



High-Performance Gearheads for Servomotors
Harmonic Planetary

HPN-A Right Angle Series

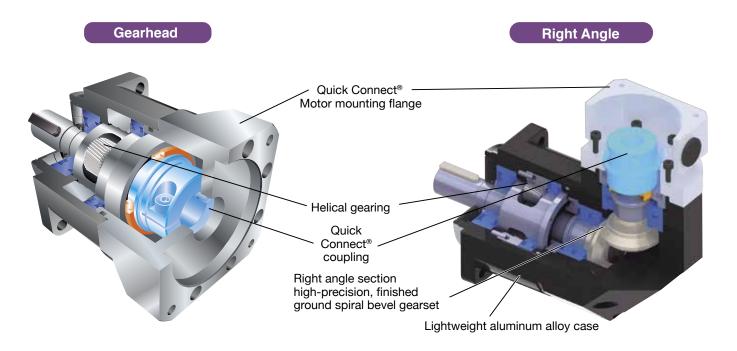




Harmonic Planetary HPN Series



HPN precision planetary gearheads are quiet, lightweight and compact with low cost and quick delivery.



HPN Planetary gearheads feature a robust design utilizing helical gears for quiet performance and long life. These gearheads are available with short lead times and are designed to couple to any servomotor with our Quick Connect® motor adaptation system. HPN gearheads are suitable for use in a wide range of applications for precision motion control and positioning. HPN Harmonic Planetary® gears are available in 5 sizes: 11, 14, 20, 32, and 40, with reduction ratios ranging from 3:1 to 50:1.

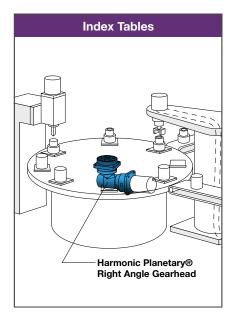
- Low Backlash:
 - Single Stage: < 6 arc minutes
 - Double Stage: < 9 arc minutes
- High Efficiency

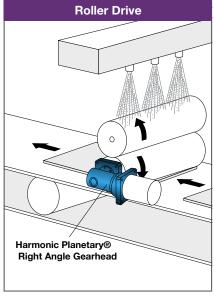
- Available Reduction Ratios: 3:1 to 50:1
- Helical Gearing
- ◆ Low Noise Design
- ◆ Smooth, High-Speed Transmission

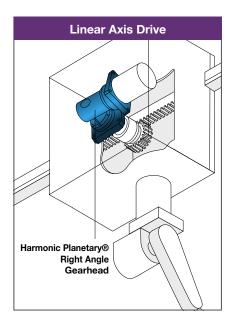
Create a high-precision actuator by connecting any manufacturer's servomotor to our precision gearhead with Quick Connect® motor adaptation design.



Application Examples







3

HarmonicPlanetary® HPN Right Angle

Size

11, 14, 20, 32, 40

5 Sizes

Peak Torque

 $9\mathrm{Nm}\sim752\mathrm{Nm}$

Reduction Ratio

Single Stage: 3:1 to 10:1 Two Stage: 15:1 to 50:1

Backlash

Single Stage: <6 arc-min Two Stage: <9 arc-min

Easy mounting to a wide variety of servomotors

Quick Connect® motor adaptation system includes a clamshell style servo coupling and piloted adapter flange.

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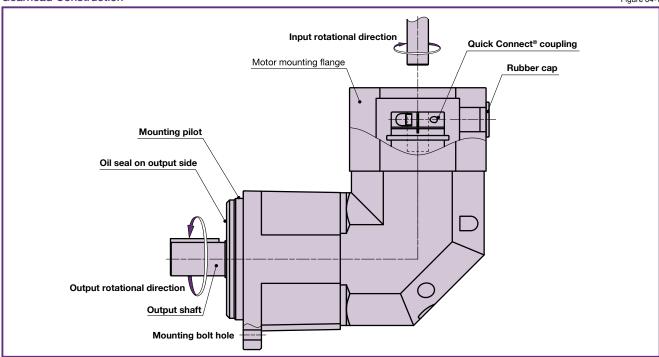
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HPN - 20 A - 15 - J6 RA2 - Motor Code

Model Name **Design Revision** Reduction Ratio **Output Shaft Configuration** Right Angle Specification Input Configuration 11 4, 5, 7, 10 RA1 This code represents the motor J6: Shaft output with key and RA1, RA2 **HPN** 14 mounting configuration. If center tapped hole 20 3, 4, 5, 7, 10, 15, 20, RA2, RA3 unknown, substitute the motor Right Angle J8: Shaft output with center 32 25, 30, 35, 40, 45, 50 RA3, RA4 model # and the motor code will HarmonicPlanetary® tapped hole be identified (or assigned). RA4, RA5

Gearhead Construction Figure 04-1



Rating Table

Please contact us if you have any questions about specifications and comparisons with other company's products.

