



aerospace climate control electromechanical filtration fluid & gas handling hydraulics pneumatics process control sealing & shielding





## Parker Economic Servo Package P series









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#### **Powerful servo solution**

#### Main features

- Auto configuration (BiSS-C base)
- Multiple feedback interface
   Serial(BiSS-C, EnDAT2.2, Tamagawa), Quadrature, SinCos
- User-friendly drive software
  - Step by step easy configuration
  - Pre-defined profile function
  - Auto tuning (real-time)
  - Various homing mode
  - Jog mode & Point to Point movement
  - 4 channel oscilloscope
  - Easy firmware update
- Programmable I/O
  - 1ms update rate
  - 16 channel digital input, 8 channel digital output
  - 2 channel analog input/output
- Various compatibility and application
  - ETH, ETT, OSPE
  - Rotary, Linear, DD servo motors and more

# EnDat 2.2

## In-Position Technologies



#### **Pre-defined profile function**

In-Postion Technologies

#### • Available 64 profiles

Start Index	0	•			
Stop Deceleration	100000	UU/s^2			
Current Index	0				
Feedback Speed	0	rpm or mm/s			
Position Actual Value	110919	UU			
ON ON	- ON - O	ON 📰 ON			
SVON POT	NOT HOM	IE STOP			
ON ON	- ON - C	ON 💼 ON			
PCON GAIN2	PCL NCL	EMG			
ON ON	ON 00	ON 💼 ON			
A-RST START	PAUSE REG	T HSTART			
ON ON	- ON - O	ON 💼 ON			
ISELO ISEL1	ISEL2 ISEL	3 ISEL4			
ON ON	- ON - O	ON 📰 ON			
ISEL5 ABSRQ	JSTART JDIF	PCLR			
ON ON	- ON - O	ON 💼 ON			
AOVR Reserved	Reserved Reserv	ed Reserved			
► START	STOP	PAUSE			
💡 Drive Enable	🖓 Driv	Drive Disable			

#### • Variable profile mode

#### - Absolute/Relative move





#### - Blending Absolute/Relative move





#### - Registration Absolute/Relative move



#### - Rotary Absolute/Relative/Shortest move



#### • Loop method

- Go to Next Index
- Wait for Start
- Stop



- I/O control
  - Start, Stop, REG, EOS
  - I/O0~5(Index number selecting & monitoring)

### In-Position Technologies

#### • Multi-drop connection

- RS422 serial communication interface for tasking ,test driving, gain turning, parameter setting and pre-defined position mode.
- This interface can be used for bus interface by using the multi-drop. (Max 32 axes)



• The maximum packet size of MODBUS-RTU is 256 Byte

	Ite	em	Specification			
	Communi	cation rule	ANSI/TIA/EIA-422 Standard			
	Communica	tion protocol	MODBUS-RTU			
		Data bit	8 bit			
	Data Type	Stop bit	1 bit			
		Parity	None			
	Syncrono	us method	Asynchronous			
	Baud rate		9600/19200/38400/57600/115200 bit for second			
Available distance			Max. 200m			
	Current co	onsumption	Under 100mA			

