sha	aft Length	Gearhead Adapter Length				
Frame Size	mm	in	mm	in			
60	16 – 35	0.630 - 1.378	16.5	0.65			
	35.1 – 41	1.382 - 1.614	22.5	0.886			
90	20 - 40	0.787 – 1.575	20	0.787			
	40.1 - 48	1.579 – 1.890	28.5	1.122			
115	22 - 50	0.866 - 1.969	24	0.945			
	50.1 - 61	1.972 - 2.402	35	1.378			
142	26 - 62	1.023 – 2.44	30	1.181			
	46 - 82	1.811 – 3.23	50	1.969			

Recommended Parker Motor and Mounting Kit

	Recon	nmended Servo	Motor	Recommended Stepper Motor					
Frame Size	Motor	Mounting Kit	AD Dimension	Motor	Mounting Kit	AD Dimension			
60 or 23	BE23 SM23	MU60-033	16.5 mm	LV23 HV23	MU60-005	16.5 mm			
90 or 34	MPP092 BE34	MU90-092 MU90-005	20 mm	LV34 HV34	MU90-005	20 mm			
115 or 42	MPP100 MPP115	MU-115-039 MU115-010	24 mm						
142	MPP115 MPP142	MU142-010 Mu142-146	30 mm						

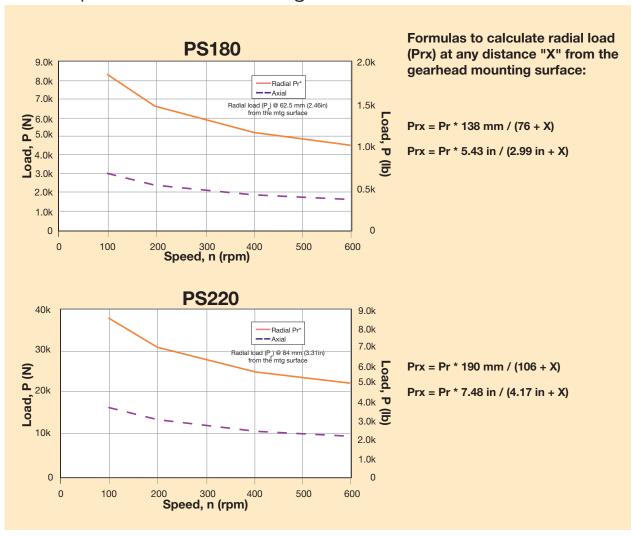
^{*} Common to PS, PX, RS and RX Series Gearheads **PX/RX23 use MU60, PX/RX34 use MU90, PX/RX42 use MU115

PS Performance Specifications

Parameter	Units	Ratio	PS180	PS220		
		3,4,5,7,10	735 (6500)	1413 (12,500)		
Nominal Output Torque T _{nom r}	Nm (in-lb)	15,20,25, 30,40,50	1017 (9000)	1808 (16,000)		
		70,100	893 (7900)	1582 (14,000)		
Maximum Acceleration Output Torque 1)	Nm (in-lb)	3,4,5,7,10 70,100	972 (8600)	1763 (15,600)		
T _{acc r}	WIII (III-115)	15,20,25, 30,40,50	1198 (10,600)	2011 (17,800)		
Emergency Stop Output Torque ²⁾	Nm (in-lb)	3,4,5,7,10 70,100	2237 (19,800)	4068 (36,000)		
T _{em r}	Will (III-ID)	15,20,25, 30,40,50	2757 (24,400)	4520 (40,000)		
		3,4,5	1600	1200		
		7,10	2000	1500		
Nominal Input Speed N _{nom r}	RPM	15,20,25, 30,40,50	2400	1800		
		70,100	2800	2100		
Maximum Input Speed N _{max r}	RPM	3 – 100	3000	2300		
Standard Backlash ³⁾	arc-min	3 – 10	4	4		
Standard Backlash	arc-min	15 – 100	6	6		
Low Backlash 3)	arc-min	3 – 10	3	3		
2011 Buokidon	aro min	15 – 100	5	5		
Efficiency at Nominal Torque	%	3 – 10	97	97		
	, ,	15 – 100	94	94		
Noise Level at: 2000 RPM ⁴⁾ 3000 RPM ⁴⁾	db	3 – 100	66 —	68 —		
Torsional Stiffness	Nm/arc-min (in-lb/arc- min)	3 – 100	110 (973)	210 (1,858)		
Maximum Allowable Case Temperature	°C	3 – 100	-20 t	to 90		
Degree of Protection			IP	65		
Maximum Weight	kg (lbs)	3 – 10	26 (57)	49 (108)		
Waxiii Weight	ng (ibs)	15 – 100	35 (77)	71 (157)		