Table 05-1

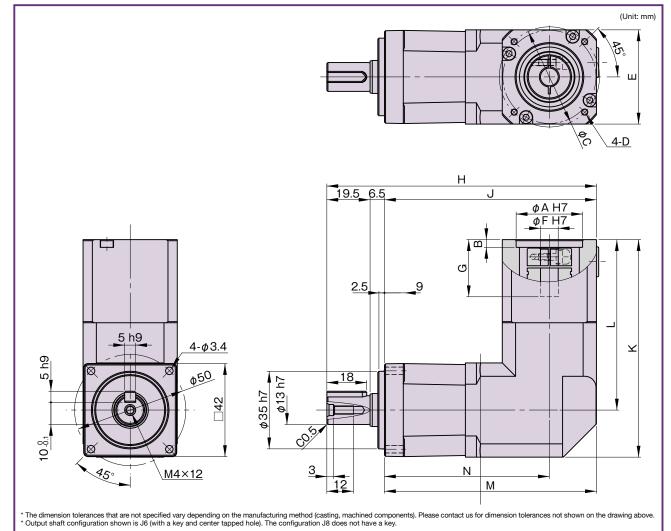
٥.	Number of	D. ::	Rated output torque *1 L10	Rated output torque *1 L50	Limit for repeated peak torque *2	Limit for momentary peak torque *3	Rated Input Speed (rpm) *4	Maximum Input Speed (rpm) *5	Backlash
Size	stages	Ratio	N·m	N·m	N·m	peak torque N⋅m	rpm	rpm	arc-min
		4	9	14	14	40	, p	, p	<9
İ		5	9	14	16	40			<8
11A	1	7	8	11	11	40	3000	10000	
		10	7	9	9	40		İ	<7
		3	14	21	21	78			
		4	18	28	28	104			
	1	5	18	29	35	107			<6
		7	20	30	37	100			
		10	14	18	18	79			
		15	21	30	43	97			
14A		20	23	30	49	100	3000	6000	
		25	26	30	38	102			
	2	30	26	40	48	98			<9
	_	35	28	40	49	99			
		40	29	30	38	100			
		45	29	30	38	100			
		50	20	26	26	94			
		3	31	45	45	147			
		4	50	60	60	196			
	1	5	52	75	75	245			<6
		7	55	80	105	256			
		10	41	54	54	216			
204		15	59	80	105	256	2000		
20A		20	66	80	140	256	3000	6000	
		25	72	80	114	256			
	2	30	72	80	139	250			<9
		35 40	79 80	80 80	112 112	256 256			
		45	80	80	112	256			
		50	58	75	75	216			
		3	84	84	84	288			
		4	112	112	112	384			
	1	5	127	139	139	480		İ	<6
	·	7	135	195	195	625			
		10	128	185	185	625			
		15	146	200	225	625		İ	
32A		20	162	200	297	625	3000	6000	
		25	176	200	371	625			
		30	179	250	376	625			
	2	35	193	250	376	625			<9
		40	200	300	376	625			
		45	206	300	376	625			
		50	193	251	251	625			
		3	186	186	186	1,137			
		4	245	245	245	1,265			
	1	5	298	310	310	1,265		5000	<6
		7	317	430	430	829			
	<u> </u>	10	302	480	509	829			
		15	342	417	417	1265			
40A		20	380	555	555	1265	3000		
		25	413	650	694	1127			
	2	30	421	650	752	1265		6000	<9
		35	452	700	752	1127			
		40	468	700	752	1127			
		45	484	700	752	1,127			
	I.	50	432	562	562	1,162			

Performance

Table 05-2

											Tubic 00 L
Size		11		14	20	32	40	14	20	32	40
Number of stages				1					2	2	
Reduction ratio	4	5	7, 10		3, 4, 5	, 7, 10		1	15, 20, 25, 30,	35, 40, 45, 5	0
Backlash arc min	<9	<8	<7		<	6			<	9	

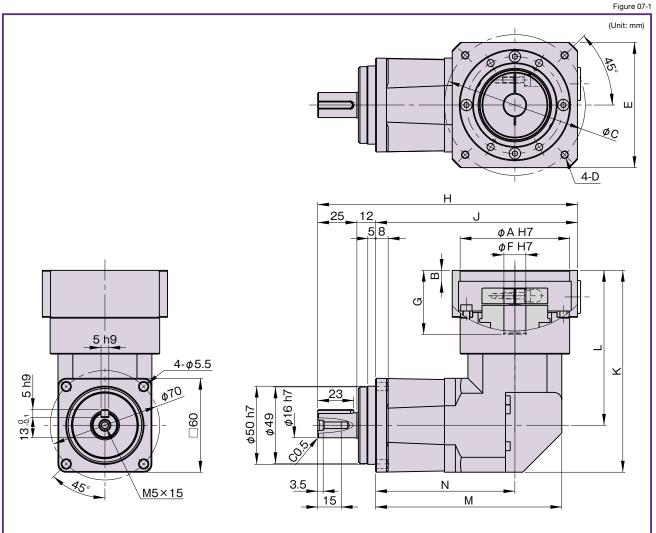
^{*1:} Rated torque is based on life of 20,000 hours at max average input speed.
*2: Limit for torque during start and stop cycles.
*3: Limit for torque during emergency stops or from external shock loads. Always operate below this value.
*4: Limit for average input speed during operation.
*5: Maximum instantaneous input speed.



Dimensions Table 06-1

-		.00	'												(Unit: mm)
	A (H7)	В	С	D	Е	Motor Sha	ft Diameter H7)	G	н	J	К	L	М	N	Mass
	,,,,,,				_	Min	Max			ŭ	, · ·	_			(kg) *2
Single Stage	Pilot Diameter ^{*1}	I	Bolt Circle Diameter ⁻¹	Bolt Hole Thread and Depth ⁻¹	Input Flange Width (square) ⁻¹	8	8	Input Coupling Bore Depth ⁻¹	Length Dimension Output Axis ^{*1}	Length Output Axis ⁻¹	Length Input Axis*1	Length Output Axis*1	95.7	74.4	0.95

^{*1:} Dimensions for Quick Connect Adaptation Designs are tailored to the customer specified motor; detailed part #, drawings, and models furnished upon request *2: The mass varies slightly depending on the reduction ratio and on the inside diameter of the input shaft coupling



^{*} The dimension tolerances that are not specified vary depending on the manufacturing method (casting, machined components). Please contact us for dimension tolerances not shown on the drawing above.

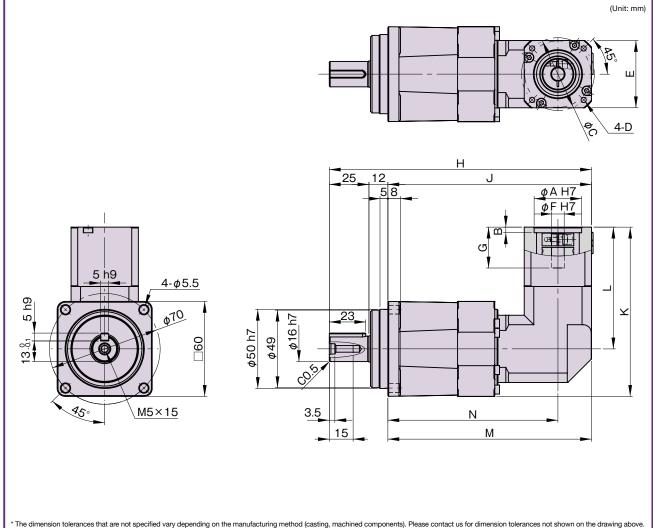
* Output shaft configuration shown is J6 (with a key and center tapped hole). The configuration J8 does not have a key.