#### **Servo Drive**

#### **Technical Data**

## In-Position Technologies

www.iptech1.com | (877) 478-3241 | help@iptech1.com

Moto	r Output Power	PD-01	PD-02	PD-04	PD-08		
	Shaft Power @ Continuous Current	100 Watts	200 Watts	400 Watts	800 Watts		
	Shaft Power @ Peak Current	300 Watts	600 Watts	1,200 Watts	2,400 Watts		
Drive	Output Power						
	Continuous Current (RMS)	1.4 Amps	1.7 Amps	3.0 Amps	5.2 Amps		
	Peak Current (RMS)	4.2 Amps	5.1 Amps	9.0 Amps	15.6 Amps		
	Bus Voltage	340VDC					
Drive	Input Voltage		230 VAC, 3	Ø, 50/60Hz			
Drive	Control Voltage		230 VAC, 1	Ø, 50/60Hz			
			,	,			
Moto	r Output Power	PD-10	PD-20	PD-35			
	Shaft Power @ Continuous Current	1.000 Watts	2.000 Watts	3.500 Watts			
	Shaft Power @ Peak Current	3.000 Watts	6.000 Watts	10.500 Watts			
Drive	Output Power	-,	-,				
2	Continuous Current (BMS)	6 75 Amps	13.5 Amps	16 7 Amps			
	Peak Current (RMS)	20.25 Amps	10.5 Amps	50 1 Amps			
	Rue Voltage	20.20 Amp3	340.0 Amps	Vdc			
Drivo	Input Voltage		230 V/AC 3				
Drive			200 VAC, 0	0,50/00112			
Dive	Control voltage		230 VAC, 1	Ø, 30/00HZ			
Deufe							
Perio			CO 5		1		
	Servo update		62.5µ s	econas			
	Accuracy	± 1 encoder count ; encoder dependent					
	Communication		Sinus	soidal			
Input							
	Command	Step a	nd direction, CW a	nd CCW (Position of	control)		
	Enable / Reset		12-24	4VDC			
	Encoder	Quadrature	Incremental encod	ler, BiSS-C (absolu	te) encoder,		
			EnDAT 2.	2, SinCos			
Outp	ut						
	Fault		24VDC,	, 120mA			
	Brake	Solid	state, normally op	en, 1Amp @ 24VD0	) max		
	Encoder Out		RS-422 compatibl	e differential driver			
I/O							
	Digital input	-	16-channel, +24V c	common, selectable	Э		
	Digital output	8-0	channel, Differentia	l (Isolated), selecta	ble		
	Analog input		2-channel, ±10	V (max.), 12bits			
	Analog output	2-	channel, ±10V (ma	x.), selectable, 12b	oits		
Com	munications						
	Tura	USB 2.	0 for firmware uplo	ad and drive config	guration		
	Туре		RS422 for ope	ration interface			
	Standard	ANSI/ TIA/ EIA-422 standard					
	Baud Rate	9,6	00/ 19,200/ 38,400	/ 57,600/ 115,200	bps		
Stand	dards		CE, F	RoHS			
Envir	onmental						
	Temperature		0 - 50 °C(	32 - 122 °F )			
	Humidity		0 - 90% non	-condensina			
	Shock / Vibration	15	5g, 11msec half sic	n / 10-2,000Hz @ 2	2q		
			0,	, ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	0		

Parker Economic Servo Package Servo Drive

## In-Postion Technologies

**Dimensions** 



(Unit: mm)

		PD-01 ~ 04	PD-08 / 10	PD-20 / 35
н	Height	158	158	158
ОН	Overall Height	169	169	169
OW	Overall Width	38	58	88
W1	Width 1	6	10	44
W2	Width 2	26	48	44
W3	Width 3	32	42	78
W4	Width 4	6	6	5
D	Depth	107.7	127.7	112.5
OD	Overall Depth	173	197	198

Note)

- This is for your reference only. For exact dimension, please refer to the drawing file available from http://solutions.parker.com/AUG\_EM.

#### Servo Motor (FAL Series Motor)

#### **Technical Data**

Motor	Output Power		PM-FALR5AMxx	PM-FAL01AMxx	PM-FAL015AMxx			
	Rated Output Power		50 Watts	100 Watts	150 Watts			
Motor	Output Torque							
	Potod Torquo	N-m	0.16	0.32	0.48			
	naleu lorque	kgf-cm	1.62	3.25	4.87			
	Instantaneous Peak	N-m	0.48	0.96	1.43			
	Torque	kgf-cm	4.87	9.74	14.62			
Motor	Speed							
	Rated Speed		3000 rpm					
	Peak Speed			5000 rpm				
Mama	at of Inortia	kg-m² x 10-4	0.02	0.05	0.06			
wome	nt or menta	gf-cm-s <sup>2</sup>	0.02	0.05	0.07			
Availat	ble Moment of Load Inertia		Motor Inc	ertia x 30	x 20			
Positio	n Feedback		BiSS-C Interface – 18bit					
Weight			0.4kg	0.5kg	0.7kg			