Parker MotionSizer sizing software available for free download at parkermotion.com.
 Maximum of 1,000 stops
 Measured at 2% of rated torque
 Measured at 1 meter

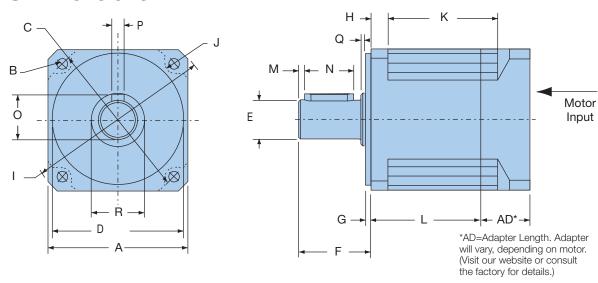
PS Output Shaft Load Rating



^{*} Radial load applied to center of the shaft.

PS Dimensions

Free 3D Solid Models and drawings available at parkermotion.com



Metric Frame Sizes

	1	A	ı	В	(0	ı)	ı	E	ı	F	(G	ı	Н		I		J
		ıare		olt	_	olt		lot	Sh	tput aft	Sh	tput aft		lot		nge		using		using
Frame	Fla	nge	Н	ole	Cir	cle	Dian	neter	Dian	neter	Ler	ngth	Inici	kness	Inici	kness	Diai	meter	Re	cess
Size	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in
PS180	182	7.165	13	0.512	215	8.465	160	6.299	55	2.165	105	4.134	20	0.787	16	0.630	240	9.449	16	0.630
PS220	220	8.661	17	0.669	250	9.843	180	7.087	75	2.953	138	5.433	30	1.181	22	0.866	290	11.417	16	0.630

	- 1	K 1	K	(2	L	.1	L	.2	r	V I	- 1	N	()	- 1	Р		Q	- 1	R
	Re	cess	Rec	ess																
	Le	ngth	Leng	th (for	Len	igth	Lengt	th (for	Dist	ance										
	(for	ratios	ratio	s 15-	(for r	atios	ratio	s 15-	from	Shaft	Key	way			Key	way	Sho	ulder	Sho	ulder
Fran	ne 3	·10)	10	00)	3-	10)	10	00)	E	nd	Ler	ngth	Key F	leight	Wi	dth	He	ight	Diar	neter
Fran Size		,	10 mm	-,	3-	.,	10 mm	.,	mm			ngth in	-	_	Wi mm		He mm	J .	Diar mm	
	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	J .	mm	in

PS InertiaAll moment of inertia values are as reflected at the input of the gearhead

			Frame	e Size
	Ratio	Units	PS180	PS220
	3 to 100	mm	15.9-35	24-48
	3 to 100	in	0.626-1.378	0.945-1.89
	3	gm-cm-sec ²	28.6	_
	3	oz-in-sec ²	0.397	_
	4, 5	gm-cm-sec ²	17.6	62.6
	4, 5	oz-in-sec ²	0.244	0.869
Small Motor Shaft	7, 10	gm-cm-sec ²	9.24	34.3
Diameter Range	7, 10	oz-in-sec ²	0.128	0.476
	15	gm-cm-sec ²	15.8	51.0
	15	oz-in-sec ²	0.219	0.708
	20, 25	gm-cm-sec ²	16.7	53.3
	20, 25	oz-in-sec ²	0.232	0.741
	00 40 50 70 400	gm-cm-sec ²	7.450	27.1
	30, 40, 50, 70, 100	oz-in-sec²	0.104	0.377

			Frame	e Size
	Ratio	Units	PS180	PS220
	3 to 100	mm	35-42	48-55
	3 10 100	in	1.38-1.65	1.89-2.17
	3	gm-cm-sec ²	37.8	111
	3	oz-in-sec ²	0.526	1.54
	4, 5	gm-cm-sec ²	25.6	72.4
	4, 5	oz-in-sec ²	0.356	1.01
Large Motor Shaft	7, 10	gm-cm-sec ²	15.8	44.1
Diameter Range	7, 10	oz-in-sec ²	0.219	0.613
	15	gm-cm-sec ²	23.8	60.8
	15	oz-in-sec ²	0.331	0.845
	20, 25	gm-cm-sec ²	24.7	62.9
	20, 23	oz-in-sec ²	0.344	0.874
	00 40 50 70 400	gm-cm-sec ²	14.0	37.0
	30, 40, 50, 70, 100	oz-in-sec ²	0.195	0.513