Dimensions Table 07-1 (Unit: mm)

	A (H7)	В	С	D	Ę	Motor Sha		G	н		к		М	N	Mass
	Α (Π/)	В	U	D	Ē	F (I Min	Max	G		J	, ,	•	IVI	IN .	(kg) *2
Single Stage	Pilot Diameter*1		Bolt Circle Diameter ⁻¹	Bolt Hole Thread and Depth ⁻¹	Input Flange Width (square)*1	8	24	Input Coupling Bore Depth ^{*1}	Length Dimension Output Axis ⁻¹	Length Output Axis ⁻¹	Length Input Axis ⁻¹	Length Output Axis ⁻¹	119	89	2.1

^{*1:} Dimensions for Quick Connect Adaptation Designs are tailored to the customer specified motor; detailed part #, drawings, and models furnished upon request *2: The mass varies slightly depending on the reduction ratio and on the inside diameter of the input shaft coupling

Figure 08-1



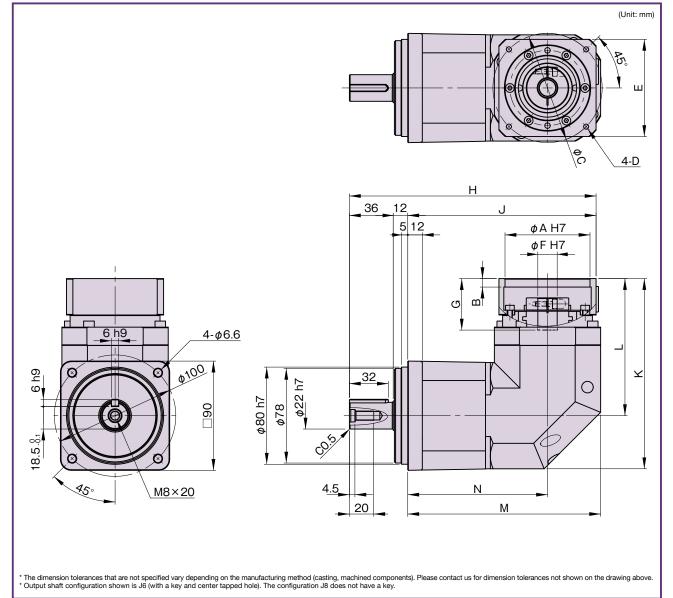
* The dimension tolerances that are not specified vary depending on the manufacturing method (casting, machined components). Please contact us for dimension tolerances not shown on the drawing above. * Output shaft configuration shown is J6 (with a key and center tapped hole). The configuration J8 does not have a key.

Table 08-1 (Unit: mm)

	A (H7)	В	С	D	E	Motor Sha		G	н	J	К	L	M	N	Mass (kg) *²
						Min	Max								(1.9)
Double Stage	Pilot Diameter*1		Bolt Circle Diameter ⁻¹	Bolt Hole Thread and Depth ⁻¹	Input Flange Width (square) ⁻¹	8	24	Input Coupling Bore Depth ^{*1}	Length Dimension Output Axis ⁻¹	Length Output Axis ⁻¹	Length Input Axis ⁻¹	Length Output Axis ^{*1}	128.7 / 142	107.4 / 112	2.3

^{*1:} Dimensions for Quick Connect Adaptation Designs are tailored to the customer specified motor; detailed part #, drawings, and models furnished upon request *2: The mass varies slightly depending on the reduction ratio and on the inside diameter of the input shaft coupling



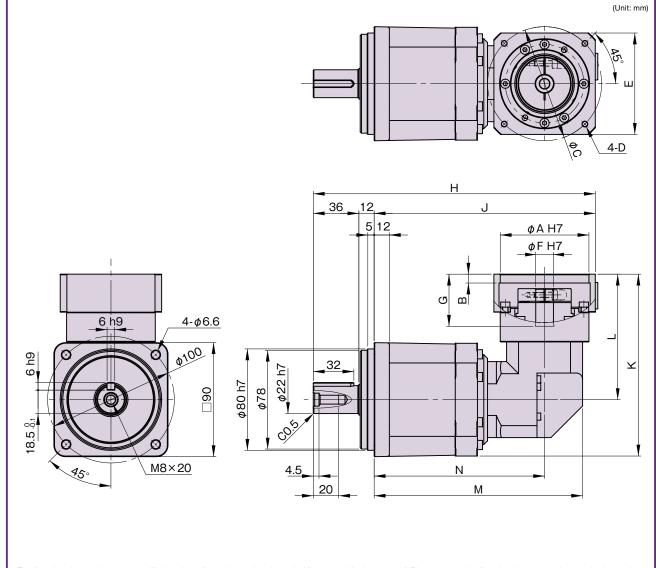


Dimensions

Table 09-1 (Unit: mm)

	A (H7)	В	С	D	E	Motor Sha		G	н	J	K	L	M	N	Mass (kg) *²
						Min	Max								(149)
Single Stage	Pilot Diameter ^{·1}		Bolt Circle Diameter ¹¹	Bolt Hole Thread and Depth ⁻¹	Input Flange Width (square)*1	14	24	Input Coupling Bore Depth ⁻¹	Length Dimension Output Axis*1	Length Output Axis ⁻¹	Length Input Axis ⁻¹	Length Output Axis ⁻¹	158.9	115.1	5.8

^{*1:} Dimensions for Quick Connect Adaptation Designs are tailored to the customer specified motor; detailed part #, drawings, and models furnished upon request *2: The mass varies slightly depending on the reduction ratio and on the inside diameter of the input shaft coupling



* The dimension tolerances that are not specified vary depending on the manufacturing method (casting, machined components). Please contact us for dimension tolerances not shown on the drawing above.

* Output shaft configuration shown is J6 (with a key and center tapped hole). The configuration J8 does not have a key.

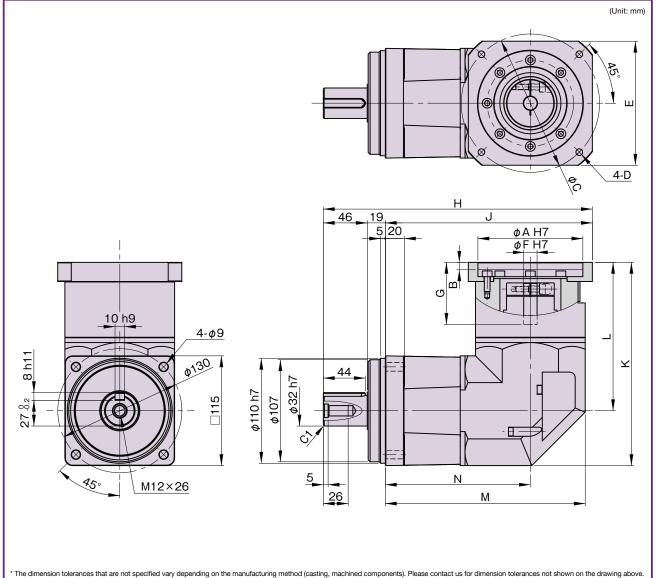
Dimensions

Table 010-1 (Unit: mm)