Standards

CE

Environmental		
	Temperature	0 - 40 °C
	Humidity	20-80% non-condensing
	Shock / Vibration	5G (49m/s²)







In-Position Technologies

#### Dimensions



(Unit: mm)

	OW	ОН	OL	L	Ν	W	D	F	М	S	т
PM-FALR5AMN			103.2	78.2	78.2		23				
PM-FAL01AMN			120.2	95.2					35	25	
PM-FAL015AMN	40	60	140.2	115.2	20	20.5	0	Б	35		2.5
PM-FALR5AM2	40	60	139.6	114.6	30	32.5	0	5	23		
PM-FAL01AM2			156.6	131.6					35		
PM-FAL015AM2			176.6	151.6					35		

Note)

- FAL series are no-key type, Detail drawings and N-T curves are available at http://solutions.parker.com/AUG\_EM



#### Servo Motor (FBL Series Motor)

#### **Technical Data**

Motor	Output Power		PM-FBL01AMxx	PM-FBL02AMxx	PM-FBL04AMxx			
	Rated Output Power		100 Watts	200 Watts	400 Watts			
Motor	Output Torque							
	Potod Torquo	N-m	0.32	0.64	1.27			
	nateu lorque	kgf-cm	3.25	6.50	12.99			
	Instantaneous Peak	N-m	0.96	1.91	3.82			
	Torque	kgf-cm	9.74	19.49	38.98			
Motor	Speed							
	Rated Speed		3000 rpm					
	Peak Speed			5000 rpm				
Momo	at of Inortia	kg-m² x 10-4	0.09	0.15	0.25			
WOME	ni or mertia	gf-cm-s <sup>2</sup>	0.09	0.15	0.25			
Availat	ble Moment of Load Inertia		Motor Inertia x 20					
Positio	n Feedback		BiSS-C Interface – 19bit					
Weight			0.7kg	0.9kg	1.3kg			

Standards

CE

Environmental							
	Temperature	0 - 40 °C					
	Humidity	20-80% non-condensing					
	Shock / Vibration	5G (49m/s²)					







In-Postion Technologies

#### Dimensions



														`	,
	OW	ОН	OL	L	Ν	W	D	F	S	т	KW	KH	KD	KL	Р
PM-FBL01AMN			107.2	77.2											
PM-FBL02AMN			118.2	88.2											
PM-FBL04AMN	60	00	138.2	108.2	50	40 E	14	G	20	0	F	0	F	00 F	00
PM-FBL01AMK2	02	80	147.2	117.2	50	49.5	14	0	30	3	5	3	5	22.5	80
PM-FBL02AMK2			158.2	128.2											
PM-FBL04AMK			178.2	148.2											

Note)

- Detail drawings and N-T curves are available at http://solutions.parker.com/AUG\_EM



## Parker Economic Servo Package Technical data Servo Motor (FCL Series Motor) In-Position Technologies

www.iptech1.com | (877) 478-3241 | help@iptech1.com

#### **Technical Data**

Motor	Output Power		PM-FCL04AMxx	PM-FCL06AMxx	PM-FCL08AMxx	PM-FCL10AMxx	
	Rated Output Power		400 Watts	600 Watts	750 Watts	1000 Watts	
Motor	Output Torque						
	Potod Torquo	N-m	1.27	1.91	2.39	3.18	
	naleu lorque	kgf-cm	13	19.5	24.36	32.5	
	Instantaneous Peak	N-m	3.82	5.73	7.16	9.55	
	Torque	kgf-cm	38.98	58.47	73.08	97.44	
Motor	Speed						
	Rated Speed		3000 rpm				
	Peak Speed			5000	) rpm		
Momo	nt of Inortia	kg-m <sup>2</sup> x 10-4	0.5	0.88	1.25	1.62	
wome	ni or mertia	gf-cm-s <sup>2</sup>	0.51	0.89	1.27	1.65	
Availat	ole Moment of Load Ine	ertia		Motor Ine	ertia x 15		
Positic	n Feedback			BiSS-C Inter	rface – 19bit		
Weight	t		1.6kg	2.2kg	2.7kg	3.8kg	