RS Performance Specifications

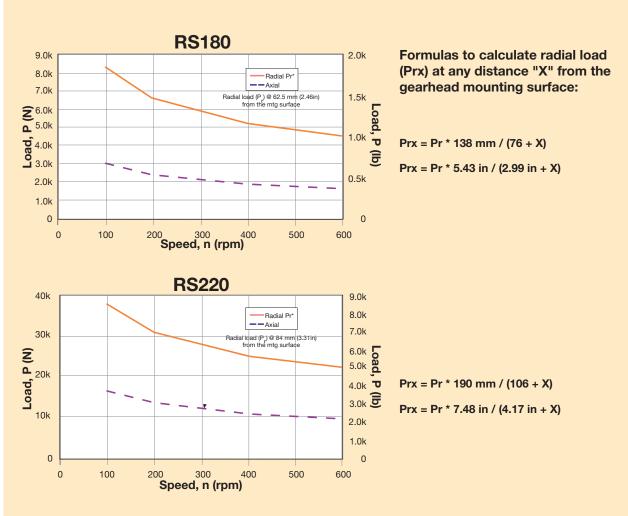
Parameter	Units	Ratio	RS180	RS220
		5	316 (2800)	678 (6000)
Nominal Output Torque T _{nom r}	Nm (in-lb)	10	621 (5500)	1299 (11,500)
Nominal Output Torque Tnom r	14111 (111-10)	15,20,25	938 (8300)	1808 (16,000)
		30,40,50,100	836 (7400)	1469 (13,000)
		5	373 (3300)	902 (7,100)
Maximum Acceleration Output	Nm (in-lb)	10	734 (6500)	1582 (14,000)
Torque ¹⁾ T _{acc r}		15,20,25, 30,40,50,100	1096 (9700)	2000 (17,700)
		5	870 (7700)	1853 (16,400)
Emergency Stop Output Torque 2)	Nm (in-lb)	10	1695 (15,000)	3684 (32,600)
T _{em r}	TVIII (III ID)	15,20,25, 30,40,50,100	2520 (22,300)	4588 (40,600)
		5,10	1600	1200
Nominal Input Speed N _{nom r}	RPM	5,20, 25,30,40	2000	1500
		50,100	2400	1800
Maximum Input Speed N _{max r}	RPM	5 – 100	3000	2300
Standard Backlash 3)	arc-min	5 – 10	10	10
Otaliaara Baokiaon	aro min	15 – 100	8	8
Low Backlash 3)	arc-min	5 – 10	6	6
		15 – 100	4	4
Efficiency at Nominal Torque	%	5 – 100	94	94
Noise Level at: 1500 RPM ⁴⁾ 2000 RPM ⁴⁾ 3000 RPM ⁴⁾	db	5 – 100	– 72 –	– – 72
Torsional Stiffness	Nm/arc-min (in-lb/arc-min)	5 – 100	90 (800)	170 (1,500)
Maximum Allowable Case Temperature	° C	5 – 100	-20 t	to 90
Degree of Protection			IP	
Maximum Weight 1) Portor Metion Sizer sizing anotheror quallable for	kg (lbs)	5 – 100	43 (94)	80 (177)

¹⁾ Parker MotionSizer sizing software available for free download at parkermotion.com.

²⁾ Maximum of 1,000 stops

³⁾ Measured at 2% of rated torque 4) Measured at 1 meter.

RS Output Shaft Load Rating



^{*} Radial load applied to center of the shaft.