		A H7)	В	С	D	E	Motor Sha	ft Diameter H7)	G	н	J	К	L	М	N	Mass (kg) *2
Į							Min	Max								(kg) -
	Double Stage	Pilot Diameter ⁻¹		Bolt Circle Diameter*1	Bolt Hole Thread and Depth ⁻¹	Input Flange Width (square) ⁻¹	11	24	Input Coupling Bore Depth ⁻¹	Length Dimension Output Axis ¹¹	Length Output Axis ⁻¹	Length Input Axis ⁻¹	Length Output Axis ⁻¹	164.5	164.5	4.3

^{*1:} Dimensions for Quick Connect Adaptation Designs are tailored to the customer specified motor; detailed part #, drawings, and models furnished upon request *2: The mass varies slightly depending on the reduction ratio and on the inside diameter of the input shaft coupling

Figure 011-1



^{*} The dimension tolerances that are not specified vary depending on the manufacturing method (casting, machined components). Please contact us for dimension tolerances not shown on the drawing above.

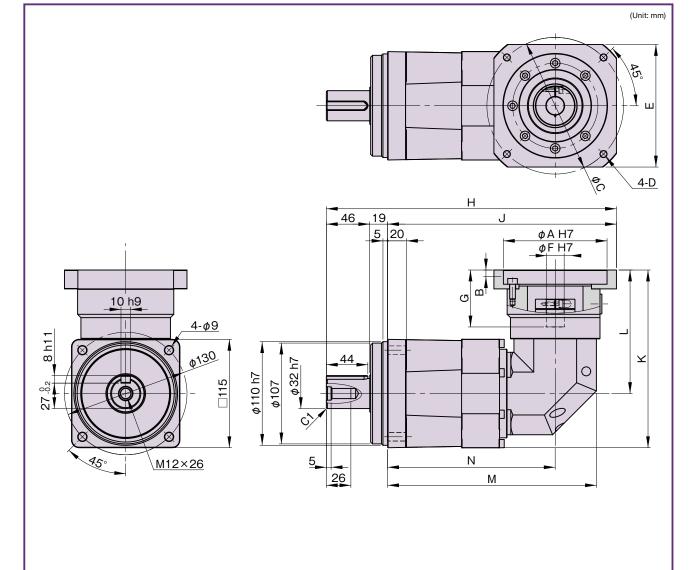
* Output shaft configuration shown is J6 (with a key and center tapped hole). The configuration J8 does not have a key.

Table 011-1 (Unit: mm)

	A (H7)	В	С	D	E	Motor Sha		G	н	J	K	L	М	N	Mass (kg) *²
						Min	Max								(-9/
ngle age	Pilot Diameter ^{*1}		Bolt Circle Diameter*1	Bolt Hole Thread and Depth ⁻¹	Input Flange Width (square) ⁻¹	14	35	Input Coupling Bore Depth ⁻¹	Length Dimension Output Axis ⁻¹	Length Output Axis ⁻¹	Length Input Axis ^{*1}	Length Output Axis [™]	209.5	152	15

^{*1:} Dimensions for Quick Connect Adaptation Designs are tailored to the customer specified motor; detailed part #, drawings, and models furnished upon request *2: The mass varies slightly depending on the reduction ratio and on the inside diameter of the input shaft coupling

Figure 012-1



^{*} The dimension tolerances that are not specified vary depending on the manufacturing method (casting, machined components). Please contact us for dimension tolerances not shown on the drawing above.

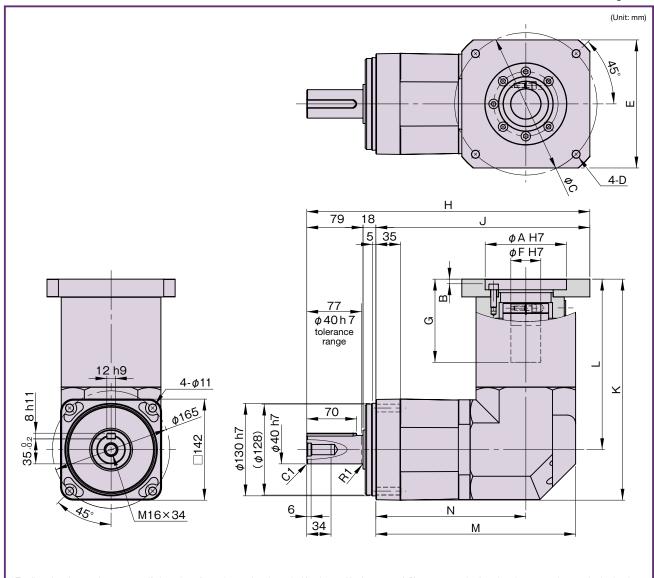
* Output shaft configuration shown is J6 (with a key and center tapped hole). The configuration J8 does not have a key.

Table 012-1 (Unit: mm)

	A (H7)	В	С	D	E	Motor Sha		G	н	J	K	L	М	N	Mass (kg) *²
						Min	Max								(9)
Double Stage	Pilot Diameter ^{*1}	l	Bolt Circle Diameter*1	Bolt Hole Thread and Depth ¹¹	Input Flange Width (square) ⁻¹	14	24	Input Coupling Bore Depth ⁻¹	Length Dimension Output Axis ⁻¹	Length Output Axis ⁻¹	Length Input Axis ⁻¹	Length Output Axis ⁻¹	221.6	177.8	11

^{*1:} Dimensions for Quick Connect Adaptation Designs are tailored to the customer specified motor; detailed part #, drawings, and models furnished upon request *2: The mass varies slightly depending on the reduction ratio and on the inside diameter of the input shaft coupling

Figure 013-1



^{*} The dimension tolerances that are not specified vary depending on the manufacturing method (casting, machined components). Please contact us for dimension tolerances not shown on the drawing above.