Standards

CE

Environmental						
	Temperature	0 - 40 °C				
	Humidity	20-80% non-condensing				
	Shock / Vibration		5G (49	9m/s²)		









Parker Economic Servo Package Servo Motor



#### **Dimensions**



	OW	ОН	OL	L	Ν	W	D	F	S	Т	KW	KH	KD	KL	Р	
PM-FCL03DMK PM-FCL04AMK	80 98		138.7	98.7			14				5	3	5			
PM-FCL05DMK PM-FCL06AMK			156.7	116.7												
PM-FCL06DMK PM-FCL08AMK		80 98		174.7	134.7	70	63.6	19	10	40		6	3.5	6	25	105
PM-FCL07DMK PM-FCL10AMK			08	192.7	152.7						2					
PM-FCL03AMK2 PM-FCL04AMK2			90	179	139			14			Ę	5	3	5	20	105
PM-FCL05DMK2 PM-FCL06AMK2				197	157			19				6	3.5	6		
PM-FCL06DMK2 PM-FCL08AMK2				215	175											
PM-FCL07DMK2 PM-FCL10AMK2				233	193											

(Unit: mm)

#### Note)

- Detail drawings and N-T curves are available at http://solutions.parker.com/AUG\_EM

## Parker Economic Servo Package Technical data Servo Motor (FE Series Motor) In-Postion Technologies

#### **Technical Data**

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Motor	Output Power		PM-FE09AMxx	PM-FE15AMxx	PM-FE22AMxx	PM-FE30AMxx						
	Rated Output Power		900 Watts	1500 Watts	1500 Watts 2200 Watts							
Motor	Output Torque											
	Potod Torquo	N-m	2.86	4.77	7	9.55						
	naleu lorque	kgf-cm	29.2	48.7	71.4	97.4						
	Instantaneous Peak	N-m	8.59	14.32	21.01	28.65						
	Torque	kgf-cm	87.7	146.1	214.3	292.2						
Motor	Speed											
	Rated Speed		3000 rpm									
	Peak Speed		5000 rpm									
Momo	nt of Inortia	kg-m <sup>2</sup> x 10-4	5.66	10.18	14.62	19.04						
wome	ni or merila	gf-cm-s <sup>2</sup>	5.77	5.77 10.39 14.92		19.43						
Availat	ole Moment of Load Ine	rtia	Motor Inertia x 10									
Positio	n Feedback		BiSS-C Interface – 19bit									
Weight	t		5.0kg	6.7kg	8.5kg	10.1kg						

Standards

CE

Environmental	
Temperature	0 - 40 °C
Humidity	20-80% non-condensing
Shock / Vibration	5G (49m/s²)









Parker Economic Servo Package Servo Motor

## In-Position Technologies

#### Dimensions



(Unit: mm)

	WO	OH	OL	L	Ν	W	D	F	S	Т	KW	KH	KD	KL	Р
PM-FE03MMK PM-FE05GMK PM-FE06DMK PM-FE09AMK			197.3	139.3		102.5	10				5	2	5		
PM-FE06MMK PM-FE09GMK PM-FE11DMK PM-FE15AMK			217.3	159.3			10				5	3	5		
PM-FE09MMK PM-FE13GMK PM-FE16DMK PM-FE22AMK			237.3	179.3			22				6	3.5	6	05	105
PM-FE12MMK PM-FE17GMK PM-FE22DMK PM-FE30AMK	130	231.7	255.3	197.3	197.3 110 177.3		24	10	50	c	8	4	7		
PM-FE03MMK2 PM-FE05GMK2 PM-FE06DMK2 PM-FE09AMK2			235.3	177.3			19	19	58	U	F	0	F	25	105
PM-FE06MMK2 PM-FE09GMK2 PM-FE11DMK2 PM-FE15AMK2			255.3	197.3							5	3	5		
PM-FE09MMK2 PM-FE13GMK2 PM-FE16DMK2 PM-FE22AMK2			275.3	217.3			22				6	3.5	6		
PM-FE12MMK2 PM-FE17GMK2 PM-FE22DMK2 PM-FE30AMK2			293.3	235.3			24				8	4	7		