RS Inertia

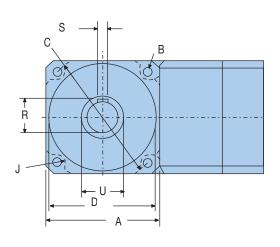
All moment of inertia values are as reflected at the input of the gearhead

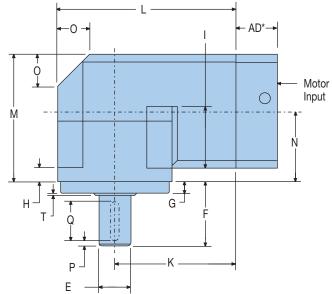
		Frame	e Size
Ratio	Units	RS180	RS220
5	gm-cm-sec ²	26.5	82.2
3	oz-in-sec ²	0.368	1.14
10	gm-cm-sec ²	16.7	50.4
10	oz-in-sec ²	0.232	0.700
45 20	gm-cm-sec ²	15.2	47.4
15, 30	oz-in-sec ²	0.211	0.658
20, 25, 40	gm-cm-sec ²	10.7	34.3
20, 25, 40	oz-in-sec ²	0.149	0.476
50, 100	gm-cm-sec ²	6.70	21.2
50, 100	oz-in-sec ²	0.093	0.294

RS Dimensions

Free 3D Solid Models and drawings available at parkermotion.com

*AD=Adapter Length. Adapter will vary, depending on motor. (Visit our website or consult the factory for details.)





Metric Frame Sizes

	Α		В		С		D		E		F		G	
	Square		Bolt		Bolt		Pilot		Output Shaft		Output Shaft		Pilot	
Frame	Fla	nge	He	ole	Cir	cle	Dian	neter	Dian	neter	Ler	igth	Thick	cness
Size	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in
RS180	182	7.165	13	0.512	215	8.465	160	6.299	55	2.165	105	4.134	20	0.787
RS220	220	8.661	17	0.669	250	9.843	180	7.087	75	2.953	138	5.433	30	1.181

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							Distance						Dista	nce to
	Fla	nge	Rec	cess	Hou	sing	to O	utput	Hou	sing	Hou	sing	Inp	out
Frame	Thick	cness	Ler	ngth	Rec	ess	Cent	erline	Ler	ngth	Wi	dth	Cent	erline
Size	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in
RS180	16	0.630	97.5	3.839	16	0.630	172	6.772	263	10.354	197	7.756	106	4.173
RS220	22	0.866	101	3.976	16	0.630	230	9.055	340	13.386	245	9.646	135	5.315

	0		Р		Q		R		S		T		U	
Taper Frame Distance			Distance from Shaft End		Keyway Length		Key Height		Keyway Width		Shoulder Height		Shoulder Diameter	
Size	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in
RS180	55	2.165	6	0.236	70	2.756	59	2.323	16	0.630	3	0.118	70	2.756
RS220	60	2.362	6	0.236	90	3.543	79.5	3.130	20	0.787	3	0.118	95	3.740

Stealth® How to Order

Choose gearhead series, frame size, ratio, backlash and orientation from the chart below.

Gearhead Ordering Information

		① ②	3	4 5
Or	der Example:	PS 180 -	- 003 - XX	X - S H
1	2	3	4	(5)
Series	Frame Size	Ratio	Backlash	Orientation
PS	180 (Metric) 220 (Metric)	003, 004, 005, 007, 010, 015, 020, 025, 030, 040, 050, 070, 100	S = Standard L = Low	See illustrations below H = Horizontal orientation U = Output shaft pointing up D = Output shaft pointing down
RS	180 (Metric) 220 (Metric)	005, 010, 015, 020, 025, 030, 040, 050,100	S = Standard L = Low	See illustrations below H = Horizontal orientation U = Output shaft pointing up D = Output shaft pointing down E = Motor input facing up F = Motor input facing down

Recommended Parker Motor and Mounting Kit

F	Rec	ommended Ser	vo Motor
Frame Size	Motor	Mounting Kit	AD Dimension
PS180	MPP142	MT180-131	67.5 mm
	MPP180	MT180-096	109 mm
PS220	MPP180	MT220-021	104 mm
	MPP230	MT220-022	138 mm
RS180	MPP142	MZ180-025	80 mm
	MPP190	MZ180-032	120 mm
RS220	MPP190	MZ220-009	108 mm
	MPP230	Consult Factory	—

Sizing/Selection Design Assistance

To properly size and select a gearhead for a specific application requires consideration of several interrelated parameters including: speed, continuous torque, repetitive peak torque or acceleration torque, emergency stop torque, duty cycle, ambient temperature and radial and axial shaft load.

The 9 step procedure on pages 60-61 provides a straightforward method of selecting the correct gearhead for your application.