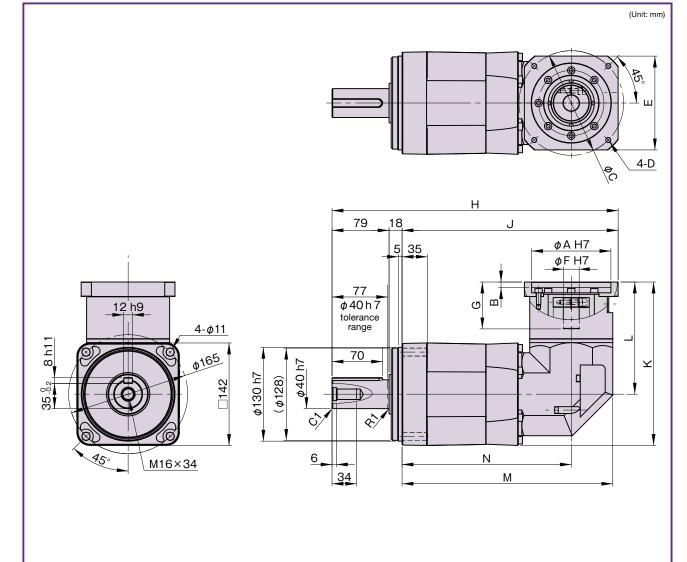
* Output shaft configuration shown is J6 (with a key and center tapped hole). The configuration J8 does not have a key.

Table 013-1 (Unit: mm)

	A (H7)	В	С	D	E		ft Diameter H7)	G	н	J	K	L	М	N	Mass (kg) *²
						Min	Max								(119)
Sing Stag		1	Bolt Circle Diameter*1	Bolt Hole Thread and Depth ⁻¹	Input Flange Width (square) ⁻¹	16	42	Input Coupling Bore Depth ⁻¹	Length Dimension Output Axis ¹¹	Length Output Axis ⁻¹	Length Input Axis ⁻¹	Length Output Axis ⁻¹	280.7	210.7	28

^{*1:} Dimensions for Quick Connect Adaptation Designs are tailored to the customer specified motor; detailed part #, drawings, and models furnished upon request *2: The mass varies slightly depending on the reduction ratio and on the inside diameter of the input shaft coupling

Figure 014-1



^{*} The dimension tolerances that are not specified vary depending on the manufacturing method (casting, machined components). Please contact us for dimension tolerances not shown on the drawing above.

* Output shaft configuration shown is J6 (with a key and center tapped hole). The configuration J8 does not have a key.

Table 014-1

	A (H7)	В	С	D	E	Motor Sha	ft Diameter H7)	G	н	J	К	L	М	N	Mass (kg) *2
						Min	Max								. 5,
Double Stage	Pilot Diameter*1		Bolt Circle Diameter ⁻¹	Bolt Hole Thread and Depth ¹¹	Input Flange Width (square)*1	14	35	Input Coupling Bore Depth ⁻¹	Length Dimension Output Axis ⁻¹	Length Output Axis ⁻¹	Length Input Axis ⁻¹	Length Output Axis ⁻¹	337	279.5	24

^{*1:} Dimensions for Quick Connect Adaptation Designs are tailored to the customer specified motor; detailed part #, drawings, and models furnished upon request *2: The mass varies slightly depending on the reduction ratio and on the inside diameter of the input shaft coupling



Efficiency

In general, the efficiency of a speed reducer depends on the reduction ratio, input rotational speed, load torque, temperature and lubrication condition.

The efficiency under the following measurement conditions is plotted in the graphs on the next page.

The values in the graph are average values.

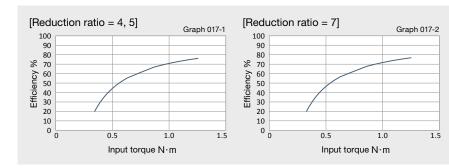
Measurement Condition

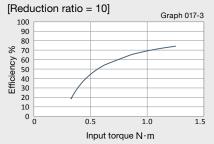
Table 016-1

Input speed	HPN: 3000rpm
Ambient temperature	25°C
Lubricant	Use standard lubricant. (See page 024 for details.)