Note)

- Detail drawings and N-T curves are available at http://solutions.parker.com/AUG\_EM

#### **Servo Motor (FF Series Motor)**

#### **Technical Data**

Motor	Output Power		PM-FF30AMxx	PM-FF35DMxx				
	Rated Output Power		3000 Watts	3500 Watts				
Motor Output Torque								
	Pated Torque	N-m	9.55	16.70				
	naleu lorque	kgf-cm	97.4	170.4				
	Instantaneous Peak	N-m	28.65	50.10				
	Torque	kgf-cm	292.3	511.40				
Motor Speed								
	Rated Speed		3000 rpm	2000 rpm				
	Peak Speed		5000 rpm	3000 rpm				
kg-m <sup>2</sup> x 10-4		27.96	46.56					
wome	ni or menta	gf-cm-s <sup>2</sup>	28.53	47.51				
Availat	ble Moment of Load Ine	rtia	Motor Inertia x 5					
Positio	n Feedback		BiSS-C Inter	face – 19bit				
Weight	:		12.5kg	17.4kg				

Standards

CE

Environmental								
	Temperature	0 - 40 °C						
	Humidity	20-80% non-condensing						
	Shock / Vibration	5G (49m/s²)						





In-Position Technologies

Parker Economic Servo Package Servo Motor

#### In-Position Technologies www.iptech1.com | (877) 478-3241 | help@iptech1.com

#### **Dimensions**



	OW	OH	OL	L	N	W	D	F	S	Т	KW	KH	KD	KL	Р
PM-FF12MMK PM-FF20GMK PM-FF22DMK PM-FF30AMK			257.5	178.5		141.4	35	17	79	3	10				230
PM-FF20MMK PM-FF30GMK PM-FF35DMK			287.5	208.5								5		60	
PM-FF30MMK	100	2977	331.5	252.5	11/2								Q		
PM-FF12MMK2 PM-FF20GMK2 PM-FF22DMK2 PM-FF30AMK2	180	201.1	308.9	229.9	9							5			
PM-FF20MMK2 PM-FF30GMK2 PM-FF35DMK2			338.9	259.9											
PM-FF30MMK2			382.9	303.9											

(Unit: mm)

Note)

- Detail drawings and N-T curves are available at http://solutions.parker.com/AUG\_EM