Size 11A Gearhead

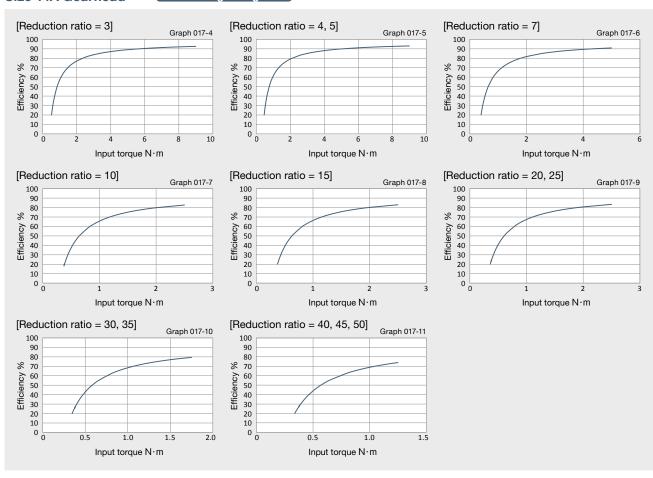
HPN Right Angle





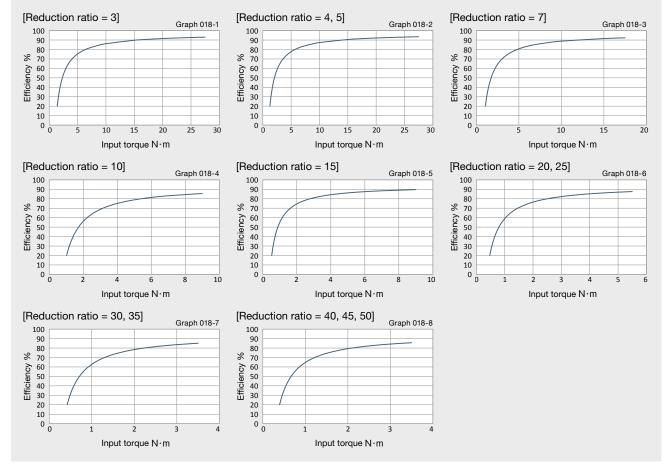
Size 14A Gearhead

HPN Right Angle



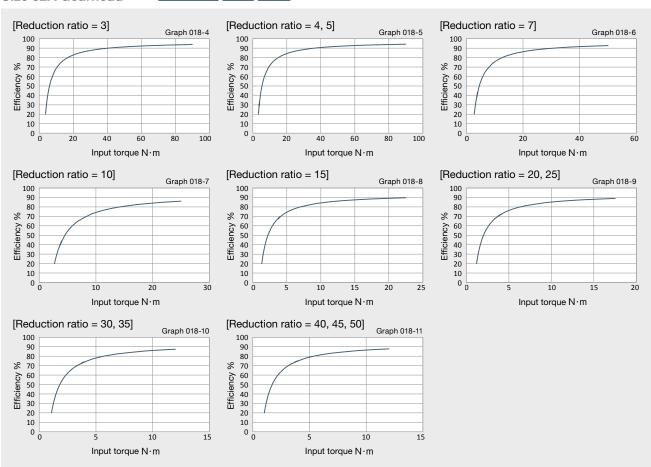
Size 20A Gearhead

HPN Right Angle



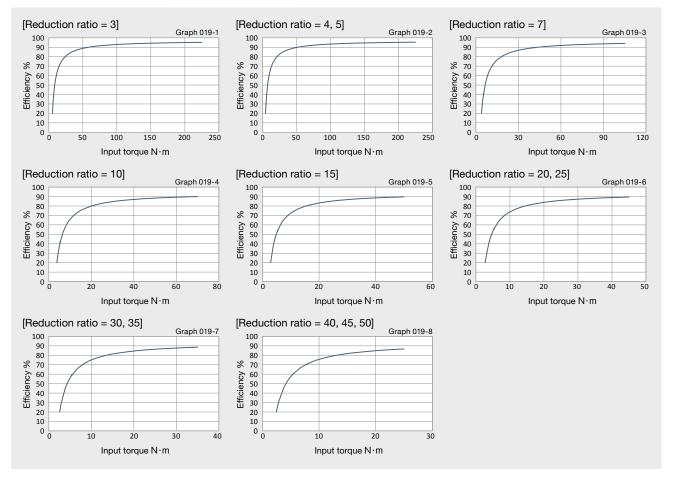
Size 32A Gearhead

HPN Right Angle

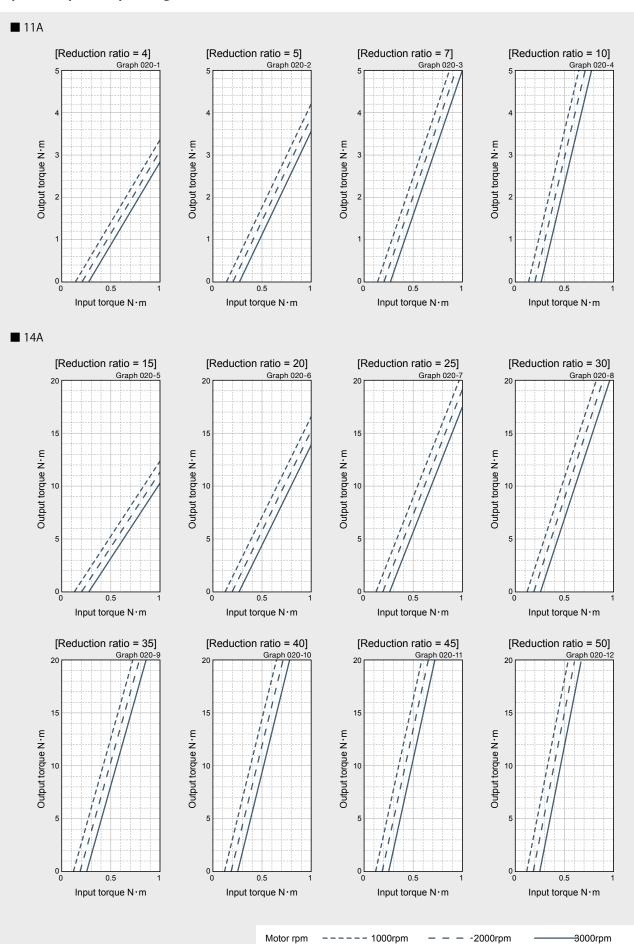


Size 40A Gearhead

HPN Right Angle



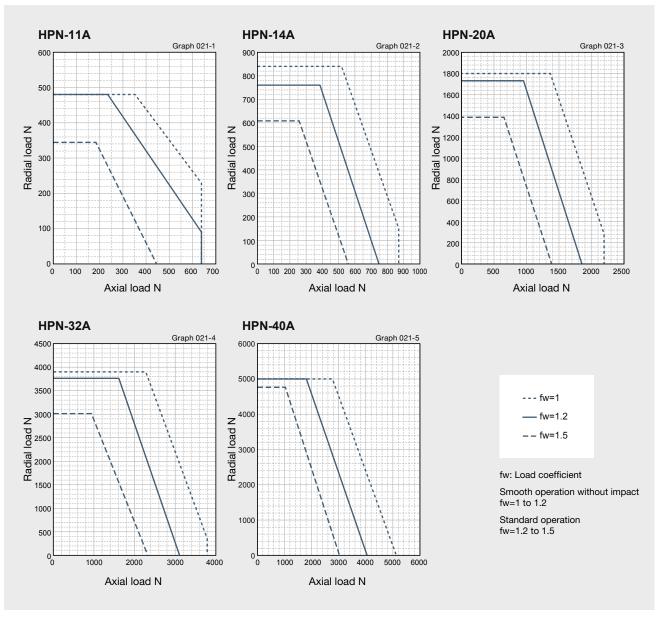
Input / Output Torque Diagram



Output Shaft Bearing Load Limits

HPN Series Output shaft load limits are plotted below.

HPN series uses radial ball bearings to support the output shaft. Please use the curve on the graph for the appropriate load coefficient (fw) that represents the expected operating condition.



Output shaft speed - 100 rpm, bearing life is based on 20,000 hours. The load-point is based on shaft center of radial load and axial load.

Assembly

Assemble and mount your gearhead in accordance with these instructions to achieve the best performance. Be sure to use the recommended bolts and use a torque wrench to achieve the proper tightening torques as recommended in tables below.

Motor Assembly Procedure

To properly mount the motor to the gearhead, follow the procedure outlined below.

• Turn the input shaft coupling and align the bolt head with the rubber cap hole.

Optional Assembly Step for Improved Sealing

- Apply a sealant to the surface of the motor flange that will contact the gearhead mounting flange. (Recommended sealant: LOCKTITE 515)
- With the speed reducer in an upright position as illustrated in the figure below, slowly insert the motor shaft into the coupling of speed reducer. Slide the motor shaft without letting it drop down. If the speed reducer cannot be positioned upright, slowly insert the motor shaft into the coupling of speed reducer, then tighten the motor bolts evenly until the motor flange and gearhead flange are in full contact. Exercise care to avoid tilting the motor when inserting it into the gearhead.
- Fasten the motor and speed reducer flange with bolts.

Belev tightening tergue

Bolt* tightening torque													
	Bolt size		M2.5	M 3	M4	M5	M6	M8	M10	M12			
	Tightening torque	N⋅m	0.59	1.4	3.2	6.3	10.7	26.1	51.5	89.9			
		kgf⋅m	0.06	0.14	0.32	0.64	1.09	2.66	5.25	9.17			

Recommended bolt: JIS B 1176 Hexagon socket head bolt, Strength: JIS B 1051 12.9 or higher Caution: Be sure to tighten the bolts to the tightening torques specified in the table.

Tighten the input shaft coupling bolt to the recommended torque specified in the table below. The bolt(s) or screw(s) is (are) already inserted into the input shaft coupling when delivered. Check the bolt size on the confirmation drawing provided.

 Bolt* tightening torque
 Table 022

 Bolt size
 M3
 M4
 M5
 M6
 M8
 M10
 M12

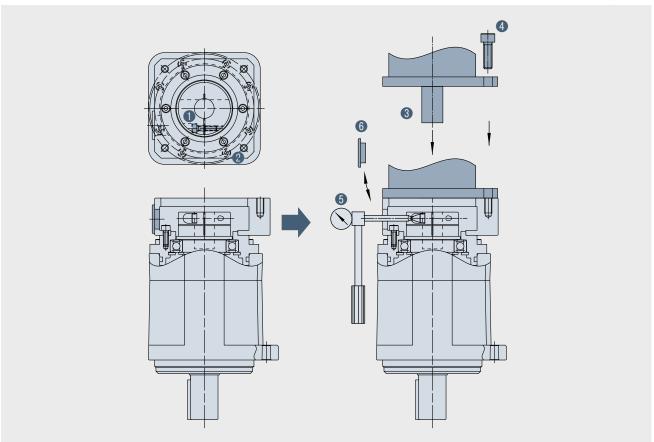
 Tightening torque
 N·m
 2.0
 4.5
 9.0
 15.3
 37.2
 73.5
 128

 kgf·m
 0.20
 0.46
 0.92
 1.56
 3.8
 7.5
 13.1

Caution: Always tighten the bolts to the tightening torque specified in the table above. If the bolts is not tightened to the torque value recommended slippage of the motor shaft in the shaft coupling may result. The bolt size will vary depending on the size of the gear and the shaft diameter of the mounted motor. Check the bolt size on the confirmation drawing provided.

· Insert the rubber cap provided. This completes the assembly.

Figure 022-1



Speed Reducer Assembly

No thread for eyebolt is provided because the mounting orientation varies depending on the customer's need. When mounting the reducer, hoist it using a sling paying extreme attention to safety.

When assembling gearheads into your equipment, check the flatness of your mounting surface and look for any burrs on tapped holes. Then fasten the flange (Part A in the diagram below) using appropriate bolts.

Bolt* tightening torque

Table 023-1

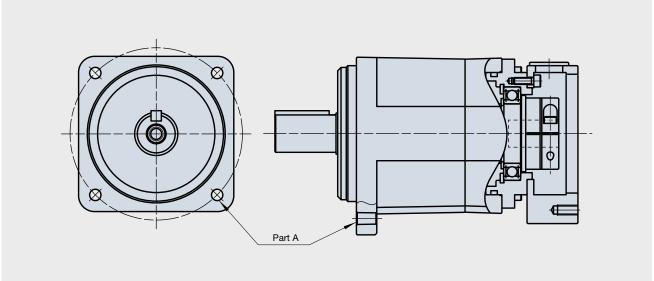
C:		HPN							
Size		11	14	20	32	40			
Number of bolts		4	4	4	4	4			
Bolt size		M3	M5	M6	M8	M10			
Mounting PCD	mm	50	70	100	130	165			
T. 1.1	N·m	1.4	6.3	10.7	26.1	51.5			
Tightening torque	kgf⋅m	0.14	0.64	1.09	2.66	5.26			
	N·m	27.9	110	223	528	1063			
Transfer torque	kgf∙m	2.85	11.3	22.8	53.9	108.5			

 $^{^{\}star}$ Recommended bolts: JIS B 1176 "Hexagon socket head bolts. "Strength classification 12.9 or higher in JIS B 1051.

Mounting the Load to the Output Shaft

When mounting a load onto the output shaft, take the specification of the output bearing into consideration.

Figure 023-1



Gearheads with an Output Shaft

Do not subject the output shaft to any impact when mounting a pulley, pinion and other parts.

An impact to the output bearing will deteriorate the speed reducer precision and may cause reduced life or failure.

Lubrication

Prevention of Grease and Oil Leakage

- Only use the recommended greases.
- Provisions for proper sealing to prevent grease leakage are incorporated into the gearheads. However, please note that some leakage may occur depending on the application or operating condition. Discuss other sealing options with our applications engineers.
- When mounting the gearhead horizontally, position the gearhead so that the rubber cap in the adapter flange is facing upwards.

Sealing

• A double lip Teflon oil seal is used for the output shaft, gaskets or o-rings on all mating surfaces.

Lubricant

The standard lubrication for the HPN series is grease. All gearheads are lubricated at the factory prior to shipment and additional application of grease during assembly is not required. The gearheads are lubricated for the life of the gear and do not require re-lubrication.

High efficiency is achieved thorough the unique planetary gear design and grease selection.

Name of Lubricant

PYRONOC UNIVERSAL 0

Manufacturer: Nippon Oil Co.

Base oil: Rened mineral oil Consistency: 375 at 25°C

Soap radical: Urea Dropping point: 250°C or higher
Standard: NLGI No. 0 Product appearance: Light yellow

Ambient Operating Temperature Range: 0°C to +40°C

The lubricant may deteriorate if the ambient operating temperature is too high or too low. Please contact our sales office or distributor for operation outside of the ambient operating temperature range.

The temperature rise of the gear depends upon the operating cycle, ambient temperature and heat conduction and radiation as affected by the customers installation of the gear. A housing surface temperature of 70°C is the maximum allowable limit.

Warranty

Please contact us or visit our website at www.harmonicdrive.net for warranty details for your specific product.

Warranty Terms

All the products are warranted against defects in workmanship and materials for the warranted period. This limited warranty does not apply to any product that has been subject to:

- User's misapplication, improper installation, inadequate maintenance, or misuse.
- Disassembling, modification or repair by others than Harmonic Drive.