Parker Economic Servo Package Technical data

#### **Ordering Code**

## In-Position Technologies

#### Motor



Drive



#### Cable



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- 4. Warranty. Seller warrants that the Products sold hereunder shall be free from defects in material or workmanship for a period of twelve months from the date of delivery to Buyer or 2,000 hours of normal use, whichever occurs first. The prices charged for Seller's products are based upon the exclusive limited warranty stated above, and upon the following disclaimer: <u>DISCLAIMER OF WARRANTY</u>: <u>THIS WARRANTY</u> COMPRISES THE SOLE AND ENTIRE WARRANTY PERTAINING TO PRODUCTS PROVIDED HEREUNDER. SELLER DISCLAIMS ALL OTHER WARRANTIES, EXPRESS AND IMPLIED, INCLUDING DESIGN, MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE.
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- Limitation on Assignment. Buyer may not assign its rights or obligations under this agreement without the prior written consent of Seller.
- 14. Force Majeure. Seller does not assume the risk and shall not be liable for delay or failure to perform any of Seller's obligations by reason of circumstances beyond the reasonable control of Seller (hereinafter "Events of Force Majeure"). Events of Force Majeure shall include without limitation: accidents, strikes or labor disputes, acts of any government or government agency, acts of nature, delays or failures in delivery from carriers or suppliers, shortages of materials, or any other cause beyond Seller's reasonable control.
- 15. <u>Waiver and Severability</u>. Failure to enforce any provision of this agreement will not waive that provision nor will any such failure prejudice Seller's right to enforce that provision in the future. Invalidation of any provision of this agreement by legislation or other rule of law shall not invalidate any other provision herein. The remaining provisions of this agreement will remain in full force and effect.
- 16. Termination. Seller may terminate this agreement for any reason and at any time by giving Buyer thirty (30) days written notice of termination. Seller may immediately terminate this agreement, in writing, if Buyer: (a) commits a breach of any provision of this agreement (b) appointments a trustee, receiver or custodian for all or any part of Buyer's property (c) files a petition for relief in bankruptcy on its own behalf, or by a third party (d) makes an assignment for the benefit of creditors, or (e) dissolves or liquidates all or a majority of its assets.
- 17. <u>Governing Law.</u> This agreement and the sale and delivery of all Products hereunder shall be deemed to have taken place in and shall be governed and construed in accordance with the laws of the State of Ohio, as applicable to contracts executed and wholly performed therein and without regard to conflicts of laws principles. Buyer irrevocably agrees and consents to the exclusive jurisdiction and venue of the courts of Cuyahoga County, Ohio with respect to any dispute, controversy or claim arising out of or relating to this agreement.
- 18. Indemnity for Infringement of Intellectual Property Rights. Seller shall have no liability for infringement of any patents, trademarks, copyrights, trade dress, trade secrets or similar rights except as provided in this Section. Seller will defend and indemnify Buyer against allegations of infringement of U.S. patents, U.S. trademarks, copyrights, trade dress and trade secrets ("Intellectual Property Rights"). Seller will defend at its expense and will pay the cost of any settlement or damages awarded in an action brought against Buyer based on an allegation that a Product sold pursuant to this Agreement infringes the Intellectual Property Rights of a third party. Seller's obligation to defend and indemnify Buyer is contingent on Buyer notifying Seller within ten (10) days after Buyer becomes aware of such allegations of infringement, and Seller having sole control over the defense of any allegations or actions including all negotiations for settlement or compromise. If a Product is subject to a claim that it infringes the Intellectual Property Rights of a third party, Seller may, at its sole expense and option, procure for Buyer the right to continue using the Product, replace or modify the Product so as to make it noninfringing, or offer to accept return of the Product and return the purchase price less a reasonable allowance for depreciation. Notwithstanding the foregoing, Seller shall have no liability for claims of infringement based on information provided by Buyer, or directed to Products delivered hereunder for which the designs are specified in whole or part by Buyer, or infringements resulting from the modification, combination or use in a system of any Product sold hereunder. The foregoing provisions of this Section shall constitute Seller's sole and exclusive liability and Buyer's sole and exclusive remedy for infringement of Intellectual Property Rights.
- 19. Entire Agreement. This agreement contains the entire agreement between the Buyer and Seller and constitutes the final, complete and exclusive expression of the terms of sale. All prior or contemporaneous written or oral agreements or negotiations with respect to the subject matter are herein merged.
- 20. Compliance with Law, U. K. Bribery Act and U.S. Foreign Corrupt Practices Act. Buyer agrees to comply with all applicable laws and regulations, including both those of the United Kingdom and the United States of America, and of the country or countries of the Territory in which Buyer may operate, including without limitation the U. K. Bribery Act, the U.S. Foreign Corrupt Practices Act ("FCPA") and the U.S. Anti-Kickback Act (the "Anti-Kickback Act"), and agrees to indemnify and hold harmless Seller from the consequences of any violation of such provisions by Buyer, its employees or agents. Buyer acknowledges that they are familiar with the provisions of the U. K. Bribery Act, the FCPA and the Anti-Kickback Act, and certifies that Buyer will adhere to the requirements thereof. In particular, Buyer represents and agrees that Buyer shall not make any payment or give anything of value, directly or indirectly to any governmental official, any foreign political party or official thereof, any candidate for foreign political office, or any commercial entity or person, for the purpose of influencing such person to purchase products or otherwise benefit the business of Seller.

#### Parker Asia Pacific

#### <u>China</u>

Sales Office Shanghai office, 86-21-28995000 Parker Hannifin Motion&Control Co. Ltd. 280 Yunqiao Road, Jin Qiao Export Processing Zone, Shanghai 201206, China

#### Sales Office

Guangzhou Office, 86 20 3878 1583 Parker Hannifin Motion&Control Co. Ltd. Room 1706, Goldlion Tower, No. 138, Ti Yu East Road, Guangzhou, 510620, China

#### Sales Office

Beijing office, 86-10-6561-0520 Parker Hannifin Motion&Control Co. Ltd. Suite B2109, 21st Floor, Hanwei Plaza, 7 Guanghua Road, Chaoyang District, Beijing, 100004, China

#### Automation Division

WUXI plant, 86-510-8116-7000 Parker Hannifin Motion and Control (Wuxi) Company Ltd. No.200, Furong Zhong Si Lu, Xishan Economic Development Zone, Wuxi 214101, Jiangsu, China

#### <u>Japan</u>

Sales Office Totsuka Office, 81-45-870-1510 Parker Hannifin Japan Ltd. 626 Totsuka-cho, Totsuka-ku, Yokohama-shi, Kanagawa, 244-0003 Japan

#### Automation Division

Asahi Plant, 81-479-64-2282 Kuroda Pneumatics Ltd. 10243 Kamakazu, Asahi-shi, Chiba 289-2505 Japan

#### <u>Korea</u>

Sales Office Ga San Office, 822-6344-0100 Parker Hannifin Korea Automation Office 13F Jei Platz B/D , 459-11 Gasan-dong, Geumcheongu, Seoul

#### Automation Division

Jang An Plant, 82 31-359-0700 Parker Korea Ltd. 759-10 Geumui-ri, Jangan-myeon, Hwaseong-si, Gyeonggi-do, 445-941, Korea

#### India

Sales Office

PHI Chennai Sales office, 91-44-43910799 Parker Hannifin India Private. Limited, Plot no. P41/2, Eight Avenue, Domestic Tariff Area, Mahindra world city, Chengalpattu, Kanchipuram District, Pin : 603002, Tamil Nadu, India

#### Automation Division

PHI Chennai MWC Plant, 91-44-43910703 Parker Hannifin India Private. Limited, Plot no. P41/2, Eight Avenue, Domestic Tariff Area, Mahindra world city, Chengalpattu, Kanchipuram District, Pin : 603002, Tamil Nadu, India

#### <u>Taiwan</u>

Sales Office Taipei Office, 886-2-22988987 Parker Hannifin Taiwan Co., Ltd. No.19, Wu Chiuan 2nd Road, Wuku Industrial Park, New Taipei City, Taiwan 248

#### Thailand Sales Office

Bangkok Office, 66-2-186-7000 Parker Hannifin (Thailand) Co., Ltd. 1265 Rama9 Road, Suanluang, Bangkok 10250

#### **Singapore**

Sales Office 65-6887-6300 Parker Hannifin Singapore Pte Ltd. No.11, Fourth Chin Bee Road, Singapore 619702

#### <u>Malaysia</u>

Sales Office Selangor Office, 603-7849-0800 Parker Hannifin Industrial (M) Sdn Bhd No. 11, Persiaran Pasak bumi, Seksyen U8, Bukit Jelutong Industrial Park, 40150 Shah Alam, Selangor

#### <u>Indonesia</u>

Sales Office 62-21-7588-1906 Parker Hannifin (Indonesia Rep Office) Techno Park Block G3/16 BSD (Bumi Serpong Damai) Tangerang, 15314 Indonesia

#### <u>Vietnam</u>

Sales Office 84 8 377 546 51 Parker Hannifin Vietnam Co., Ltd. 7-9 Road 65, Tan Quy Dong Residential Area, Tan Phong Ward, District 7, Ho Chi Minh City, Vietnam

#### Australia

Sales Office 61-(0)2-9634-7777 Parker Hannifin (Australia) Pty Limited 9 Carrington Road, Castle Hill, NSW 2154

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Parker Korea Ltd.

23, Jangangongdan 1-gil Jangan-myeon, Hwaseong-si Gyeonggi-do, 445-941, Korea Tel.: +82-31-359-0700 Fax: +82-31-359-0780 www.parker.com