Our liability shall be limited exclusively to repairing or replacing the product only found by Harmonic Drive to be defective.

Harmonic Drive shall not be liable for consequential damages of other equipment caused by the defective products, and shall not be liable for the incidental and consequential expenses and the labor costs for detaching from and installing to the driven equipment.

Disposal

When disposing of the product, disassemble it and sort the component parts by material type and dispose of the parts as industrial waste in accordance with the applicable laws and regulations. The component part materials can be classified into three categories.

- Rubber parts: Oil seals, O-rings, rubber caps
- Aluminum parts: Housings, motor flanges
- Steel parts: Other parts

All efforts have been made to ensure that the information in this catalog is complete and accurate. However, Harmonic Drive LLC is not liable for any errors, omissions or inaccuracies in the reported data. Harmonic Drive LLC reserves the right to change the product specifications, for any reason, without prior notice. For complete details please refer to our current Terms and Conditions posted on our website.

Safety



Means that improper use or handling could result in a risk of death or serious injury.

↑ Caution Means that improper use or handling could result in personal injury or damage to property.

Limited Applications This product cannot be used for the following applications:

- * Space flight hardware * Aircraft equipment
- * Nuclear power equipment
 - * Equipment and apparatus used in domestic homes
- * Vacuum environments * Automotive equipment
- * Personal recreation equipment
- * Equipment that directly works on human bodies
- * Equipment for transport of humans
- * Equipment for use in a special environment

Please consult Harmonic Drive Systems beforehand when intending to use one of its product for the aforementioned applications. Install a safety device that avoids an accident even if output of this product becomes uncontrollable due to breakdown when using it in equipment that affects human lives and that may trigger serious damage.

Design Precaution: Be certain to read the catalog when designing the equipment.

/!\

Use only in a specified environment.

- In case of using Harmonic Planetary® please ensure the following environmental conditions are complied with:
- Ambient temperature 0 to 40°C Do not expose to corrosive or explosive gas No splashing of water or oil
 No dust such as metal powder

/!\ Cautio

Install the equipment in a specified manner.

- Carry out assembly precision in the specified order according to the catalog.
- Observe our recommended tightening methods (such as bolts used)
- Operating the equipment without precise assembly can cause troubles such as generation of vibration, reduction of life, deterioration of precision and breakdown.



Install the equipment in a specified precision.

- Design and assemble parts to keep the recommended installation precision on the catalog.
- Failure to keep the precision can cause troubles such as generation of vibration, reduction of life, deterioration of precision and breakdown.



Use the specified lubricant.

- Using other lubricant than our recommended products can reduce the life. Replace the lubricant in a specified condition.
- Grease is sealed in a unit product for Harmonic Planetary®. Do not mix other kinds of grease.

Operational Precaution: Be certain to read the catalog before operating the equipment.



Do not put a finger into the gearing to turn it.

• If the gearing is turned by inserting a finger into it to turn it, the finger may be caught in the gear, resulting in an unexpected injury. Do not attempt this under any circumstances.



Apply torque within the allowable range.

- Do not apply torque exceeding the limit for momentary torque. Applying excess torque can cause troubles such as loose tightening bolts, generation of backlash and breakdown.
- Striking an arm directly attached to the output shaft can damage the arm and make the output shaft uncontrollable.



This is a heavy item. Please handle with care.

● This item is very heavy and may cause back injury or injuries due to dropping or knocking over the product and getting fingers caught in between. Please take precautions such as wearing safety shoes and use a supporting tool when handling.



Do not break down unit products.

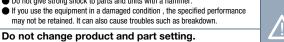
 Do not break down and reassemble unit products. Original performance may not be reproduced.



Be careful in handling products and parts.

- Do not give strong shock to parts and units with a hammer.
- If you use the equipment in a damaged condition, the specified performance may not be retained. It can also cause troubles such as breakdown.

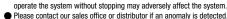
 Harmonic Planetary® products are manufactured by incorporating their parts in a set. If settings are changed, specified performance cannot be maintained.



/!` Cautior

Stop operating the system when an anomaly is detected

 Shut down the system promptly if an abnormal sound or vibration is detected, rotation is stopped, abnormally high temperature is generated, an abnormal current value is observed or other anomalies are detected. Continuing to





Be careful of oil leaks.

 Although a highly reliable oil seal is used as an output shaft, it does not guarantee leak-tight sealing. Depending on the use, please apply grease or oil for protection.



- For the product that has been stored for a long time, it is recommended to confirm performance and rust-proofing. To store the product for a long time, check no rust is generated about every six month and carry out the rust-proofing again. For the re-rust-proofing method etc., please contact Harmonic Drive Systems
- Although black oxide finish is applied to some of our products, it dose not quarantee the antirust effect.

Handling Lubricant



Precautions on handling lubricant

- Lubricant got in the eye can cause an inflammation. Wear protective glasses to prevent it from getting in your eye when you handle it.
- Lubricant coming in contact with the skin can cause an inflammation. Wear protective gloves to prevent it from contacting your skin when you handle it.
- Do not eat it (to avoid diarrhea and vomiting).
- When you open the container, you might have your hand cut by it. Wear protective gloves
- Keep lubricant off children.



Treatment of waste oil and containers

- Treatment methods are obliged by law. Treat wastes appropriately according to the law. If you are unsure how to treat them, you should consult with the dealer before treating them
- Do not apply pressure on an empty container. The remainder may ignite with an explosion.
- Do not weld, heat, drill or cut the container. The remainder may ignite with an explosion.





- If lubricant gets in your eye, you should wash your eye with clean water for 15 minutes and submit to medical treatment
- If lubricant comes in contact with your skin, you should thoroughly wash it with water and soap.
- If you swallowed it, you should immediately submit to medical treatment without throwing it up by constraint.



Storage

 Tightly plug the container after use to prevent intrusion of dusts and water. Avoid direct sunlight to store lubricant in a dark place.

Disposal



Please dispose as industrial waste.

Please dispose of the products as industrial waste when their useful life is over.

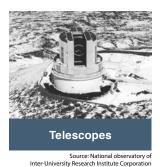
Major Applications of Our Products

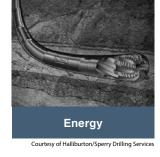


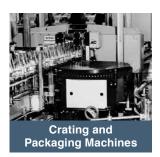
































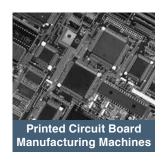
















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